

From last week (wrap up) today 2/20

Ex. Use INVERSES to solve the system

$$\begin{cases} 7x + 11y = 4 \\ 2x + 3y = 5 \end{cases} \iff Ax = b$$

row operations are gross.

$$[A|b] = \left[\begin{array}{cc|c} 7 & 11 & 4 \\ 2 & 3 & 5 \end{array} \right] \sim \dots \sim \left[\begin{array}{cc|c} 1 & 0 & c_1 \\ 0 & 1 & c_2 \end{array} \right]$$

better way? use inverses.

If we want to know what x is,

$$Ax = b \implies A^{-1} \cdot Ax = A^{-1} \cdot b$$

$$\implies (I) \cdot x = A^{-1} b$$

$$\implies x = A^{-1} b$$

Step 1: Find A^{-1}

Step 2: compute $x = A^{-1} b$.

$$A = \begin{bmatrix} 7 & 11 \\ 2 & 3 \end{bmatrix} \text{ so } A^{-1} = \frac{1}{7 \cdot 3 - 2 \cdot 11} \begin{bmatrix} 3 & -11 \\ -2 & 7 \end{bmatrix}$$

$$= \frac{1}{21 - 22} \begin{bmatrix} 3 & -11 \\ -2 & 7 \end{bmatrix}$$

$$A^{-1} = \begin{bmatrix} -3 & 11 \\ 2 & -7 \end{bmatrix}$$

$$\begin{aligned} x &= A^{-1} b \\ &= \begin{bmatrix} -3 & 11 \\ 2 & -7 \end{bmatrix} \begin{bmatrix} 4 \\ 5 \end{bmatrix} = \begin{bmatrix} -3 \cdot 4 + 5 \cdot 11 \\ 2 \cdot 4 - 7 \cdot 5 \end{bmatrix} \\ &= \begin{bmatrix} 43 \\ -27 \end{bmatrix} \end{aligned}$$

Ex. Suppose T is the linear transformation

$$T\begin{pmatrix} x \\ y \end{pmatrix} = \begin{bmatrix} 6x - 5y \\ -6x + 7y \end{bmatrix}.$$

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$A = [T(e_1) \ T(e_2)]$$

is size 2×2 .

Q₁: Is T one-to-one?

Q₂: Is T onto?

Q₃: Is T invertible? What is T^{-1} ?

T is one-to-one if $T(x) = T(y) \Rightarrow x = y$
only one way to get $T(x) = b$
for any particular b .

T is one-to-one

$\Leftrightarrow A_T$ has a pivot in every col.

\Leftrightarrow cols of A_T are lin ind

$\Leftrightarrow T(x) = b$ has at most one soln for any choice of b .

$$A = [T(e_1) \ T(e_2)] = \begin{bmatrix} 6 & -5 \\ -6 & 7 \end{bmatrix}.$$

$A \sim \begin{bmatrix} 6 & -5 \\ 0 & 2 \end{bmatrix}$ 2 pivots \Rightarrow cols lin ind
 $\Rightarrow T$ is one-to-one

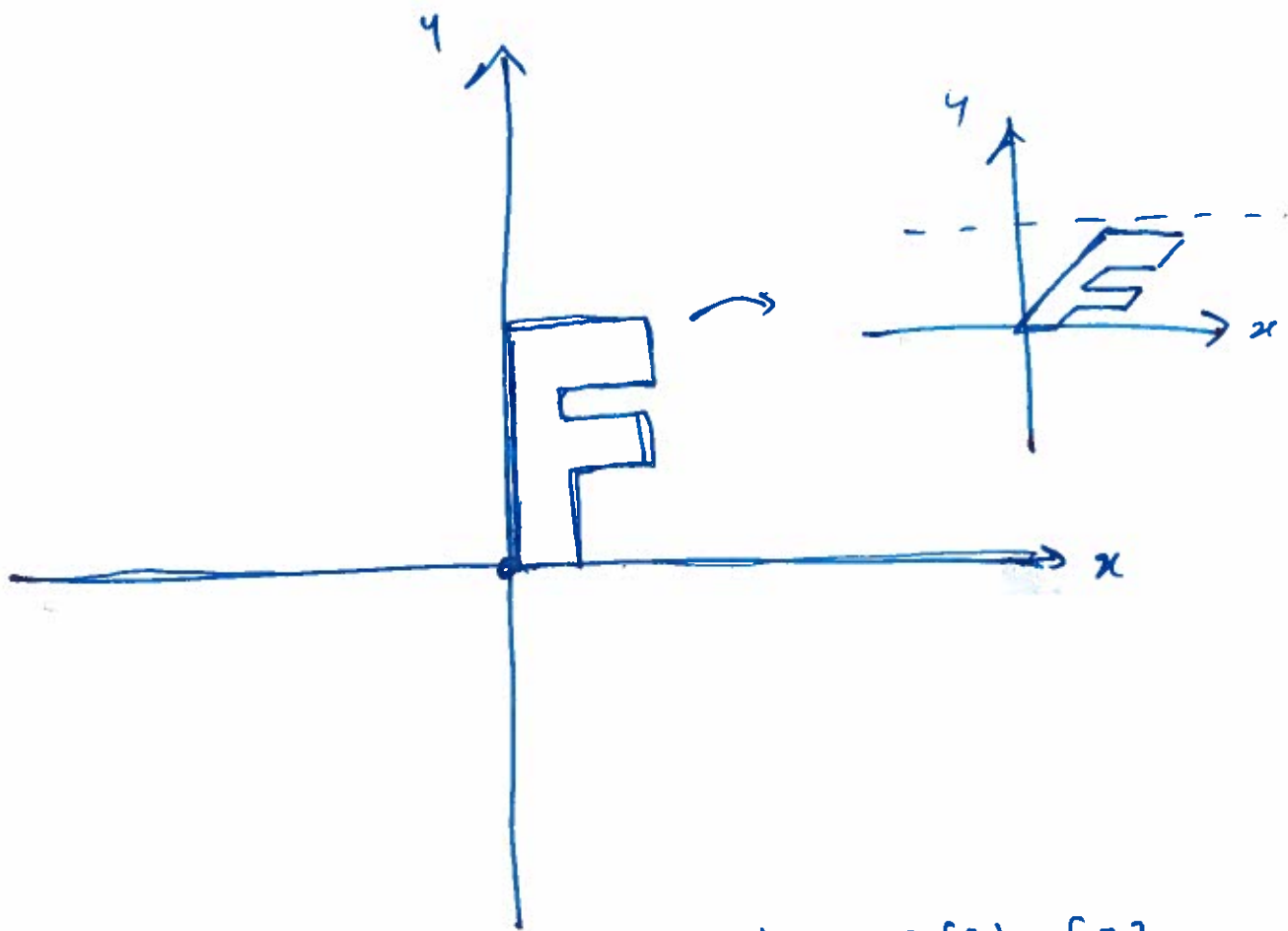
examples

one-to-one	not one-to-one
reflection $\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$	projection $\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$
rotation $\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$	zeroing out $\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$
shear $\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$	

What is a shear?

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

$T_A: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is called a shear.



$$T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$T\left(\begin{bmatrix} a \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} a \\ 0 \end{bmatrix} = \begin{bmatrix} a \\ a \end{bmatrix}$$

$$T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$T\left(\begin{bmatrix} 0 \\ 2 \end{bmatrix}\right) = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \end{bmatrix}$$

$$T\left(\begin{pmatrix} x \\ y \end{pmatrix}\right) = \begin{bmatrix} 6x - 5y \\ -6x + 7y \end{bmatrix} \leftrightarrow A = \begin{bmatrix} 6 & -5 \\ -6 & 7 \end{bmatrix}$$

2 pivots \Rightarrow T is 1-1.

Q₂: Is T onto?
 Is it possible to solve
 $T(x) = b$
 for any choice of b

\leftrightarrow Is
 $Ax = b$
 always consistent
 for any choice of b?

Solve?

$$\begin{bmatrix} 6 & -5 \\ -6 & 7 \end{bmatrix} x = b$$

alt. check if
 A has pivots in
 every row.

\uparrow

$$\text{If } A \text{ has } A^{-1} = \frac{1}{42-30} \begin{bmatrix} 7 & 5 \\ 6 & 6 \end{bmatrix} = \frac{1}{12} \begin{bmatrix} 7 & 5 \\ 6 & 6 \end{bmatrix}$$

So $x = \frac{1}{12} \begin{bmatrix} 7 & 5 \\ 6 & 6 \end{bmatrix} \cdot b$ it is always possible
 to solve $Ax = b$

b/c A was invertible.

So Q₃: Is T invertible?

If so what is the standard matrix for T^{-1} ?

Ans. T^{-1} standard matrix is A^{-1}

Sanity check.

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$$T\left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}\right) = \begin{bmatrix} 6(1) - 5(2) \\ -6(1) + 7(2) \end{bmatrix} = \begin{bmatrix} -4 \\ 8 \end{bmatrix}.$$

$$T^{-1}\left(\begin{bmatrix} -4 \\ 8 \end{bmatrix}\right) = \frac{1}{12} \begin{bmatrix} 7 & 5 \\ 6 & 6 \end{bmatrix} \begin{bmatrix} -4 \\ 8 \end{bmatrix} = \frac{1}{12} \begin{bmatrix} -28 + 40 \\ -24 + 48 \end{bmatrix} = \frac{1}{12} \begin{bmatrix} 12 \\ 24 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

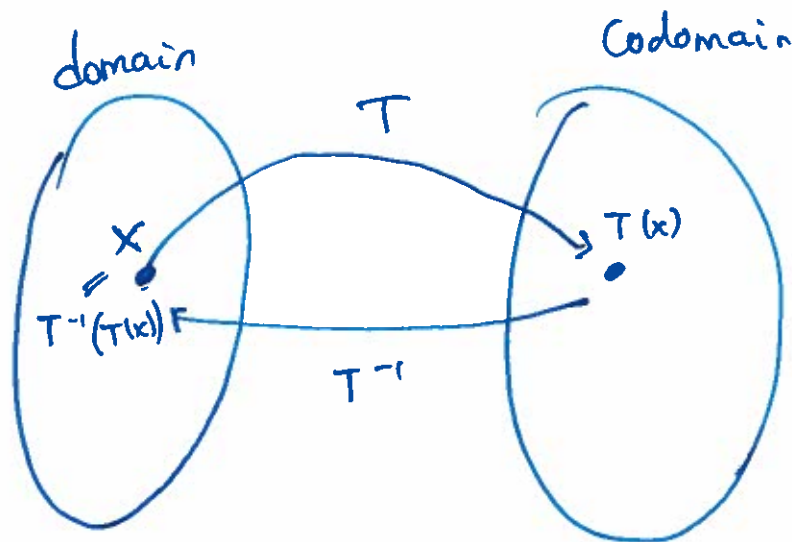
$$\text{So } T^{-1} \circ T\left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 2 \end{bmatrix}.$$

In general

$$T^{-1} \circ T(x) = x$$

$$T \circ T^{-1}(x) = x$$

What is "o"
circle thing.
means "composition"



Next up. LU-Factorization.

6

Find the LU-factorization for A

$$A = \begin{bmatrix} 12 & 9 \\ 24 & 14 \end{bmatrix}$$

Step 1: Row reduce A to ref
(so that the result is upper-A)

$$A = \begin{bmatrix} 12 & 9 \\ 24 & 14 \end{bmatrix} \sim -2R_1 + R_2 \left| \begin{bmatrix} 12 & 9 \\ 0 & -4 \end{bmatrix} \right.$$

↑ U

$$E = \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix}$$

← what you get if you do $-2R_1 + R_2$ to I.

NOTICE

$$E \cdot A = \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} 12 & 9 \\ 24 & 14 \end{bmatrix} = \begin{bmatrix} 12 & 9 \\ 0 & -4 \end{bmatrix}$$

$$E \cdot A = U \Rightarrow E^{-1} \cdot A = E^{-1} \cdot U$$

$$\Rightarrow A = E^{-1} \cdot U$$

↑

$$E^{-1} = \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix} \text{ so } \boxed{L = \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix} U = \begin{bmatrix} 12 & 9 \\ 0 & -4 \end{bmatrix}}$$

ANS (type)

$$A = L \cdot U$$

↑ lower triangular
↑ upper triangular.

$$\begin{matrix} \text{lower} & \text{upper} \\ \begin{bmatrix} 1 & 0 \\ 2 & 3 \end{bmatrix} & \begin{bmatrix} * & * \\ 0 & * \end{bmatrix} \end{matrix}$$

$$\begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix}$$

$$\begin{bmatrix} * & * & * \\ 0 & * & * \\ 0 & 0 & * \end{bmatrix}$$

upper-Δ

$$\begin{matrix} \text{lower-}\Delta \\ \begin{bmatrix} * & 0 & 0 \\ * & * & 0 \\ * & * & * \end{bmatrix} \end{matrix}$$

Ex. Find the LU-factorization of

$$A = \begin{bmatrix} 5 & 2 \\ 15 & 1 \end{bmatrix} \quad \left(\text{and check your answer!} \right)$$

Step 1: Find U by ~~not~~ getting rid of A.

$$A = \begin{bmatrix} 5 & 2 \\ 15 & 1 \end{bmatrix} \sim \begin{bmatrix} 5 & 2 \\ 0 & -5 \end{bmatrix} \quad \left(-3R_1 + R_2 \right)$$

← this is U

Step 2 Find L.

Mult. by -1

always

$$L = \begin{bmatrix} 1 & 0 \\ * & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix}$$

find this guy

Check $A = L \cdot U$?

$$\begin{bmatrix} 5 & 2 \\ 15 & 1 \end{bmatrix} \stackrel{?}{=} \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} 5 & 2 \\ 0 & -5 \end{bmatrix} \stackrel{\checkmark}{=} \begin{bmatrix} 5 & 2 \\ 15 & 1 \end{bmatrix}$$

Why LU at all?

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Say you want to solve a "nasty"

$$Ax = b$$

assume easy (or given) to find L, U .

Then

$$Ax = b$$

$$\Leftrightarrow L \cdot Ux = b$$

$$\Leftrightarrow L(Ux) = b$$

Step 1 Solve $L(y) = b$

this is easy b/c L is lower-triangular.

Step 2 Solve $Ux = y$

this is also easy, b/c U is upper-triangular!

(we've replaced 1 hard problem w/ 2 easy problems)



1) A is invertible if there is a matrix " A^{-1} " such that

$$A \cdot A^{-1} = I$$

2) T is invertible if there is a transformation " T^{-1} " such that

$$T \circ T^{-1}(x) = x$$

3) $A \sim \dots \sim I$ means there are elementary matrices E_1, E_2, \dots, E_k

s.t. .

the second row operation
the first row operation

$$\underbrace{(E_k \dots E_2 E_1)}_{A^{-1}} A = I$$

Using
LU-decomp to solve $Ax=b$.

2

Find LU & use it to solve $Ax=b$

Ex.

$$A = \begin{bmatrix} 3 & -7 & -2 \\ -3 & 5 & 1 \\ 6 & -4 & 0 \end{bmatrix} \quad b = \begin{bmatrix} -7 \\ 5 \\ 2 \end{bmatrix}.$$

Soln. I want x such that $Ax=b$.

(one way $[A|b] \sim \dots \sim \left[\begin{array}{ccc|c} 1 & 0 & 0 & c_1 \\ 0 & 1 & 0 & c_2 \\ 0 & 0 & 1 & c_3 \end{array} \right]$)

$$\begin{array}{l} \sim \begin{bmatrix} 3 & -7 & -2 \\ 0 & -2 & -1 \\ 0 & 10 & 4 \end{bmatrix} \sim \begin{bmatrix} 3 & -7 & -2 \\ 0 & -2 & -1 \\ 0 & 0 & -1 \end{bmatrix} = U \end{array}$$

(Annotations: $R_1 + R_2$, $-2R_1 + R_2$, $5R_2 + R_3$)

$$L = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 2 & -5 & 1 \end{bmatrix}$$

(Annotations: $1R_1 + R_2$, $-2R_1 + R_2$, $5R_2 + R_3$)

and.

$$L = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 2 & -5 & 1 \end{bmatrix}.$$

Check $A=LU?$

$$\begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 2 & -5 & 1 \end{bmatrix} \begin{bmatrix} 3 & -7 & -2 \\ 0 & -2 & -1 \\ 0 & 0 & -1 \end{bmatrix} = \begin{bmatrix} 3 & -7 & -2 \\ -3 & 5 & 1 \\ 6 & -4 & 0 \end{bmatrix} \quad \checkmark$$

Use $A=LU$ to solve $Ax=b$. /3

$$Ax=b$$

$$\Rightarrow LUx=b$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 2 & -5 & 1 \end{bmatrix} \underbrace{\begin{pmatrix} 3 & -7 & -2 \\ 0 & -2 & -1 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}}_{\text{"y"}} = \begin{pmatrix} -7 \\ 5 \\ 2 \end{pmatrix}$$

Solve

$$Ly=b$$

$$\left[\begin{array}{ccc|c} 1 & 0 & 0 & -7 \\ -1 & 1 & 0 & 5 \\ 2 & -5 & 1 & 2 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & 0 & -7 \\ 0 & 1 & 0 & -2 \\ 0 & -5 & 1 & +16 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & 0 & -7 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 1 & +16 \end{array} \right]$$

Next

~~Solve~~

$$y = \begin{pmatrix} -7 \\ -2 \\ +16 \end{pmatrix}$$

$$X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 65/3 \\ 4 \\ -6 \end{pmatrix}$$

Solve $Ux=y$

$$\left[\begin{array}{ccc|c} 3 & -7 & -2 & -7 \\ 0 & -2 & -1 & -2 \\ 0 & 0 & -1 & +16 \end{array} \right] \sim \left[\begin{array}{ccc|c} 3 & -7 & 0 & 37 \\ 0 & -2 & 0 & -2 \\ 0 & 0 & 1 & -16 \end{array} \right]$$

$$\sim \left[\begin{array}{ccc|c} 3 & 0 & 0 & 65 \\ 0 & +1 & 0 & 4 \\ 0 & 0 & 1 & -16 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & 0 & 65/3 \\ 0 & 1 & 0 & 4 \\ 0 & 0 & 1 & -16 \end{array} \right]$$

(more practice)

4

Find LU-decomp. (but don't do anything with it.)

$$A = \begin{bmatrix} -5 & 3 & 4 \\ 10 & -8 & -9 \\ 15 & 1 & 2 \end{bmatrix}$$

$$\begin{array}{l} \sim \\ 2R_1 + R_2 \\ 3R_1 + R_3 \end{array} \begin{bmatrix} -5 & 3 & 4 \\ 0 & -2 & -1 \\ 0 & 10 & 14 \end{bmatrix} \sim \begin{array}{l} \\ 5R_2 + R_3 \\ \end{array} \begin{bmatrix} -5 & 3 & 4 \\ 0 & -2 & -1 \\ 0 & 0 & 9 \end{bmatrix}$$

$$L = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ -3 & -5 & 1 \end{bmatrix} \quad U = \begin{bmatrix} -5 & 3 & 4 \\ 0 & -2 & -1 \\ 0 & 0 & 9 \end{bmatrix}$$

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$$A = \begin{bmatrix} 2 & 0 & 1 \\ -4 & 3 & -1 \\ 2 & 0 & 0 \end{bmatrix}$$

Something weird
will happen
with this one.

$$\sim \begin{matrix} 2R_1 + R_2 \\ -R_1 + R_2 \end{matrix} \begin{bmatrix} 2 & 0 & 1 \\ 0 & 3 & -1 \\ 0 & 0 & -1 \end{bmatrix}$$

← already
upper Δ !
after only
dealings w/
first col.

U

$$L = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \quad \checkmark$$

$$\begin{matrix} E_2 & E_1 & A \\ \left[\begin{array}{ccc} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{array} \right] & \left[\begin{array}{ccc} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{array} \right] & \left[\begin{array}{ccc} 2 & 0 & 1 \\ -4 & 3 & -1 \\ 2 & 0 & 0 \end{array} \right] \end{matrix} = \begin{matrix} U \\ \left[\begin{array}{ccc} 2 & 0 & 1 \\ 0 & 3 & -1 \\ 0 & 0 & -1 \end{array} \right] \end{matrix}$$

~~$E_2 E_1 = E_1 E_2$~~
 ~~$E_2 E_1 = E_1 E_2$~~

$$(E_2 E_1)^{-1} F, F, A = A = \underline{\underline{(E, F)^{-1} \cdot U}}$$

and.

$$(E_2 E_1)^{-1} = E_1^{-1} E_2^{-1}$$

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$$= \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} = \underline{\underline{L}}$$