

Main idea  $\frac{\partial}{\partial x}(x^2 y) = 2xy \checkmark$

### §14.3: Partial Derivatives

idea treat  
the other  
var like  
a constant

**Goal:** Describe how a function of two (or three, later) variables is changing at a point  $(a, b)$ .

**Example 47.** Let's go back to our example of the small hill that has height

$$h(x, y) = 4 - \frac{1}{4}x^2 - \frac{1}{4}y^2$$

meters at each point  $(x, y)$ . If we are standing on the hill at the point with  $(2, 1, 11/4)$ , and walk due north (the positive  $y$ -direction), at what rate will our height change? What if we walk due east (the positive  $x$ -direction)?

idea @  $(2, 1)$  how does  $y$ -change affect the height.  
@  $x=2$  Find  $\frac{d}{dy} h(2, y) = ?$  plug in  $y=1$ .

$$@ x=2 \quad h(2, y) = 4 - \frac{1}{4}(2)^2 - \frac{1}{4}y^2 = 3 - \frac{1}{4}y^2$$

$$\left. \frac{\partial h}{\partial y} \right|_{x=2} = \frac{d}{dy} \left( 3 - \frac{1}{4}y^2 \right) = -\frac{1}{2}y \quad \text{plug } y=1 \quad \left. \frac{\partial h}{\partial y} \right|_{(2,1)} = -\frac{1}{2}$$

@  $(2, 1)$  how does  $x$ -change affect the height?

$$@ y=1 \quad h(x, 1) = 4 - \frac{1}{4}x^2 - \frac{1}{4}(1)^2 = 3.75 - \frac{1}{4}x^2$$

$$\left. \frac{\partial h}{\partial x} \right|_{y=1} = \frac{d}{dx} \left( 3.75 - \frac{1}{4}x^2 \right) = -\frac{1}{2}x \quad @ x=2$$

$$\left. \frac{\partial h}{\partial x} \right|_{(2,1)} = -1$$

Let's investigate graphically.

**Definition 48.** If  $f$  is a function of two variables  $x$  and  $y$ , its

partial derivatives

are the functions  $f_x$  and  $f_y$  defined by

$$f_x(x, y) = \lim_{h \rightarrow 0} \frac{f(x+h, y) - f(x, y)}{h} \quad f_y(x, y) = \lim_{h \rightarrow 0} \frac{f(x, y+h) - f(x, y)}{h}$$

Notations:

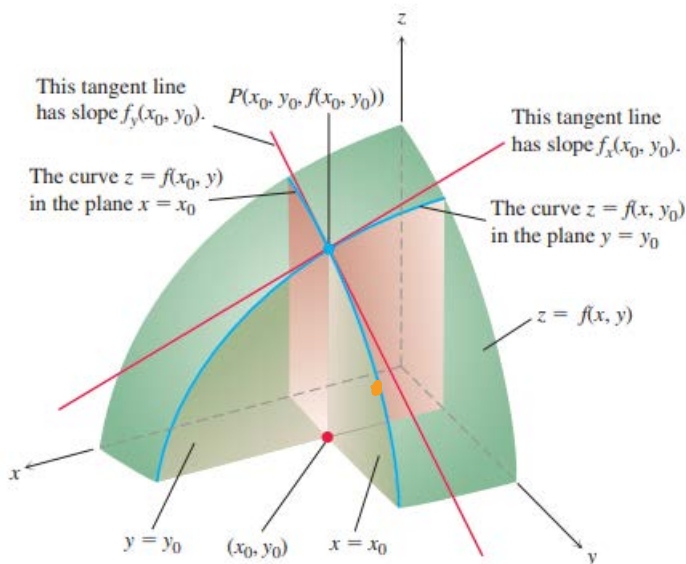
$$f_x = \frac{\partial}{\partial x} f = \frac{\partial f}{\partial x}$$

← The partial derivative of  $f$  w.r.t  $x$ .

$$f_y = \frac{\partial}{\partial y} f = \frac{\partial f}{\partial y}$$

↖ partial of  $f$  w.r.t  $y$ .

Interpretations:



**Example 49.** Find  $f_x(1, 2)$  and  $f_y(1, 2)$  of the functions below.

a)  $f(x, y) = \sqrt{5x - y}$

$$f_x = \frac{\partial}{\partial x} ((5x - y)^{1/2}) = \frac{1}{2} (5x - y)^{-1/2} * 5 = \frac{5}{2(5x - y)^{1/2}}$$

$$f_y = \frac{\partial}{\partial y} ((5x - y)^{1/2}) = \frac{1}{2} (5x - y)^{-1/2} * (-1) = \frac{-1}{2(5x - y)^{1/2}}$$

$$f_x(1, 2) = \frac{5}{2(5-2)^{1/2}} = \boxed{\frac{5}{2\sqrt{3}}}$$

$$f_y(1, 2) = \frac{-1}{2(5-2)^{1/2}} = \boxed{\frac{-1}{2\sqrt{3}}}$$

b)  $f(x, y) = \tan(xy)$

$$f_x = \sec^2(xy) * y$$

$$f_y = \sec^2(xy) * x$$

@ (2, 1)

$$f_x(2, 1) = \sec^2(2) * 1$$

$$f_y(2, 1) = \sec^2(2) * 2$$

**Question:** How would you define the second partial derivatives?

$$f_{xx} = \frac{\partial}{\partial x} f_x = \frac{\partial}{\partial x} \frac{\partial f}{\partial x} = \frac{\partial^2 f}{\partial x^2}$$

$$f_{xy} = \frac{\partial}{\partial y} f_x = \frac{\partial}{\partial y} \frac{\partial f}{\partial x} = \frac{\partial^2 f}{\partial y \partial x}$$

$$f_{yx} = \frac{\partial}{\partial x} f_y = \frac{\partial}{\partial x} \frac{\partial f}{\partial y} = \frac{\partial^2 f}{\partial x \partial y}$$

$$f_{yy} = \frac{\partial}{\partial y} f_y = \frac{\partial}{\partial y} \frac{\partial f}{\partial y} = \frac{\partial^2 f}{\partial y^2}$$

**Example 50.** Find  $f_{xx}$ ,  $f_{xy}$ ,  $f_{yx}$ , and  $f_{yy}$  of the function below.

a)  $f(x, y) = \sqrt{5x - y}$

$$f_x = \frac{5}{2\sqrt{5x-y}} \quad \checkmark$$

$$= \frac{5}{2}(5x-y)^{-1/2}$$

$$f_y = \frac{-1}{2\sqrt{5x-y}}$$

$$= -\frac{1}{2}(5x-y)^{-1/2}$$

$$f_{xx} = \frac{-5}{4}(5x-y)^{-3/2} * 5 = \frac{-25}{4(5x-y)^{3/2}}$$

← pure partials  
(double partial)

$$f_{xy} = \frac{-5}{4}(5x-y)^{-3/2} * (-1) = \frac{5}{4(5x-y)^{3/2}}$$

← mixed partials

$$f_{yx} = \frac{1}{4}(5x-y)^{-3/2} (5) = \frac{5}{4(5x-y)^{3/2}} \quad \checkmark$$

$$f_{yy} = \frac{1}{4}(5x-y)^{-3/2} (-1) = \frac{-1}{4(5x-y)^{3/2}}$$

What do you notice about  $f_{xy}$  and  $f_{yx}$  in the previous example?

*then* **Theorem 51** (Clairaut's Theorem). Suppose  $f$  is defined on a disk  $D$  that contains the point  $(a, b)$ . If the functions  $f, f_x, f_y, f_{xy}, f_{yx}$  are all continuous on  $D$ , then

$$f_{yx} = f_{xy}$$

Corollary  $f_{xyx} = f_{xxy} = f_{yxx}$

**Example 52.** *You try it!* What about functions of three variables? How many partial derivatives should  $f(x, y, z) = 2xyz - z^2y$  have? Compute them.

*1st order*

What do you notice about  $f_{xy}$  and  $f_{yx}$  in the previous example?

**Theorem 51** (Clairaut's Theorem). Suppose  $f$  is defined on a disk  $D$  that contains the point  $(a, b)$ . If the functions  $f, f_x, f_y, f_{xy}, f_{yx}$  are all continuous on  $D$ , then

$$f_{xy} = f_{yx}$$

corollary:  $f_{xyx} = f_{xxy} = f_{yxx}$  ~~same??~~  
 also  $f_{yxg} = f_{yxy} = f_{xyy}$  why?

**Example 52.** *You try it!* What about functions of three variables? How many partial derivatives should  $f(x, y, z) = 2xyz - z^2y$  have? Compute them.

$$f_x = 2yz - 0 = 2yz$$

$$f_y = 2xz - z^2$$

$$f_z = 2xy - 2zy$$

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^3$$



**Example 53.** How many rates of change should the function  $f(s, t) = \begin{bmatrix} s^2 + t \\ 2s - t \\ st \end{bmatrix}$

have? Compute them. Idem.  $f(s, t) = \langle x(s, t), y(s, t), z(s, t) \rangle$

For first component

$$\frac{\partial x}{\partial s} = \frac{\partial}{\partial s} x(s, t) = \frac{\partial}{\partial s} (s^2 + t) = 2s$$

$$\frac{\partial x}{\partial t} = \frac{\partial}{\partial t} (s^2 + t) = 1$$

$$x(s, t) = s^2 + t$$

$$y(s, t) = 2s - t$$

$$z(s, t) = st$$

$$Df = \begin{bmatrix} 2s & 1 \\ 2 & -1 \\ t & s \end{bmatrix}$$

For y-component

$$\frac{\partial y}{\partial s} = \frac{\partial}{\partial s} (2s - t) = 2$$

$$\frac{\partial y}{\partial t} = \frac{\partial}{\partial t} (2s - t) = -1$$

For z

$$\frac{\partial z}{\partial s} = \frac{\partial}{\partial s} (st) = t$$

$$\frac{\partial z}{\partial t} = \frac{\partial}{\partial t} (st) = s$$

So, we computed partial derivatives. How might we **organize** this information?

For any function  $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$  having the form  $f(x_1, \dots, x_n) = \begin{bmatrix} f_1(x_1, \dots, x_n) \\ \vdots \\ f_m(x_1, \dots, x_n) \end{bmatrix}$ ,

we have \_\_\_\_\_ inputs, \_\_\_\_\_ output, and \_\_\_\_\_ partial derivatives, which we can use to form the **total derivative**.

This is a \_\_\_\_\_ map from  $\mathbb{R}^n \rightarrow \mathbb{R}^m$ , denoted  $Df$ , and we can represent it with an \_\_\_\_\_, with one column per input and one row per output.

It has the formula  $Df_{ij} =$

**Example 54.** *You try it!* Find the total derivatives of each function:

a)  $f(x) = x^2 + 1$

b)  $\mathbf{r}(t) = \langle \cos(t), \sin(t), t \rangle$

c)  $f(x, y) = \sqrt{5x - y}$

d)  $f(x, y, z) = 2xyz - z^2y$

e)  $\mathbf{f}(s, t) = \langle s^2 + t, 2s - t, st \rangle$

**What does it mean?** In differential calculus, you learned that one interpretation of the derivative is as a slope. Another interpretation is that the derivative measures how a function transforms a neighborhood around a given point.

Check it out for yourself. (credit to samuel.gagnon.nepton, who was inspired by 3Blue1Brown.)



**Example 54.** *You try it!* Find the total derivatives of each function:

a)  $f(x) = x^2 + 1$

$f: \mathbb{R} \rightarrow \mathbb{R}$

$Df$  has size  $1 \times 1$

$[2x]$

b)  $\mathbf{r}(t) = \langle \cos(t), \sin(t), t \rangle$

$\mathbf{r}: \mathbb{R} \rightarrow \mathbb{R}^3$

$Df$  has size  $3 \times 1$

$r_1(t) = \cos t$

$r_2(t) = \sin t$

$r_3(t) = t$

$Df = \begin{bmatrix} r_1'(t) \\ r_2'(t) \\ r_3'(t) \end{bmatrix} = \begin{bmatrix} -\sin t \\ \cos t \\ 1 \end{bmatrix}$

c)  $f(x, y) = \sqrt{5x - y}$

$f: \mathbb{R}^2 \rightarrow \mathbb{R}$

$Df$  is  $1 \times 2$

$Df = [f_x \ f_y] = \left[ \frac{5}{2\sqrt{5x-y}} \quad \frac{-1}{2\sqrt{5x-y}} \right]$

d)  $f(x, y, z) = 2xyz - z^2y$

$f: \mathbb{R}^3 \rightarrow \mathbb{R}$

$Df$  is  $1 \times 3$

$Df = [f_x \ f_y \ f_z] = [2yz \quad 2xz - z^2 \quad 2xy - 2yz]$

e)  $\mathbf{f}(s, t) = \langle \overbrace{s^2}^x + \overbrace{t}^y, \overbrace{2s - t}^z, \overbrace{st}^z \rangle$

$\mathbf{f}: \mathbb{R}^2 \rightarrow \mathbb{R}^3$

$Df$  size  $3 \times 2$

$Df = \begin{bmatrix} x_s & x_t \\ y_s & y_t \\ z_s & z_t \end{bmatrix} = \begin{bmatrix} 2s & 1 \\ 2 & -1 \\ t & s \end{bmatrix}$

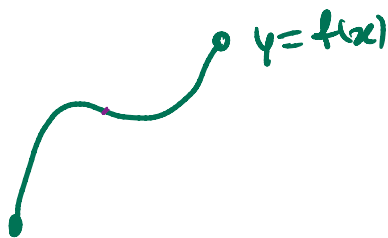
**What does it mean?** In differential calculus, you learned that one interpretation of the derivative is as a slope. Another interpretation is that the derivative measures how a function transforms a neighborhood around a given point.

Check it out for yourself. (credit to samuel.gagnon.nepton, who was inspired by 3Blue1Brown.)

In particular, the (total) derivative of **any** function  $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ , evaluated at  $\mathbf{a} = (a_1, \dots, a_n)$ , is the linear function that best approximates  $f(\mathbf{x}) - f(\mathbf{a})$  at  $\mathbf{a}$ .

This leads to the familiar linear approximation formula for functions of one variable:

$$f(x) \approx f(a) + f'(a)(x - a) = L(x)$$



**Definition 55.** The **linearization** or **linear approximation** of a differentiable function  $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$  at the point  $\mathbf{a} = (a_1, \dots, a_n)$  is



$$L(\mathbf{x}) =$$

**Example 56.** Find the linearization of the function  $f(x, y) = \sqrt{5x - y}$  at the point  $(1, 1)$ . Use it to approximate  $f(1.1, 1.1)$ .

**Question:** What do you notice about the equation of the linearization?

We say  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is **differentiable** at  $\mathbf{a}$  if its linearization is a good approximation of  $f$  near  $\mathbf{a}$ .

$$\lim_{(x,y) \rightarrow (a,b)} \frac{f(x,y) - L(x,y)}{\|(x,y) - (a,b)\|} = 0.$$

In particular, if  $f$  is a function  $f(x,y)$  of two variables, it is differentiable at  $(a,b)$  its graph has a unique tangent plane at  $(a,b, f(a,b))$ .

**Example 57.** Determine if  $f(x,y) = \begin{cases} 1 & xy = 0 \\ 0 & xy \neq 0 \end{cases}$  is differentiable at  $(0,0)$ .