

LINSEAR

ALGEBRA

Week 10

Definition (Orthogonal Vectors)

Two vectors \vec{u} and \vec{v} are **orthogonal** if $\vec{u} \cdot \vec{v} = 0$. This is equivalent to:

$$\|\vec{u} + \vec{v}\|^2 = \|\vec{u}\|^2 + \|\vec{v}\|^2$$

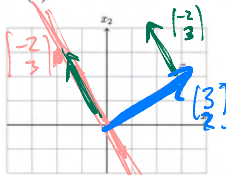
Note: The zero vector is orthogonal to every vector. But we usually only mean non-zero vectors.

If $\vec{u} \cdot \vec{w} = 0$

then $\|\vec{u} + \vec{w}\|^2 = (\vec{u} + \vec{w}) \cdot (\vec{u} + \vec{w})$
 $= \vec{u} \cdot \vec{u} + 2\vec{u} \cdot \vec{w} + \vec{w} \cdot \vec{w}$
 $= \|\vec{u}\|^2 + \|\vec{w}\|^2$



Sketch the subspace spanned by the set of all vectors \vec{u} that are orthogonal to $\vec{v} = \begin{pmatrix} 3 \\ 2 \end{pmatrix}$



Span $\left\{ \begin{bmatrix} -2 \\ 3 \end{bmatrix} \right\}$
 $= \text{Span} \left\{ \begin{bmatrix} -2 \\ 3 \end{bmatrix} \right\}$

Solve for a, b
 $\begin{bmatrix} 3 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} a \\ b \end{bmatrix} = 0$

$3a + 2b = 0$

$\begin{bmatrix} 3 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & 2/3 \end{bmatrix}$

$\vec{x} = s \begin{bmatrix} -2/3 \\ 1 \end{bmatrix}$

$\vec{v} \cdot \vec{x} = 0$

$\vec{v}^T \vec{x} = 0$

Nul(\vec{v}^T)

Summarize

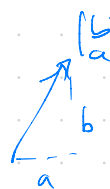
$\vec{u} \cdot \vec{w} = 0$ says the dot product is zero.

$\|\vec{u} + \vec{w}\|^2 = \|\vec{u}\|^2 + \|\vec{w}\|^2$ says the vectors \vec{u} & \vec{w} are perpendicular (90° angle w/ each other)

$m = \frac{b}{a}$

then

$m \perp = -\frac{a}{b}$



Orthogonal Complements

Definitions

Let W be a subspace of \mathbb{R}^n . A vector $\vec{x} \in \mathbb{R}^n$ is said to be **orthogonal to W** if \vec{x} is orthogonal to each vector in W .

The set of all vectors orthogonal to W is a subspace, the **orthogonal complement of W** , or W^\perp or " W perp."

$W^\perp = \{ \vec{x} \in \mathbb{R}^n : \vec{x} \cdot \vec{w} = 0 \}$

$W = \text{span} \{ \vec{v}_1, \vec{v}_2, \vec{v}_3 \}$ in \mathbb{R}^n



Soon we will do numbers here

$$\begin{cases} \vec{v}_1 \cdot \vec{x} = 0 \\ \vec{v}_2 \cdot \vec{x} = 0 \\ \vec{v}_3 \cdot \vec{x} = 0 \end{cases} \quad \begin{cases} \vec{v}_1^T \vec{x} = 0 \\ \vec{v}_2^T \vec{x} = 0 \\ \vec{v}_3^T \vec{x} = 0 \end{cases}$$

$\begin{bmatrix} \vec{v}_1^T \\ \vec{v}_2^T \\ \vec{v}_3^T \end{bmatrix} = \underline{\underline{[v_1 \ v_2 \ v_3]^T}}$

Find $\text{Nul} \left(\begin{bmatrix} \vec{v}_1^T \\ \vec{v}_2^T \\ \vec{v}_3^T \end{bmatrix} \right)$

Example

Line L is a subspace of \mathbb{R}^2 spanned by $\vec{v} = \begin{pmatrix} -1 \\ 2 \end{pmatrix}$. Then the space L^\perp is a plane. Construct an equation of the plane L^\perp .



Can also visualise line and plane with CalcPlot3D: web.monroecollege.edu/calcul3D/

$\begin{bmatrix} b \\ a \end{bmatrix} \cdot \begin{bmatrix} -a \\ b \end{bmatrix} = 0$

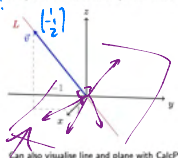
Definitions

Let W be a subspace of \mathbb{R}^n . A vector $\vec{v} \in \mathbb{R}^n$ is said to be **orthogonal** to W if \vec{v} is orthogonal to each vector in W .

The set of all vectors orthogonal to W is a subspace, the **orthogonal complement** of W , or W^\perp or W perp.

$W^\perp = \{ \vec{v} \in \mathbb{R}^n : \vec{v} \cdot \vec{w} = 0 \text{ for every } \vec{w} \in W \}$

Line L is a subspace of \mathbb{R}^3 spanned by $\vec{v} = \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix}$. Then the space L^\perp is a plane. Construct an equation of the plane L^\perp .



Want $\begin{pmatrix} a \\ b \\ c \end{pmatrix} \in \mathbb{R}^3$

st. $\begin{pmatrix} a \\ b \\ c \end{pmatrix} \cdot \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} = 0$

tell me conditions on a, b, c ?

Solve.

$a - b + 2c = 0$

$\begin{bmatrix} 1 & -1 & 2 \end{bmatrix} \begin{matrix} s \\ t \\ ? \end{matrix}$

$\vec{x} = s \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix}$

Both $\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$ & $\begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix}$

we orthogonal to $\begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix}$

Set of all solutions is $\text{span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix} \right\}$

Check $\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \cdot \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} = 0 \checkmark$
 $\begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix} \cdot \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} = 0 \checkmark$

$W = \text{span} \left\{ \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} \right\}$ then $W^\perp = \text{span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix} \right\}$

" W^\perp perp"
 is the orthogonal complement of W .

Definition

Row A is the space spanned by the rows of matrix A.

We can show that

$\dim(\text{Row}(A)) = \dim(\text{Col}(A))$

a basis for Row A is the pivot rows of RREF of A.

IF A is 2x3

$$A = \begin{pmatrix} 1 & 2 & 1 \\ 0 & 1 & 0 \end{pmatrix} \quad \text{Row } A \subseteq \mathbb{R}^3$$

$$\text{Col } A \subseteq \mathbb{R}^2$$

$$\text{Row } A = \text{span} \left\{ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right\}$$

$$A = \begin{pmatrix} 0 & 0 & 0 \\ 1 & 1 & 2 \\ 1 & 2 & 5 \end{pmatrix} \sim \begin{pmatrix} 0 & 1 & 2 \\ 0 & 0 & 3 \\ 0 & 0 & 0 \end{pmatrix}$$

Row A = span { $\begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 3 \end{pmatrix} \}$

Example *main idea*

Describe the Null(A) in terms of an orthogonal subspace.

A vector \vec{x} is in Null A if and only if

- $A\vec{x} = \vec{0}$
- This means that \vec{x} is orthogonal to each row of A.
- Row A is orthogonal complement to Null A.
- The dimension of Row A plus the dimension of Null A equals rank A + # free = # cols.

$$A\vec{x} = \vec{0}$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

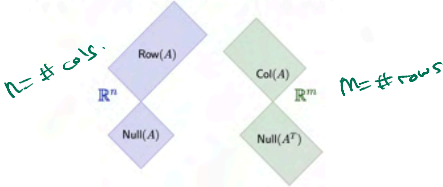
$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

Theorem (The Four Subspaces)

For any $A \in \mathbb{R}^{m \times n}$, the orthogonal complement of Row A is Null A, and the orthogonal complement of Col A is Null A^T .

The idea behind this theorem is described in the diagram below.



Additional Example (if time permits)

A has the LU factorization:

$$A = LU = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 4 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & -1 & 2 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

- Construct a basis for $(\text{Row } A)^\perp$
- Construct a basis for $(\text{Col } A)^\perp$

Hint: it is not necessary to compute A. Recall that $A^T = U^T L^T$, matrix L^T is invertible, and U^T has a non-empty nullspace.

$$\text{Col} \begin{pmatrix} 1 & 2 \\ 1 & 2 \\ 1 & 2 \end{pmatrix} = \text{Row} \begin{pmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \end{pmatrix}$$

THEOREM 3

Let A be an $m \times n$ matrix. The orthogonal complement of the row space of A is the null space of A, and the orthogonal complement of the column space of A is the null space of A^T :

$$(\text{Row } A)^\perp = \text{Null } A \quad \text{and} \quad (\text{Col } A)^\perp = \text{Null } A^T$$

$$(\text{Col } A)^\perp = (\text{Row } A^T)^\perp = \text{Null}(A^T)$$

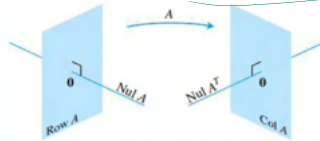
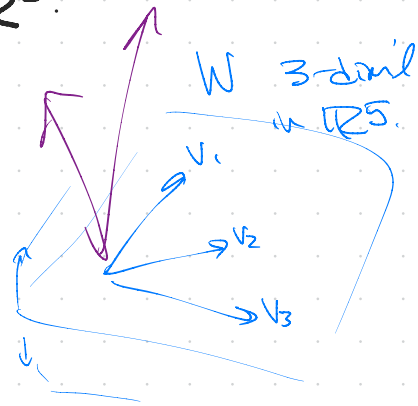


FIGURE 8 The fundamental subspaces determined by an $m \times n$ matrix A.

Example: Find a basis for the subspace W^\perp

where $W = \text{span} \{ \vec{v}_1, \vec{v}_2, \vec{v}_3 \} \subseteq \mathbb{R}^5$.

$$\vec{v}_1 = \begin{bmatrix} 1 \\ 2 \\ 2 \\ -1 \\ 3 \end{bmatrix}, \quad \vec{v}_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ -2 \\ 2 \end{bmatrix}, \quad \vec{v}_3 = \begin{bmatrix} 2 \\ 4 \\ 1 \\ 4 \\ 3 \end{bmatrix}$$



Soln. Want to solve $\vec{x} = \begin{bmatrix} a \\ b \\ c \\ d \\ e \end{bmatrix}$

$$\vec{x} \cdot \vec{v}_1 = 0 \iff \begin{bmatrix} a \\ b \\ c \\ d \\ e \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \\ 2 \\ -1 \\ 3 \end{bmatrix} = 0 \iff a + 2b + 2c - d + 3e = 0$$

$$\vec{x} \cdot \vec{v}_2 = 0 \iff \begin{bmatrix} a \\ b \\ c \\ d \\ e \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 0 \\ 1 \\ -2 \\ 2 \end{bmatrix} = 0 \iff c - 2d + 2e = 0$$

$$\vec{x} \cdot \vec{v}_3 = 0 \iff \begin{bmatrix} a \\ b \\ c \\ d \\ e \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 4 \\ 1 \\ 4 \\ 3 \end{bmatrix} = 0 \iff 2a + 4b + c + 4d + 3e = 0$$

$$\vec{x} = s \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} -3 \\ 0 \\ 2 \\ 1 \\ 0 \end{bmatrix}$$

$$x_1 + 2s + 3t = 0$$

$$x_2 = s \text{ free}$$

$$2x_3 - 2t = 0$$

$$x_4 = t \text{ free}$$

$$x_5 = 0$$

$$A = \begin{bmatrix} 1 & 2 & 2 & -1 & 3 \\ 0 & 0 & 1 & -2 & 2 \\ 2 & 4 & 1 & 4 & 3 \end{bmatrix} \xrightarrow{\sim} \begin{bmatrix} 1 & 2 & 0 & 3 & 0 \\ 0 & 0 & 1 & -2 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$W^\perp = \text{span} \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \\ 2 \\ 1 \\ 0 \end{bmatrix} \right\}$$

is a basis for W^\perp

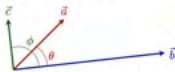
$$\left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \\ 2 \\ 1 \\ 0 \end{bmatrix} \right\}$$

Theorem

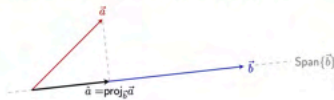
$\vec{a} \cdot \vec{b} = |\vec{a}| |\vec{b}| \cos \theta$. Thus, if $\vec{a} \cdot \vec{b} = 0$, then:

- \vec{a} and/or \vec{b} are _____ vectors, or
- \vec{a} and \vec{b} are _____.

For example, consider the vectors below.



Suppose we want to find the closed vector in $\text{Span}\{\vec{b}\}$ to \vec{a} .



- Later in this Chapter, we will make connections between dot products and **projections**.
- Projections are also used throughout multivariable calculus courses.

do now.

6.1 EXERCISES

Compute the quantities in Exercises 1–8 using the vectors

$\mathbf{u} = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$, $\mathbf{v} = \begin{bmatrix} 4 \\ 6 \end{bmatrix}$, $\mathbf{w} = \begin{bmatrix} 3 \\ -1 \\ -5 \end{bmatrix}$, $\mathbf{x} = \begin{bmatrix} 6 \\ -2 \\ 3 \end{bmatrix}$

- $\mathbf{u} \cdot \mathbf{u}$, $\mathbf{v} \cdot \mathbf{u}$, and $\frac{\mathbf{v} \cdot \mathbf{u}}{\mathbf{u} \cdot \mathbf{u}}$
- $\mathbf{w} \cdot \mathbf{w}$, $\mathbf{x} \cdot \mathbf{w}$, and $\frac{\mathbf{x} \cdot \mathbf{w}}{\mathbf{w} \cdot \mathbf{w}}$
- $\frac{1}{\mathbf{w} \cdot \mathbf{w}}$
- $\frac{1}{\mathbf{u} \cdot \mathbf{u}}$
- $\left(\frac{\mathbf{u} \cdot \mathbf{v}}{\mathbf{v} \cdot \mathbf{v}}\right) \mathbf{v}$
- $\left(\frac{\mathbf{x} \cdot \mathbf{w}}{\mathbf{x} \cdot \mathbf{x}}\right) \mathbf{x}$
- $\|\mathbf{w}\|$
- $\|\mathbf{x}\|$

In Exercises 9–12, find a unit vector in the direction of the given vector.

- $\begin{bmatrix} -30 \\ 40 \end{bmatrix}$
- $\begin{bmatrix} -6 \\ 4 \\ -3 \end{bmatrix}$
- $\begin{bmatrix} 7/4 \\ 1/2 \\ 1 \end{bmatrix}$
- $\begin{bmatrix} 8/3 \\ 2 \end{bmatrix}$

13. Find the distance between $\mathbf{x} = \begin{bmatrix} 10 \\ -3 \end{bmatrix}$ and $\mathbf{y} = \begin{bmatrix} -1 \\ -5 \end{bmatrix}$.

14. Find the distance between $\mathbf{u} = \begin{bmatrix} 0 \\ -5 \\ 2 \end{bmatrix}$ and $\mathbf{z} = \begin{bmatrix} -4 \\ -1 \\ 8 \end{bmatrix}$.

Determine which pairs of vectors in Exercises 15–18 are orthogonal.

- $\mathbf{a} = \begin{bmatrix} 8 \\ -5 \end{bmatrix}$, $\mathbf{b} = \begin{bmatrix} -2 \\ -3 \end{bmatrix}$
- $\mathbf{u} = \begin{bmatrix} 12 \\ 3 \\ -5 \end{bmatrix}$, $\mathbf{v} = \begin{bmatrix} 2 \\ -3 \\ 3 \end{bmatrix}$
- $\mathbf{u} = \begin{bmatrix} 3 \\ 2 \\ -5 \end{bmatrix}$, $\mathbf{v} = \begin{bmatrix} -4 \\ -2 \\ 6 \end{bmatrix}$
- $\mathbf{y} = \begin{bmatrix} -3 \\ 7 \\ 4 \\ 0 \end{bmatrix}$, $\mathbf{z} = \begin{bmatrix} 1 \\ -8 \\ 15 \\ -7 \end{bmatrix}$

In Exercises 19 and 20, all vectors are in \mathbb{R}^n . Mark each statement True or False. Justify each answer.

- $\mathbf{v} \cdot \mathbf{v} = \|\mathbf{v}\|^2$.
- For any scalar c , $\mathbf{u} \cdot (c\mathbf{v}) = c(\mathbf{u} \cdot \mathbf{v})$.
- If the distance from \mathbf{u} to \mathbf{v} equals the distance from \mathbf{u} to $-\mathbf{v}$, then \mathbf{u} and \mathbf{v} are orthogonal.
- For a square matrix A , vectors in $\text{Col } A$ are orthogonal to vectors in $\text{Nul } A$.

e. If vectors $\mathbf{v}_1, \dots, \mathbf{v}_p$ span a subspace W and if \mathbf{x} is orthogonal to each \mathbf{v}_j for $j = 1, \dots, p$, then \mathbf{x} is in W^\perp .

- $\mathbf{a} \cdot \mathbf{v} - \mathbf{v} \cdot \mathbf{u} = 0$.
- For any scalar c , $\|c\mathbf{v}\| = c\|\mathbf{v}\|$.
- If \mathbf{x} is orthogonal to every vector in a subspace W , then \mathbf{x} is in W^\perp .
- If $\|\mathbf{u}\|^2 + \|\mathbf{v}\|^2 = \|\mathbf{u} + \mathbf{v}\|^2$, then \mathbf{u} and \mathbf{v} are orthogonal.
- For an $m \times n$ matrix A , vectors in the null space of A are orthogonal to vectors in the row space of A .

- Use the transpose definition of the inner product to verify parts (b) and (c) of Theorem 1. Mention the appropriate facts from Chapter 2.
- Let $\mathbf{u} = (u_1, u_2, u_3)$. Explain why $\mathbf{u} \cdot \mathbf{u} \geq 0$. When is $\mathbf{u} \cdot \mathbf{u} = 0$?

23. Let $\mathbf{u} = \begin{bmatrix} 2 \\ -5 \\ -1 \end{bmatrix}$ and $\mathbf{v} = \begin{bmatrix} -7 \\ -4 \\ 6 \end{bmatrix}$. Compute and compare $\mathbf{u} \cdot \mathbf{v}$, $\|\mathbf{u}\|^2$, $\|\mathbf{v}\|^2$, and $\|\mathbf{u} + \mathbf{v}\|^2$. Do not use the Pythagorean Theorem.

24. Verify the *parallelogram law* for vectors \mathbf{u} and \mathbf{v} in \mathbb{R}^n : $\|\mathbf{u} + \mathbf{v}\|^2 + \|\mathbf{u} - \mathbf{v}\|^2 = 2\|\mathbf{u}\|^2 + 2\|\mathbf{v}\|^2$

25. Let $\mathbf{v} = \begin{bmatrix} a \\ b \end{bmatrix}$. Describe the set H of vectors $\begin{bmatrix} x \\ y \end{bmatrix}$ that are orthogonal to \mathbf{v} . [Hint: Consider $\mathbf{v} = \mathbf{0}$ and $\mathbf{v} \neq \mathbf{0}$.]

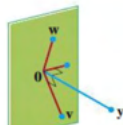
26. Let $\mathbf{u} = \begin{bmatrix} 5 \\ 7 \end{bmatrix}$, and let W be the set of all \mathbf{x} in \mathbb{R}^3 such that $\mathbf{u} \cdot \mathbf{x} = 0$. What theorem in Chapter 4 can be used to show that W is a subspace of \mathbb{R}^3 ? Describe W in geometric language.

27. Suppose a vector \mathbf{y} is orthogonal to vectors \mathbf{u} and \mathbf{v} . Show that \mathbf{y} is orthogonal to the vector $\mathbf{u} + \mathbf{v}$.

28. Suppose \mathbf{y} is orthogonal to \mathbf{u} and \mathbf{v} . Show that \mathbf{y} is orthogonal to every \mathbf{w} in $\text{Span}\{\mathbf{u}, \mathbf{v}\}$. [Hint: An arbitrary \mathbf{w} in $\text{Span}\{\mathbf{u}, \mathbf{v}\}$ has the form $\mathbf{w} = c_1\mathbf{u} + c_2\mathbf{v}$. Show that \mathbf{y} is orthogonal to such a vector \mathbf{w} .]

29. Let $W = \text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$. Show that if \mathbf{x} is orthogonal to each \mathbf{v}_j , for $1 \leq j \leq p$, then \mathbf{x} is orthogonal to every vector in W .

Lay Linear Algebra.



Section 6.2 : Orthogonal Sets

Chapter 6 : Orthogonality and Least Squares

Math 1554 Linear Algebra

Week	Mon	Tue	Wed	Thu	Fri
1	1.84-1.92	1.93	WS1.1	1.94	WS1.2, 1.95
2	1.93-1.97	1.98	WS1.3	1.99	WS1.4, 1.99
3	1.99-2.03	2.04	WS1.5, 2.05	2.06	WS1.6, 2.07
4	2.03-2.07	2.08, 2.09	WS1.7, 2.10	2.11	WS1.8, 2.12
5	2.07-2.11	2.12, 2.13	WS1.9, 2.14	2.15	WS1.10, 2.16
6	2.11-2.15	2.16	WS1.11, 2.17	2.18	WS1.12, 2.19
7	2.15-2.19	2.20	WS1.13	2.21	WS1.14, 2.22
8	2.19-2.23	2.24	WS1.15, 2.25	2.26	WS1.16, 2.27
9	2.23-2.27	2.28	WS1.17, 2.29	2.30	WS1.18, 2.31
10	2.27-2.31	3.1	WS1.19, 3.2	3.3	WS1.20, 3.4
11	3.1-3.5	3.6	WS1.21, 3.7	3.8	WS1.22, 3.9
12	3.5-3.9	4.0	WS1.23, 4.1	4.2	WS1.24, 4.3
13	4.1-4.5	4.6	WS1.25, 4.7	4.8	WS1.26, 4.9
14	4.5-4.9	5.0	WS1.27, 5.1	5.2	WS1.28, 5.3
15	4.9-5.3	5.4	WS1.29, 5.5	5.6	WS1.30, 5.7
16	5.3-5.7	5.8	WS1.31, 5.9	6.0	WS1.32, 6.1
17	5.7-6.1	6.2	WS1.33, 6.3	6.4	WS1.34, 6.5

Topics and Objectives

Topics

1. Orthogonal Sets of Vectors
2. Orthogonal Bases and Projections.

Learning Objectives

1. Apply the concepts of orthogonality to
 - a) compute orthogonal projections and distances,
 - b) express a vector as a linear combination of orthogonal vectors,
 - c) characterize bases for subspaces of \mathbb{R}^n , and
 - d) construct orthonormal bases.

Motivating Question

What are the special properties of this basis for \mathbb{R}^3 ?

$$\begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix} / \sqrt{11}, \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix} / \sqrt{6}, \begin{bmatrix} -1 \\ -4 \\ 7 \end{bmatrix} / \sqrt{66}$$

Section 6.2 : Orthogonal Sets

Chapter 6 : Orthogonality and Least Squares

Math 1554 Linear Algebra

Orthogonal Vector Sets

$$\begin{pmatrix} 4 \\ 2 \end{pmatrix} = \frac{4 \cdot 3}{2} = \begin{pmatrix} 6 \end{pmatrix} \quad \begin{pmatrix} 5 \\ 2 \end{pmatrix} = \frac{5 \cdot 4}{2} = \begin{pmatrix} 10 \end{pmatrix}$$

Linear Independence

Definition

A set of vectors $\{\vec{u}_1, \dots, \vec{u}_p\}$ are an orthogonal set of vectors if for each $j \neq k$, $\vec{u}_j \perp \vec{u}_k$.

Example: Fill in the missing entries to make $\{\vec{u}_1, \vec{u}_2, \vec{u}_3\}$ an orthogonal set of vectors.

$$\vec{u}_1 = \begin{bmatrix} 4 \\ 1 \\ 1 \end{bmatrix}, \vec{u}_2 = \begin{bmatrix} -2 \\ 1 \\ 7 \end{bmatrix}, \vec{u}_3 = \begin{bmatrix} 1 \\ ? \\ ? \end{bmatrix}$$

Theorem (Linear Independence for Orthogonal Sets)

Let $\{\vec{u}_1, \dots, \vec{u}_p\}$ be an orthogonal set of vectors. Then, for scalars c_1, \dots, c_p ,

$$\|c_1 \vec{u}_1 + \dots + c_p \vec{u}_p\|^2 = c_1^2 \|\vec{u}_1\|^2 + \dots + c_p^2 \|\vec{u}_p\|^2.$$

In particular, if all the vectors \vec{u}_i are non-zero, the set of vectors $\{\vec{u}_1, \dots, \vec{u}_p\}$ are linearly independent.

$$\vec{u}_1 \cdot \vec{u}_2 = 0 \rightarrow -8 + 1 + k = 0$$

$$\vec{u}_1 \cdot \vec{u}_3 = 0$$

$$\begin{bmatrix} 4 & 1 & 1 \\ -2 & 1 & 7 \end{bmatrix} \sim \begin{bmatrix} -2 & 1 & 7 \\ 0 & 3 & 15 \end{bmatrix} \sim \begin{bmatrix} -2 & 1 & 7 \\ 0 & 1 & 5 \end{bmatrix}$$

$$\vec{u}_2 \cdot \vec{u}_3 = 0$$

$$\begin{bmatrix} 4 \\ 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} a \\ b \\ c \end{bmatrix} = 0 \Leftrightarrow 4a + b + c = 0$$

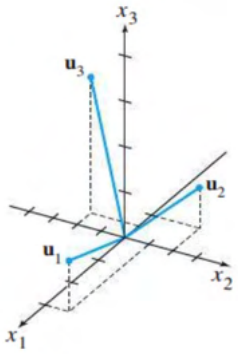
$$\begin{bmatrix} -2 \\ 1 \\ 7 \end{bmatrix} \cdot \begin{bmatrix} a \\ b \\ c \end{bmatrix} = 0 \Leftrightarrow -2a + b + 7c = 0$$

$$\vec{x} = s \begin{bmatrix} 1 \\ -5 \\ 1 \end{bmatrix}$$



$\left\{ \begin{bmatrix} 4 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -2 \\ 1 \\ 7 \end{bmatrix}, \begin{bmatrix} 1 \\ -5 \\ 1 \end{bmatrix} \right\}$ orthogonal set

$\left\{ \begin{bmatrix} 4 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -2 \\ 1 \\ 7 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right\}$ orthogonal set!



EXAMPLE 1 Show that $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is an orthogonal set, where

$$\mathbf{u}_1 = \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix}, \quad \mathbf{u}_2 = \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}, \quad \mathbf{u}_3 = \begin{bmatrix} -1/2 \\ -2 \\ 7/2 \end{bmatrix}$$

FIGURE 1

Orthogonal Bases

Next time

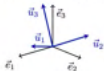
Theorem (Expansion in Orthogonal Basis)

Let $\{\vec{u}_1, \dots, \vec{u}_p\}$ be an orthogonal basis for a subspace W of \mathbb{R}^n . Then, for any vector $\vec{w} \in W$,

$$\vec{w} = c_1 \vec{u}_1 + \dots + c_p \vec{u}_p.$$

Above, the scalars are $c_j = \frac{\vec{w} \cdot \vec{u}_j}{\vec{u}_j \cdot \vec{u}_j}$.

For example, any vector $\vec{w} \in \mathbb{R}^3$ can be written as a linear combination of $\{\vec{e}_1, \vec{e}_2, \vec{e}_3\}$, or some other orthogonal basis $\{\vec{u}_1, \vec{u}_2, \vec{u}_3\}$.



Example

$$\vec{x} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \quad \vec{u} = \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix}, \quad \vec{v} = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}, \quad \vec{w} = \begin{pmatrix} 3 \\ -1 \\ 1 \end{pmatrix}$$

Let W be the subspace of \mathbb{R}^3 that is orthogonal to \vec{w} .

- a) Check that an orthogonal basis for W is given by \vec{u} and \vec{v} .
- b) Compute the expansion of \vec{x} in basis W .

Knack?

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THEOREM 4 If $S = \{\vec{u}_1, \dots, \vec{u}_p\}$ is an orthogonal set of nonzero vectors in \mathbb{R}^n , then S is linearly independent and hence is a basis for the subspace spanned by S .

Projections

Let \vec{u} be a non-zero vector, and let \vec{v} be some other vector. The **orthogonal projection** of \vec{v} onto the direction of \vec{u} is the vector in the span of \vec{u} that is closest to \vec{v} .

$$\text{proj}_{\vec{u}} \vec{v} = \frac{\vec{v} \cdot \vec{u}}{\vec{u} \cdot \vec{u}} \vec{u}$$

The vector $\vec{w} = \vec{v} - \text{proj}_{\vec{u}} \vec{v}$ is orthogonal to \vec{u} , so that

$$\vec{v} = \text{proj}_{\vec{u}} \vec{v} + \vec{w}$$

$$\|\vec{v}\|^2 = \|\text{proj}_{\vec{u}} \vec{v}\|^2 + \|\vec{w}\|^2$$



Example

Let L be spanned by $(1, 1, 1)$ in \mathbb{R}^3 .

- 1. Find the projection of $\vec{v} = (-3, 5, 6, -4)$ onto the line L .
- 2. How close is \vec{v} to the line L ?

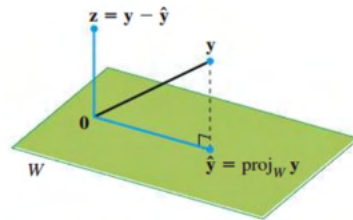


FIGURE 2
Finding α to make $\vec{y} - \hat{\vec{y}}$ orthogonal to \vec{u} .

Next time

$\vec{u} \cdot \vec{v} = 0$ so the easy way works!

$$\vec{x} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \vec{u} = \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix}, \vec{v} = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}, \vec{x} = \begin{pmatrix} 3 \\ -4 \\ 1 \end{pmatrix}$$

Let W be the subspace of \mathbb{R}^3 that is orthogonal to \vec{x} .

- Check that an orthogonal basis for W is given by \vec{u} and \vec{v} .
- Compute the expansion of \vec{x} in basis W .

Theorem (Expansion in Orthogonal Basis)

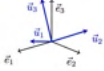
Let $\{\vec{u}_1, \dots, \vec{u}_p\}$ be an orthogonal basis for a subspace W of \mathbb{R}^n . Then, for any vector $\vec{u} \in W$,

$$\vec{u} = c_1 \vec{u}_1 + \dots + c_p \vec{u}_p.$$

Above, the scalars are $c_j = \frac{\vec{u} \cdot \vec{u}_j}{\vec{u}_j \cdot \vec{u}_j}$.

WARNING!

For example, any vector $\vec{u} \in \mathbb{R}^3$ can be written as a linear combination of $\{\vec{e}_1, \vec{e}_2, \vec{e}_3\}$, or some other orthogonal basis $\{\vec{u}_1, \vec{u}_2, \vec{u}_3\}$.



coordinates of \vec{x} in basis B

$$\begin{bmatrix} 3 \\ -4 \\ 1 \end{bmatrix}_B = \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} \text{ means}$$

$$\vec{x} = c_1 \vec{v}_1 + c_2 \vec{v}_2 + c_3 \vec{v}_3$$

where $\vec{v}_1, \vec{v}_2, \vec{v}_3$ basis for $W = \text{span}\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$
 $\vec{x} \in W$.

$W = \text{span}\{\vec{u}, \vec{v}\}$ plane in \mathbb{R}^3

$$\begin{bmatrix} 3 \\ -4 \\ 1 \end{bmatrix}_B = \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$

$$\begin{bmatrix} 3 \\ -4 \\ 1 \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

$$2 \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} + (-1) \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ -4 \\ 1 \end{bmatrix} \checkmark$$

OLD WAY

$$\left[\begin{array}{cc|c} 1 & -1 & 3 \\ -2 & 0 & -4 \\ 1 & 1 & 1 \end{array} \right] \sim \frac{1}{2} \text{row} \left[\begin{array}{cc|c} 1 & -1 & 3 \\ 1 & 0 & 2 \\ 1 & 1 & 1 \end{array} \right] \quad \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$

$$\sim \uparrow \left[\begin{array}{cc|c} 1 & 0 & 2 \\ 0 & -1 & 1 \\ 0 & 1 & -1 \end{array} \right] \sim \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$

EASIER WAY

$$c_1 = \frac{\begin{bmatrix} 3 \\ -4 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}}{\begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}} = \frac{3+8+1}{1+4+1} = \frac{12}{6} = 2$$

$$c_2 = \frac{\begin{bmatrix} 3 \\ -4 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}}{\begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}} = \frac{-3+1}{1+1} = \frac{-2}{2} = -1$$

Ex. What happens if $\vec{s} \notin W = \text{span}\{\vec{v}_1, \vec{v}_2\}$?

New $\vec{v}_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$ $\vec{v}_2 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$ $\vec{s} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$

If $\vec{s} \notin W$
then don't
get \vec{s} back?

(Want to use the formula

Check - $\vec{v}_1 \cdot \vec{v}_2 = 0$

$$\vec{s} \stackrel{?}{=} \frac{\vec{s} \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 + \frac{\vec{s} \cdot \vec{v}_2}{\vec{v}_2 \cdot \vec{v}_2} \vec{v}_2$$

$$\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} = -1 + 1 = 0$$

So $\{\vec{v}_1, \vec{v}_2\}$ orthogonal
basis for W .

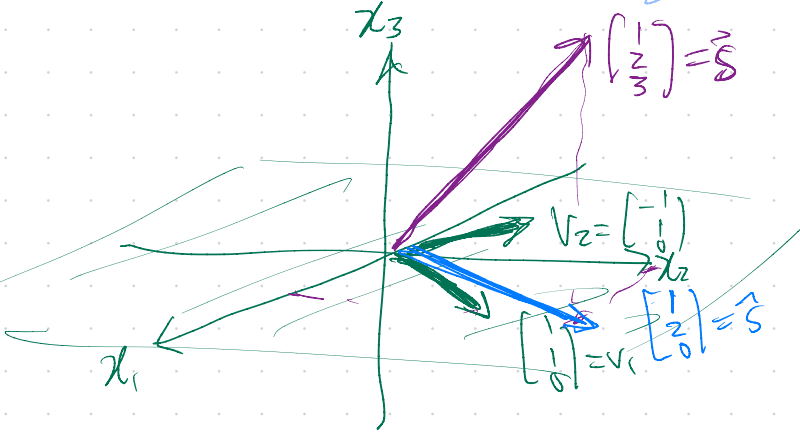
$$= \frac{\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}}{\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + \frac{\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}}{\begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$$

$$= \frac{3}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + \frac{1}{2} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} \neq \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \vec{s}$$

x_3

$$\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \vec{s}$$

\hookrightarrow hat



$$\vec{v}_2 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} = \vec{s}$$

$$\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = \vec{v}_1$$

$W = \text{span}\{\vec{v}_1, \vec{v}_2\}$
is the floor.

EXAMPLE 3 Let $y = \begin{bmatrix} 7 \\ 6 \end{bmatrix}$ and $u = \begin{bmatrix} 4 \\ 2 \end{bmatrix}$. Find the orthogonal projection of y onto u . Then write y as the sum of two orthogonal vectors, one in $\text{Span}\{u\}$ and one orthogonal to u .

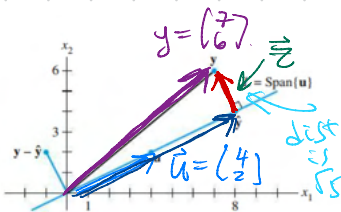


FIGURE 3 The orthogonal projection of y onto a line L through the origin.

$$\hat{y} = \text{proj}_u(\vec{y}) = \hat{y}$$

$$\hat{y} = C * \vec{u}$$

$$\hat{y} = \frac{\vec{y} \cdot \vec{u}}{\vec{u} \cdot \vec{u}} \vec{u} = \frac{\begin{bmatrix} 7 \\ 6 \end{bmatrix} \cdot \begin{bmatrix} 4 \\ 2 \end{bmatrix}}{\begin{bmatrix} 4 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} 4 \\ 2 \end{bmatrix}} \begin{bmatrix} 4 \\ 2 \end{bmatrix} = \frac{40}{20} \begin{bmatrix} 4 \\ 2 \end{bmatrix} = 2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} = \begin{bmatrix} 8 \\ 4 \end{bmatrix}$$

New Q: how close is $\vec{y} = \begin{bmatrix} 7 \\ 6 \end{bmatrix}$ to $\text{span}\{\vec{u}\}$?

$$2\vec{u} + \vec{z} = \vec{y} \quad \text{so} \quad \|\vec{z}\| = \|\vec{y} - \hat{y}\| = \left\| \begin{bmatrix} 7 \\ 6 \end{bmatrix} - \begin{bmatrix} 8 \\ 4 \end{bmatrix} \right\| = \left\| \begin{bmatrix} -1 \\ 2 \end{bmatrix} \right\| = \sqrt{1+4} = \sqrt{5}$$

Definition

Definition (Orthonormal Basis)
 An **orthonormal basis** for a subspace W is an orthogonal basis $\{\vec{u}_1, \dots, \vec{u}_p\}$ in which every vector \vec{u}_i has unit length. In this case, for each $\vec{w} \in W$,

$$\vec{w} = [(\vec{w} \cdot \vec{u}_1)\vec{u}_1 + \dots + (\vec{w} \cdot \vec{u}_p)\vec{u}_p]$$

$$\|\vec{w}\| = \sqrt{[(\vec{w} \cdot \vec{u}_1)]^2 + \dots + [(\vec{w} \cdot \vec{u}_p)]^2}$$

Example

The subspace W is a subspace of \mathbb{R}^3 perpendicular to $(1, 1, 1)$. Calculate the missing coefficients in the orthonormal basis for W .

$$\left\{ \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \right\}$$

is an orthonormal basis for $(\text{span}\{(1,1,1)\})^\perp$

Step 1: Find a basis of $(\text{span}\{(1,1,1)\})^\perp$

consisting of orthogonal vectors.

Step 2: Normalize them.

IF \vec{v}_1, \vec{v}_2 are orthogonal basis for $(\text{span}\{(1,1,1)\})^\perp$

Then

$$\left\{ \frac{1}{\|\vec{v}_1\|} \vec{v}_1, \frac{1}{\|\vec{v}_2\|} \vec{v}_2 \right\}$$

orthonormal basis

want $\begin{bmatrix} a \\ b \\ c \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = 0$

(so that $\begin{bmatrix} a \\ b \\ c \end{bmatrix} \in (\text{span}\{(1,1,1)\})^\perp$)

also $\begin{bmatrix} a \\ b \\ c \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = 0$

(so that $\begin{bmatrix} a \\ b \\ c \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$ are orthogonal)

Compute Null of

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 2 \end{bmatrix} \vec{x} = \begin{bmatrix} -z \\ -z \\ z \end{bmatrix}$$

Orthogonal Matrices

An orthogonal matrix is a square matrix whose columns are orthonormal.

Theorem

An $n \times n$ matrix U has orthonormal columns if and only if $U^T U = I_n$.

Note that this theorem does not apply when $n > m$. Why?

$$A = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{pmatrix} \quad A \text{ has orthonormal columns? } \boxed{?}$$

Theorem

Theorem (Mapping Properties of Orthogonal Matrices)

Assume $m \times m$ matrix U has orthonormal columns. Then

- (Preserves length) $\|Ux\| = \|x\|$
- (Preserves angles) $(Ux) \cdot (Uy) = x \cdot y$
- (Preserves orthogonality) If $x \perp y = 0$

then $Ux \cdot Uy = 0$

$$\|Ux\|^2 = (Ux) \cdot (Ux) = (Ux)^T Ux = x^T U^T Ux = x^T I x = x^T x = \|x\|^2$$

Additional Example (if time permits)

A 4×4 orthonormal matrix is below. It's columns are orthonormal.

$$A = \begin{bmatrix} 1/2 & 2/\sqrt{10} & 1/2 & 1/\sqrt{10} \\ 1/2 & 1/\sqrt{10} & -1/2 & -2/\sqrt{10} \\ 1/2 & -1/\sqrt{10} & -3/2 & 2/\sqrt{10} \\ 1/2 & -2/\sqrt{10} & 1/2 & -1/\sqrt{10} \end{bmatrix}$$

Verify that the rows also form an orthonormal basis.

If U is orthogonal matrix then $\det(U) = ?$

Step 1

$$\det(U^T U) \stackrel{?}{=} \det(I) = 1$$

$$= \det(U^T) + \det(U)$$

$$= (\det U)(\det U) = 1$$

$$\Rightarrow (\det U)^2 = 1$$

$$\Rightarrow \det U = 1 \text{ or } -1$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1/2 \end{bmatrix}$$

Section 12.1 Example 10

$$U = \begin{bmatrix} 1/\sqrt{2} & 0 & 1/\sqrt{2} \\ 0 & 1 & 0 \\ -1/\sqrt{2} & 0 & 1/\sqrt{2} \end{bmatrix}$$

Section 12.1 Example 10

has orthonormal columns

$$U_1 \cdot U_1 = 1 \quad \|U_1\|^2 = 1$$

$$\overline{U_1} \cdot U_2 = 0$$

$$U^T U = \begin{bmatrix} 1/2 & 0 & -1/2 \\ 0 & 1 & 0 \\ 1/2 & 0 & 1/2 \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} & 0 & 1/\sqrt{2} \\ 0 & 1 & 0 \\ -1/\sqrt{2} & 0 & 1/\sqrt{2} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$U_i \cdot U_j = 0$$

$$U_i \cdot U_i = 1$$

6.2 EXERCISES

In Exercises 1–6, determine which sets of vectors are orthogonal.

$$1. \begin{bmatrix} -1 \\ 4 \\ -3 \end{bmatrix}, \begin{bmatrix} 5 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ -4 \\ -7 \end{bmatrix}$$

$$2. \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} -5 \\ -2 \\ 1 \end{bmatrix}$$

$$5. \begin{bmatrix} 3 \\ -2 \\ 1 \\ 3 \end{bmatrix}, \begin{bmatrix} -1 \\ 3 \\ -3 \\ 4 \end{bmatrix}, \begin{bmatrix} 3 \\ 8 \\ 7 \\ 0 \end{bmatrix}$$

$$6. \begin{bmatrix} 5 \\ -4 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} -4 \\ 1 \\ -3 \\ 8 \end{bmatrix}, \begin{bmatrix} 3 \\ 3 \\ 5 \\ -1 \end{bmatrix}$$

In Exercises 7–10, show that $\{\mathbf{u}_1, \mathbf{u}_2\}$ or $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is an orthogonal basis for \mathbb{R}^2 or \mathbb{R}^3 , respectively. Then express \mathbf{x} as a linear combination of the \mathbf{u} 's.

$$3. \begin{bmatrix} 2 \\ -7 \\ -1 \end{bmatrix}, \begin{bmatrix} -6 \\ -3 \\ 9 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \\ -1 \end{bmatrix}$$

$$4. \begin{bmatrix} 2 \\ -5 \\ -3 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ -3 \end{bmatrix}, \begin{bmatrix} 4 \\ -2 \\ 6 \end{bmatrix}$$

$$7. \mathbf{u}_1 = \begin{bmatrix} 2 \\ -3 \end{bmatrix}, \mathbf{u}_2 = \begin{bmatrix} 6 \\ 4 \end{bmatrix}, \text{ and } \mathbf{x} = \begin{bmatrix} 9 \\ -7 \end{bmatrix}$$

¹A better name might be *orthonormal matrix*, and this term is found in some statistics texts. However, *orthogonal matrix* is the standard term in linear algebra.

$$8. \mathbf{u}_1 = \begin{bmatrix} 3 \\ 1 \end{bmatrix}, \mathbf{u}_2 = \begin{bmatrix} -2 \\ 6 \end{bmatrix}, \text{ and } \mathbf{x} = \begin{bmatrix} -6 \\ 3 \end{bmatrix}$$

$$9. \mathbf{u}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \mathbf{u}_2 = \begin{bmatrix} -1 \\ 4 \\ 1 \end{bmatrix}, \mathbf{u}_3 = \begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix}, \text{ and } \mathbf{x} = \begin{bmatrix} 8 \\ -4 \\ -3 \end{bmatrix}$$

$$10. \mathbf{u}_1 = \begin{bmatrix} 3 \\ -3 \\ 0 \end{bmatrix}, \mathbf{u}_2 = \begin{bmatrix} 2 \\ 2 \\ -1 \end{bmatrix}, \mathbf{u}_3 = \begin{bmatrix} 1 \\ 1 \\ 4 \end{bmatrix}, \text{ and } \mathbf{x} = \begin{bmatrix} 5 \\ -3 \\ 1 \end{bmatrix}$$

11. Compute the orthogonal projection of $\begin{bmatrix} 1 \\ 7 \end{bmatrix}$ onto the line through $\begin{bmatrix} -4 \\ 2 \end{bmatrix}$ and the origin.

12. Compute the orthogonal projection of $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$ onto the line through $\begin{bmatrix} -1 \\ 3 \end{bmatrix}$ and the origin.

13. Let $\mathbf{y} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$ and $\mathbf{u} = \begin{bmatrix} 4 \\ -7 \end{bmatrix}$. Write \mathbf{y} as the sum of two orthogonal vectors, one in $\text{Span}\{\mathbf{u}\}$ and one orthogonal to \mathbf{u} .

14. Let $\mathbf{y} = \begin{bmatrix} 2 \\ 6 \end{bmatrix}$ and $\mathbf{u} = \begin{bmatrix} 7 \\ 1 \end{bmatrix}$. Write \mathbf{y} as the sum of a vector in $\text{Span}\{\mathbf{u}\}$ and a vector orthogonal to \mathbf{u} .

15. Let $\mathbf{y} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$ and $\mathbf{u} = \begin{bmatrix} 8 \\ 6 \end{bmatrix}$. Compute the distance from \mathbf{y} to the line through \mathbf{u} and the origin.

16. Let $\mathbf{y} = \begin{bmatrix} -3 \\ 9 \end{bmatrix}$ and $\mathbf{u} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$. Compute the distance from \mathbf{y} to the line through \mathbf{u} and the origin.

In Exercises 17–22, determine which sets of vectors are orthonormal. If a set is only orthogonal, normalize the vectors to produce an orthonormal set.

$$17. \begin{bmatrix} 1/3 \\ 1/3 \\ 1/3 \end{bmatrix}, \begin{bmatrix} -1/2 \\ 0 \\ 1/2 \end{bmatrix}$$

$$18. \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 0 \end{bmatrix}$$

$$19. \begin{bmatrix} -.6 \\ .8 \end{bmatrix}, \begin{bmatrix} .8 \\ .6 \end{bmatrix}$$

$$20. \begin{bmatrix} -2/3 \\ 1/3 \\ 2/3 \end{bmatrix}, \begin{bmatrix} 1/3 \\ 2/3 \\ 0 \end{bmatrix}$$

$$21. \begin{bmatrix} 1/\sqrt{10} \\ 3/\sqrt{20} \\ 3/\sqrt{20} \end{bmatrix}, \begin{bmatrix} 3/\sqrt{10} \\ -1/\sqrt{20} \\ -1/\sqrt{20} \end{bmatrix}, \begin{bmatrix} 0 \\ -1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}$$

$$22. \begin{bmatrix} 1/\sqrt{18} \\ 4/\sqrt{18} \\ 1/\sqrt{18} \end{bmatrix}, \begin{bmatrix} 1/\sqrt{2} \\ 0 \\ -1/\sqrt{2} \end{bmatrix}, \begin{bmatrix} -2/3 \\ 1/3 \\ -2/3 \end{bmatrix}$$

In Exercises 23 and 24, all vectors are in \mathbb{R}^n . Mark each statement True or False. Justify each answer.

- If \mathbf{y} is a linear combination of nonzero vectors from an orthogonal set, then the weights in the linear combination can be computed without row operations on a matrix.
- If the vectors in an orthogonal set of nonzero vectors are normalized, then some of the new vectors may not be orthogonal.
- A matrix with orthonormal columns is an orthogonal matrix.
- If L is a line through $\mathbf{0}$ and if $\hat{\mathbf{y}}$ is the orthogonal projection of \mathbf{y} onto L , then $\|\hat{\mathbf{y}}\|$ gives the distance from \mathbf{y} to L .

- Not every orthogonal set in \mathbb{R}^n is linearly independent.
- If a set $S = \{\mathbf{u}_1, \dots, \mathbf{u}_p\}$ has the property that $\mathbf{u}_i \cdot \mathbf{u}_j = 0$ whenever $i \neq j$, then S is an orthonormal set.
- If the columns of an $m \times n$ matrix A are orthonormal, then the linear mapping $\mathbf{x} \mapsto A\mathbf{x}$ preserves lengths.
- The orthogonal projection of \mathbf{y} onto \mathbf{v} is the same as the orthogonal projection of \mathbf{y} onto $c\mathbf{v}$ whenever $c \neq 0$.
- An orthogonal matrix is invertible.

24. a. Not every orthogonal set in \mathbb{R}^n is linearly independent.
 b. If a set $S = \{\mathbf{u}_1, \dots, \mathbf{u}_p\}$ has the property that $\mathbf{u}_i \cdot \mathbf{u}_j = 0$ whenever $i \neq j$, then S is an orthonormal set.
 c. If the columns of an $m \times n$ matrix A are orthonormal, then the linear mapping $\mathbf{x} \mapsto A\mathbf{x}$ preserves lengths.
 d. The orthogonal projection of \mathbf{y} onto \mathbf{v} is the same as the orthogonal projection of \mathbf{y} onto $c\mathbf{v}$ whenever $c \neq 0$.
 e. An orthogonal matrix is invertible.

25. Prove Theorem 7. [Hint: For (a), compute $\|U\mathbf{x}\|^2$, or prove (b) first.]

26. Suppose W is a subspace of \mathbb{R}^n spanned by n nonzero orthogonal vectors. Explain why $W = \mathbb{R}^n$.

27. Let U be a square matrix with orthonormal columns. Explain why U is invertible. (Mention the theorems you use.)

28. Let U be an $n \times n$ orthogonal matrix. Show that the rows of U form an orthonormal basis of \mathbb{R}^n .

29. Let U and V be $n \times n$ orthogonal matrices. Explain why UV is an orthogonal matrix. [That is, explain why UV is invertible and its inverse is $(UV)^T$.]

30. Let U be an orthogonal matrix, and construct V by interchanging some of the columns of U . Explain why V is an orthogonal matrix.

31. Show that the orthogonal projection of a vector \mathbf{y} onto a line L through the origin in \mathbb{R}^2 does not depend on the choice of the nonzero \mathbf{u} in L used in the formula for $\hat{\mathbf{y}}$. To do this, suppose \mathbf{y} and \mathbf{u} are given and $\hat{\mathbf{y}}$ has been computed by formula (2) in this section. Replace \mathbf{u} in that formula by $c\mathbf{u}$, where c is an unspecified nonzero scalar. Show that the new formula gives the same $\hat{\mathbf{y}}$.

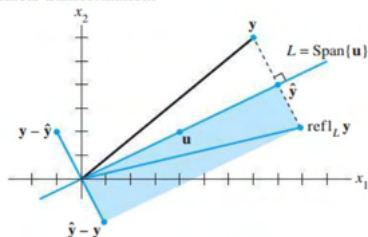
32. Let $\{\mathbf{v}_1, \mathbf{v}_2\}$ be an orthogonal set of nonzero vectors, and let c_1, c_2 be any nonzero scalars. Show that $\{c_1\mathbf{v}_1, c_2\mathbf{v}_2\}$ is also an orthogonal set. Since orthogonality of a set is defined in terms of pairs of vectors, this shows that if the vectors in an orthogonal set are normalized, the new set will still be orthogonal.

33. Given $\mathbf{u} \neq \mathbf{0}$ in \mathbb{R}^n , let $L = \text{Span}\{\mathbf{u}\}$. Show that the mapping $\mathbf{x} \mapsto \text{proj}_L \mathbf{x}$ is a linear transformation.

34. Given $\mathbf{u} \neq \mathbf{0}$ in \mathbb{R}^n , let $L = \text{Span}\{\mathbf{u}\}$. For \mathbf{y} in \mathbb{R}^n , the reflection of \mathbf{y} in L is the point $\text{refl}_L \mathbf{y}$ defined by

$$\text{refl}_L \mathbf{y} = 2 \cdot \text{proj}_L \mathbf{y} - \mathbf{y}$$

See the figure, which shows that $\text{refl}_L \mathbf{y}$ is the sum of $\hat{\mathbf{y}} = \text{proj}_L \mathbf{y}$ and $\hat{\mathbf{y}} - \mathbf{y}$. Show that the mapping $\mathbf{y} \mapsto \text{refl}_L \mathbf{y}$ is a linear transformation.



The reflection of \mathbf{y} in a line through the origin.

35. [M] Show that the columns of the matrix A are orthogonal by making an appropriate matrix calculation. State the calculation you use.

$$A = \begin{bmatrix} -6 & -3 & 6 & 1 \\ -1 & 2 & 1 & -6 \\ 3 & 6 & 3 & -2 \\ 6 & -3 & 6 & -1 \\ 2 & -1 & 2 & 3 \\ -3 & 6 & 3 & 2 \\ -2 & -1 & 2 & -3 \\ 1 & 2 & 1 & 6 \end{bmatrix}$$

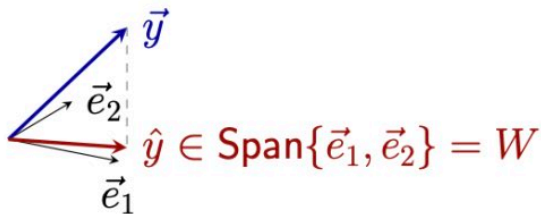
36. [M] In parts (a)–(d), let U be the matrix formed by normalizing each column of the matrix A in Exercise 35.

- a. Compute $U^T U$ and $U U^T$. How do they differ?
 b. Generate a random vector \mathbf{y} in \mathbb{R}^8 , and compute $\mathbf{p} = U U^T \mathbf{y}$ and $\mathbf{z} = \mathbf{y} - \mathbf{p}$. Explain why \mathbf{p} is in $\text{Col } A$. Verify that \mathbf{z} is orthogonal to \mathbf{p} .
 c. Verify that \mathbf{z} is orthogonal to each column of U .
 d. Notice that $\mathbf{y} = \mathbf{p} + \mathbf{z}$, with \mathbf{p} in $\text{Col } A$. Explain why \mathbf{z} is in $(\text{Col } A)^\perp$. (The significance of this decomposition of \mathbf{y} will be explained in the next section.)

Section 6.3 : Orthogonal Projections

Chapter 6 : Orthogonality and Least Squares

Math 1554 Linear Algebra



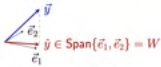
Vectors \vec{e}_1 and \vec{e}_2 form an orthonormal basis for subspace W .

Vector \vec{y} is not in W .

The orthogonal projection of \vec{y} onto $W = \text{Span}\{\vec{e}_1, \vec{e}_2\}$ is \hat{y} .

Section 6.3 : Orthogonal Projections

Chapter 6 : Orthogonality and Least Squares
Math 1554 Linear Algebra



Vectors \vec{e}_1 and \vec{e}_2 form an orthogonal basis for subspace W .
Vector \vec{y} is not in W .
The orthogonal projection of \vec{y} onto $W = \text{Span}\{\vec{e}_1, \vec{e}_2\}$ is \hat{y} .

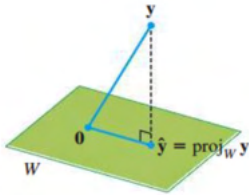


FIGURE 1

Topics and Objectives

Topics

1. Orthogonal projections and their basic properties
2. Best approximations

Learning Objectives

1. Apply concepts of orthogonality and projections to
 - a) compute orthogonal projections and distances,
 - b) express a vector as a linear combination of orthogonal vectors,
 - c) construct vector approximations using projections,
 - d) characterize bases for subspaces of \mathbb{R}^n , and
 - e) construct orthonormal bases.

Motivating Question For the matrix A and vector \vec{b} , which vector \vec{b} in column space of A , is closest to \vec{y} ?

$$A = \begin{bmatrix} 1 & 3 \\ 3 & 0 \\ -4 & -2 \end{bmatrix}, \quad \vec{b} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

9	3/4 - 3/8	5.3	WS5.3	5.5	WS5.5	6.1
10	3/11 - 3/15	6.1.6.2	WS6.1	6.2	WS6.2	6.3
11	3/18 - 3/22	Break	Break	Break	Break	Break
12	3/25 - 3/29	6.4	WS6.3	6.4, 6.5	WS6.4	6.5
13	4/1 - 4/5	6.6	WS5.5, 6.6	Exam 3, Review	Cancelled	PageRank

THEOREM 8

The Orthogonal Decomposition Theorem

Let W be a subspace of \mathbb{R}^n . Then each \vec{y} in \mathbb{R}^n can be written uniquely in the form

$$\vec{y} = \hat{y} + \vec{z} \quad (1)$$

where \hat{y} is in W and \vec{z} is in W^\perp . In fact, if $\{\vec{u}_1, \dots, \vec{u}_p\}$ is any orthogonal basis of W , then

$$\hat{y} = \frac{\vec{y} \cdot \vec{u}_1}{\vec{u}_1 \cdot \vec{u}_1} \vec{u}_1 + \dots + \frac{\vec{y} \cdot \vec{u}_p}{\vec{u}_p \cdot \vec{u}_p} \vec{u}_p \quad (2)$$

and $\vec{z} = \vec{y} - \hat{y}$.

$$\vec{y} = \begin{bmatrix} -1 \\ 4 \\ 3 \end{bmatrix}, \quad \vec{u}_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \quad \vec{u}_2 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$$

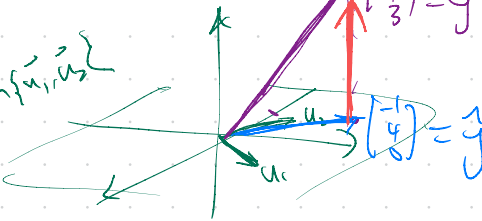
$$\begin{aligned} \hat{y} &= \text{proj}_{\{\vec{u}_1, \vec{u}_2\}}(\vec{y}) = \frac{\vec{y} \cdot \vec{u}_1}{\vec{u}_1 \cdot \vec{u}_1} \vec{u}_1 + \frac{\vec{y} \cdot \vec{u}_2}{\vec{u}_2 \cdot \vec{u}_2} \vec{u}_2 \\ &= \frac{-1+4}{1+1} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + \frac{1+4}{1+1} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \\ &= \frac{3}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + \frac{5}{2} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 \\ 4 \\ 0 \end{bmatrix} \end{aligned}$$

Q1: Find \hat{y}

Q2: write \vec{y} as $\hat{y} + \vec{z}$
 $\vec{y} = \hat{y} + \vec{z}$

where $\vec{z} \in W^\perp$

$W = \text{span}\{\vec{u}_1, \vec{u}_2\}$



$$\begin{aligned} \vec{z} &= \begin{bmatrix} -1 \\ 4 \\ 3 \end{bmatrix} - \begin{bmatrix} -1 \\ 4 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 3 \end{bmatrix} \\ &= \vec{y} - \hat{y} \end{aligned}$$



Example 1

Let u_1, \dots, u_5 be an orthonormal basis for \mathbb{R}^5 . Let $W = \text{Span}\{u_1, u_2\}$. For a vector $y \in \mathbb{R}^5$, write $y = \tilde{y} + w$, where $\tilde{y} \in W$ and $w \in W^\perp$.

Suppose

$y \in \mathbb{R}^5$ and $\{u_1, \dots, u_5\}$ orthogonal basis for \mathbb{R}^5 .

Orthogonal Decomposition Theorem

Theorem
Let W be a subspace of \mathbb{R}^n . Then, each vector $y \in \mathbb{R}^n$ has the unique decomposition $y = \tilde{y} + w$, $\tilde{y} \in W$, $w \in W^\perp$.
And, if u_1, \dots, u_n is any orthogonal basis for W , $\tilde{y} = \frac{y \cdot u_1}{u_1 \cdot u_1} u_1 + \dots + \frac{y \cdot u_n}{u_n \cdot u_n} u_n$.
We say that \tilde{y} is the orthogonal projection of y onto W .

$\dim W + \dim W^\perp = n$

If time permits, we will prove this theorem on the next slide.

From Ex 6.2 coordinates on orthogonal basis

opt 1.

$\tilde{y} = \frac{y \cdot u_1}{u_1 \cdot u_1} u_1 + \frac{y \cdot u_2}{u_2 \cdot u_2} u_2 + \frac{y \cdot u_3}{u_3 \cdot u_3} u_3 + \frac{y \cdot u_4}{u_4 \cdot u_4} u_4 + \frac{y \cdot u_5}{u_5 \cdot u_5} u_5$

$W = \text{span}\{u_1, u_2\}$ in W^\perp .

$\tilde{y} + w$

$(u_1, u_2, u_3, u_4, u_5)$

Why is the decomp. unique?
In general for any basis $\{u_1, \dots, u_5\}$ of \mathbb{R}^5 for any $y \in \mathbb{R}^5$
 $y = c_1 u_1 + c_2 u_2 + \dots + c_5 u_5$
① system is consistent
b/c $\text{span}\{u_1, \dots, u_5\} = \mathbb{R}^5$

② representation is unique
b/c $\{u_1, \dots, u_5\}$ are lin ind.

Proof (if time permits)

We can write $y = \tilde{y} + w$.
Then, $w = y - \tilde{y}$ is in W^\perp because

Uniqueness:

Example 2a

$y = \begin{pmatrix} -1 \\ 2 \\ 6 \end{pmatrix}$, $u_1 = \begin{pmatrix} 3 \\ -1 \\ 2 \end{pmatrix}$, $u_2 = \begin{pmatrix} 1 \\ -1 \\ -2 \end{pmatrix}$

Construct the decomposition $y = \tilde{y} + w$, where \tilde{y} is the orthogonal projection of y onto the subspace $W = \text{Span}\{u_1, u_2\}$.

must be an orthogonal basis for finding proj. to work!!

Step 1: Find $\tilde{y} = \text{proj}_{W} y$

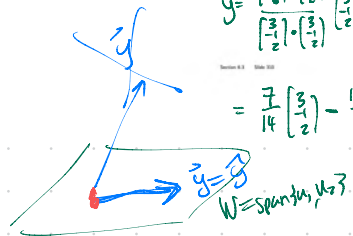
WARNING before doing this you MUST CHECK $u_1 \cdot u_2 = 0$

$\tilde{y} = \frac{\begin{bmatrix} -1 \\ 2 \\ 6 \end{bmatrix} \cdot \begin{bmatrix} 3 \\ -1 \\ 2 \end{bmatrix}}{\begin{bmatrix} 3 \\ -1 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} 3 \\ -1 \\ 2 \end{bmatrix}} \begin{bmatrix} 3 \\ -1 \\ 2 \end{bmatrix} + \frac{\begin{bmatrix} -1 \\ 2 \\ 6 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ -1 \\ -2 \end{bmatrix}}{\begin{bmatrix} 1 \\ -1 \\ -2 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ -1 \\ -2 \end{bmatrix}} \begin{bmatrix} 1 \\ -1 \\ -2 \end{bmatrix}$

$= \frac{7}{14} \begin{bmatrix} 3 \\ -1 \\ 2 \end{bmatrix} - \frac{15}{6} \begin{bmatrix} 1 \\ -1 \\ -2 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 3 \\ -1 \\ 2 \end{bmatrix} - \frac{5}{2} \begin{bmatrix} 1 \\ -1 \\ -2 \end{bmatrix}$

$= \frac{1}{2} \begin{bmatrix} 3 \\ -1 \\ 2 \end{bmatrix} - 5 \begin{bmatrix} 1 \\ -1 \\ -2 \end{bmatrix}$

$= \frac{1}{2} \begin{bmatrix} -7 \\ 9 \\ 12 \end{bmatrix} = \begin{bmatrix} -3.5 \\ 4.5 \\ 6 \end{bmatrix}$



Step 2: Find $w = y - \tilde{y} = \begin{bmatrix} -1 \\ 2 \\ 6 \end{bmatrix} - \begin{bmatrix} -3.5 \\ 4.5 \\ 6 \end{bmatrix} = \begin{bmatrix} 2.5 \\ -2.5 \\ 0 \end{bmatrix}$

Best Approximation Theorem

Theorem

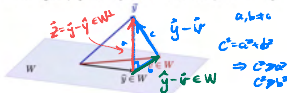
Let W be a subspace of \mathbb{R}^n , $\vec{y} \in \mathbb{R}^n$, and \vec{y}_0 is the orthogonal projection of \vec{y} onto W . Then for any $\vec{v} \in W$, we have

$$\|\vec{y} - \vec{y}_0\| < \|\vec{y} - \vec{v}\|$$

That is, \vec{y}_0 is the unique vector in W that is closest to \vec{y} .

Proof (if time permits)

The orthogonal projection of \vec{y} onto W is the closest point in W to \vec{y} .

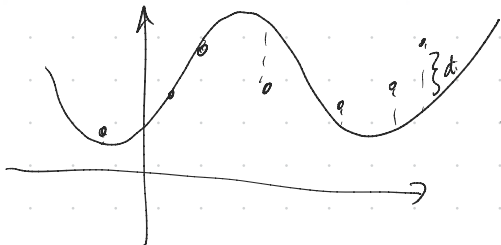


$$\|\vec{y} - \vec{v}\| \text{ or } \|\vec{y} - \vec{y}_0\|$$

which is bigger?

$\sum d_i^2$ small as possible.

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Example 2b

$$\vec{y} = \begin{pmatrix} -1 \\ 2 \\ 6 \end{pmatrix}, \vec{u}_1 = \begin{pmatrix} 3 \\ -1 \\ 2 \end{pmatrix}, \vec{u}_2 = \begin{pmatrix} 1 \\ -1 \\ -2 \end{pmatrix}$$

What is the distance between \vec{y} and subspace $W = \text{Span}\{\vec{u}_1, \vec{u}_2\}$? Note that these vectors are the same vectors that we used in Example 2a.

Additional Example (if time permits)

Indicate whether each statement is true or false. If true, explain why in one or two sentences. If false, give a counter example or explain why in one or two sentences.

- a) If \vec{x} is orthogonal to \vec{v} and \vec{w} , then \vec{x} is also orthogonal to $\vec{v} - \vec{w}$.
- b) If $\text{proj}_W \vec{y} = \vec{y}$, then $\vec{y} \in W$.
- c) If $\vec{y} = \vec{u}_1 + \vec{v}_1$, where $\vec{u}_1 \in W$ and $\vec{v}_1 \in W^\perp$, then \vec{u}_1 is the orthogonal projection of \vec{y} onto W .

List of accomplishments.

* orthogonality

* orthogonal basis, orthonormal basis

* orthogonal matrix

* properties of orthogonal matrix (oops & now)

* Orthogonal decomp.

* orthogonal projection

* least distance to W .

remaining

* G-S.

* least squares.

Section 6.3 Slide 33

Section 6.3 Slide 34

6.3 EXERCISES

In Exercises 1 and 2, you may assume that $\{u_1, \dots, u_4\}$ is an orthogonal basis for \mathbb{R}^4 .

$$1. u_1 = \begin{bmatrix} 0 \\ 1 \\ -4 \\ -1 \end{bmatrix}, u_2 = \begin{bmatrix} 3 \\ 5 \\ 1 \\ 1 \end{bmatrix}, u_3 = \begin{bmatrix} 1 \\ 0 \\ 1 \\ -4 \end{bmatrix}, u_4 = \begin{bmatrix} 5 \\ -3 \\ -1 \\ 1 \end{bmatrix}$$

$x = \begin{bmatrix} 10 \\ -8 \\ 2 \\ 0 \end{bmatrix}$. Write x as the sum of two vectors, one in

Span $\{u_1, u_2, u_3\}$ and the other in Span $\{u_4\}$.

$$2. u_1 = \begin{bmatrix} 1 \\ 2 \\ 1 \\ 1 \end{bmatrix}, u_2 = \begin{bmatrix} -2 \\ 1 \\ 1 \\ 1 \end{bmatrix}, u_3 = \begin{bmatrix} 1 \\ 1 \\ -2 \\ -1 \end{bmatrix}, u_4 = \begin{bmatrix} -1 \\ 1 \\ 1 \\ -2 \end{bmatrix}$$

$v = \begin{bmatrix} 4 \\ 5 \\ -3 \\ 3 \end{bmatrix}$. Write v as the sum of two vectors, one in

Span $\{u_1\}$ and the other in Span $\{u_2, u_3, u_4\}$.

In Exercises 3–6, verify that $\{u_1, u_2\}$ is an orthogonal set, and then find the orthogonal projection of y onto Span $\{u_1, u_2\}$.

$$3. y = \begin{bmatrix} -1 \\ 4 \\ 3 \end{bmatrix}, u_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, u_2 = \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$$

$$4. y = \begin{bmatrix} 6 \\ 3 \\ -2 \end{bmatrix}, u_1 = \begin{bmatrix} 3 \\ 4 \\ 0 \end{bmatrix}, u_2 = \begin{bmatrix} -4 \\ 3 \\ 0 \end{bmatrix}$$

$$5. y = \begin{bmatrix} -1 \\ 2 \\ 6 \end{bmatrix}, u_1 = \begin{bmatrix} 3 \\ -1 \\ 2 \end{bmatrix}, u_2 = \begin{bmatrix} 1 \\ -1 \\ -2 \end{bmatrix}$$

$$6. y = \begin{bmatrix} 6 \\ 4 \\ 1 \end{bmatrix}, u_1 = \begin{bmatrix} -4 \\ -1 \\ 1 \end{bmatrix}, u_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

In Exercises 7–10, let W be the subspace spanned by the u 's, and write y as the sum of a vector in W and a vector orthogonal to W .

$$7. y = \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix}, u_1 = \begin{bmatrix} 1 \\ 3 \\ -2 \end{bmatrix}, u_2 = \begin{bmatrix} 5 \\ 1 \\ 4 \end{bmatrix}$$

$$8. y = \begin{bmatrix} -1 \\ 4 \\ 3 \end{bmatrix}, u_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, u_2 = \begin{bmatrix} -1 \\ 3 \\ -2 \end{bmatrix}$$

$$9. y = \begin{bmatrix} 4 \\ 3 \\ 3 \\ -1 \end{bmatrix}, u_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 1 \end{bmatrix}, u_2 = \begin{bmatrix} -1 \\ 3 \\ 1 \\ -2 \end{bmatrix}, u_3 = \begin{bmatrix} -1 \\ 0 \\ 1 \\ 1 \end{bmatrix}$$

$$10. y = \begin{bmatrix} 3 \\ 4 \\ 5 \\ 6 \end{bmatrix}, u_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix}, u_2 = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix}, u_3 = \begin{bmatrix} 0 \\ -1 \\ 1 \\ -1 \end{bmatrix}$$

In Exercises 11 and 12, find the closest point to y in the subspace W spanned by v_1 and v_2 .

$$11. y = \begin{bmatrix} 3 \\ 1 \\ 5 \\ 1 \end{bmatrix}, v_1 = \begin{bmatrix} 3 \\ 1 \\ -1 \\ 1 \end{bmatrix}, v_2 = \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix}$$

$$12. y = \begin{bmatrix} 3 \\ -1 \\ 1 \\ 13 \end{bmatrix}, v_1 = \begin{bmatrix} 1 \\ -2 \\ -1 \\ 2 \end{bmatrix}, v_2 = \begin{bmatrix} -4 \\ 1 \\ 0 \\ 3 \end{bmatrix}$$

In Exercises 13 and 14, find the best approximation to z by vectors of the form $c_1v_1 + c_2v_2$.

$$13. z = \begin{bmatrix} 3 \\ -7 \\ 2 \\ 3 \end{bmatrix}, v_1 = \begin{bmatrix} 2 \\ -1 \\ -3 \\ 1 \end{bmatrix}, v_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ -1 \end{bmatrix}$$

$$14. z = \begin{bmatrix} 2 \\ 4 \\ 0 \\ -1 \end{bmatrix}, v_1 = \begin{bmatrix} 2 \\ 0 \\ -1 \\ -3 \end{bmatrix}, v_2 = \begin{bmatrix} 5 \\ -2 \\ 4 \\ 2 \end{bmatrix}$$

15. Let $y = \begin{bmatrix} 5 \\ -9 \\ 5 \end{bmatrix}, u_1 = \begin{bmatrix} -3 \\ -5 \\ 1 \end{bmatrix}, u_2 = \begin{bmatrix} -3 \\ 2 \\ 1 \end{bmatrix}$. Find the distance from y to the plane in \mathbb{R}^3 spanned by u_1 and u_2 .

16. Let $y, v_1,$ and v_2 be as in Exercise 12. Find the distance from y to the subspace of \mathbb{R}^4 spanned by v_1 and v_2 .

$$17. \text{ Let } y = \begin{bmatrix} 4 \\ 8 \\ 1 \end{bmatrix}, u_1 = \begin{bmatrix} 2/3 \\ 1/3 \\ 2/3 \end{bmatrix}, u_2 = \begin{bmatrix} -2/3 \\ 2/3 \\ 1/3 \end{bmatrix}, \text{ and } W = \text{Span}\{u_1, u_2\}.$$

a. Let $U = [u_1 \ u_2]$. Compute $U^T U$ and $U U^T$.

b. Compute $\text{proj}_W y$ and $(U U^T)y$.

$$18. \text{ Let } y = \begin{bmatrix} 7 \\ 9 \end{bmatrix}, u_1 = \begin{bmatrix} 1/\sqrt{10} \\ -3/\sqrt{10} \end{bmatrix}, \text{ and } W = \text{Span}\{u_1\}.$$

a. Let U be the 2×1 matrix whose only column is u_1 . Compute $U^T U$ and $U U^T$.

b. Compute $\text{proj}_W y$ and $(U U^T)y$.

$$19. \text{ Let } u_1 = \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix}, u_2 = \begin{bmatrix} -1 \\ -1 \\ 2 \end{bmatrix}, \text{ and } u_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}. \text{ Note that}$$

u_1 and u_2 are orthogonal but that u_3 is not orthogonal to u_1 or u_2 . It can be shown that u_3 is not in the subspace W spanned by u_1 and u_2 . Use this fact to construct a nonzero vector v in \mathbb{R}^3 that is orthogonal to u_1 and u_2 .

$$20. \text{ Let } u_1 \text{ and } u_2 \text{ be as in Exercise 19, and let } u_4 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}. \text{ It can}$$

be shown that u_4 is not in the subspace W spanned by u_1 and u_2 . Use this fact to construct a nonzero vector v in \mathbb{R}^3 that is orthogonal to u_1 and u_2 .

In Exercises 21 and 22, all vectors and subspaces are in \mathbb{R}^n . Mark each statement True or False. Justify each answer.

21. a. If z is orthogonal to u_1 and to u_2 and if $W = \text{Span}\{u_1, u_2\}$, then z must be in W^\perp .

b. For each y and each subspace W , the vector $y - \text{proj}_W y$ is orthogonal to W .

c. The orthogonal projection \hat{y} of y onto a subspace W can sometimes depend on the orthogonal basis for W used to compute \hat{y} .

d. If y is in a subspace W , then the orthogonal projection of y onto W is y itself.

e. If the columns of an $n \times p$ matrix U are orthonormal, then $U U^T y$ is the orthogonal projection of y onto the column space of U .

22. a. If W is a subspace of \mathbb{R}^n and if v is in both W and W^\perp , then v must be the zero vector.

b. In the Orthogonal Decomposition Theorem, each term in formula (2) for \hat{y} is itself an orthogonal projection of y onto a subspace of W .

c. If $y = z_1 + z_2$, where z_1 is in a subspace W and z_2 is in W^\perp , then z_1 must be the orthogonal projection of y onto W .

d. The best approximation to y by elements of a subspace W is given by the vector $y - \text{proj}_W y$.

e. If an $n \times p$ matrix U has orthonormal columns, then $U U^T x = x$ for all x in \mathbb{R}^n .

23. Let A be an $m \times n$ matrix. Prove that every vector x in \mathbb{R}^n can be written in the form $x = p + u$, where p is in Row A and u is in Nul A . Also, show that if the equation $Ax = b$ is consistent, then there is a unique p in Row A such that $Ap = b$.

24. Let W be a subspace of \mathbb{R}^n with an orthogonal basis $\{w_1, \dots, w_p\}$, and let $\{v_1, \dots, v_k\}$ be an orthogonal basis for W^\perp .

a. Explain why $\{w_1, \dots, w_p, v_1, \dots, v_k\}$ is an orthogonal set.

b. Explain why the set in part (a) spans \mathbb{R}^n .

c. Show that $\dim W + \dim W^\perp = n$.

25. [M] Let U be the 8×4 matrix in Exercise 36 in Section 6.2. Find the closest point to $y = (1, 1, 1, 1, 1, 1, 1, 1)$ in Col U . Write the keystrokes or commands you use to solve this problem.

26. [M] Let U be the matrix in Exercise 25. Find the distance from $b = (1, 1, 1, 1, -1, -1, -1, -1)$ to Col U .