

§13.1 Curves in Space & Their Tangents

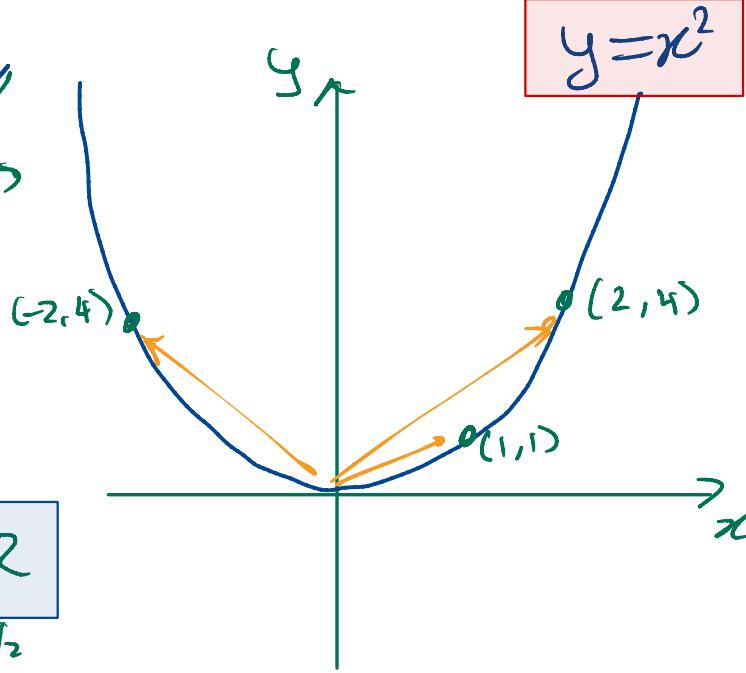
The description we gave of a line last week generalizes to produce other one-dimensional graphs in \mathbb{R}^2 and \mathbb{R}^3 as well. We said that a function $\mathbf{r} : \mathbb{R} \rightarrow \mathbb{R}^3$ with $\mathbf{r}(t) = \mathbf{v}t + \mathbf{r}_0$ produces a straight line when graphed.

This is an example of a **vector-valued function**: its input is a real number t and its output is a vector. We graph a vector-valued function by plotting all of the terminal points of its output vectors, placing their initial points at the origin.

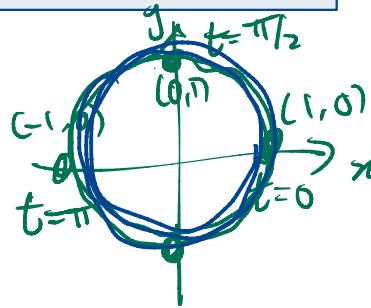
You have seen several examples already:

$$(1) \mathbf{r}(t) = \vec{OP} + t\vec{v}, t \in \mathbb{R}$$

(output is a vector)
but we think of it as
the points that are
pointed by the output
vectors.



$$(2) \mathbf{r}(t) = \langle \cos t, \sin t \rangle, t \in \mathbb{R}$$



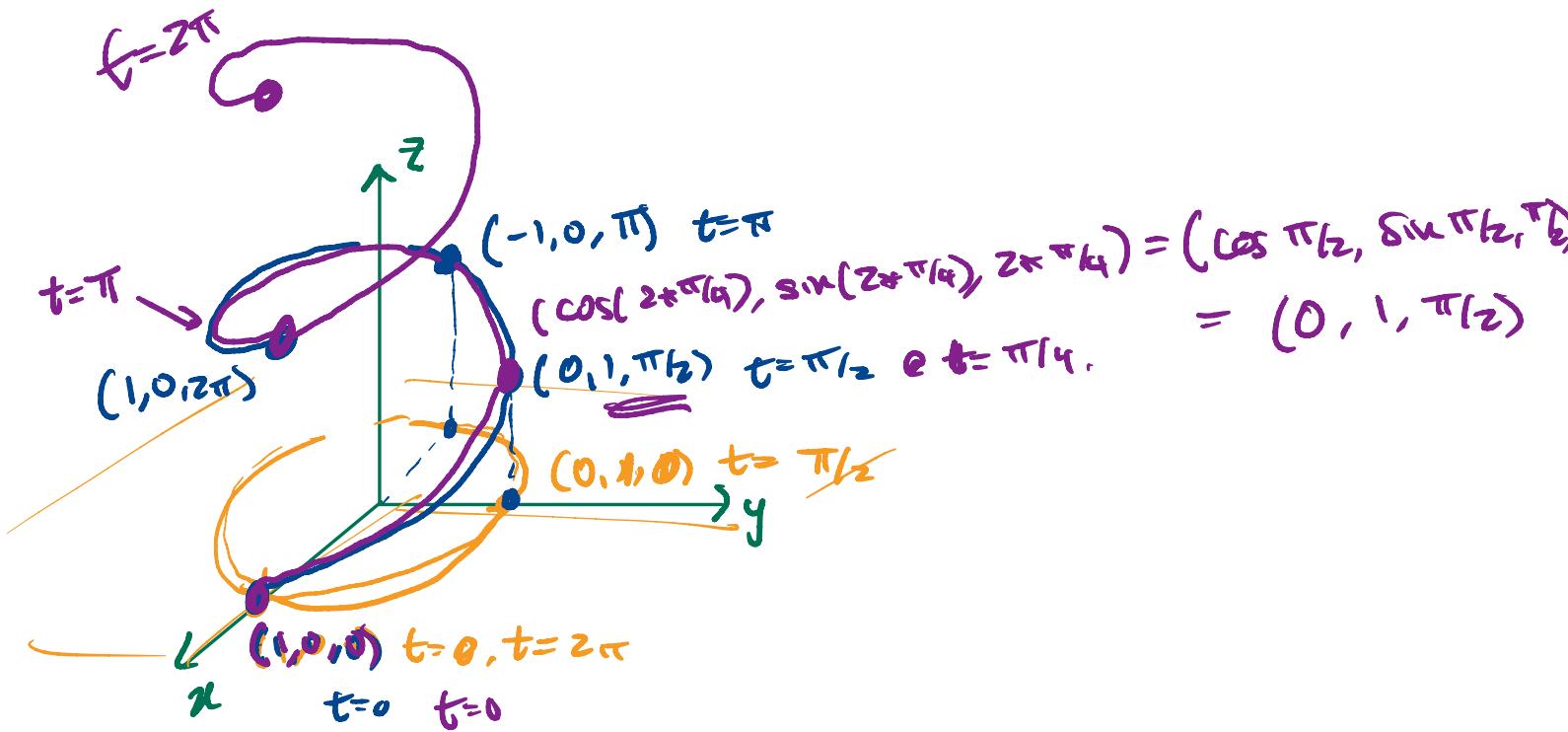
$$(3) \mathbf{r}(t) = \langle t, t^2 \rangle, t \in \mathbb{R}$$

Given a fixed curve C in space, producing a vector-valued function \mathbf{r} whose graph is C is called **parametrizing** the curve C , and \mathbf{r} is called a **parametrization** of C .
 "Parameter" aka variable.

$$\rightarrow \vec{r}_0(t) = \langle \cos t, \sin t, 0 \rangle$$

Replace t with $2t$.

Example 10. Consider $\mathbf{r}_1(t) = \langle \cos(t), \sin(t), t \rangle$ and $\mathbf{r}_2(t) = \langle \cos(2t), \sin(2t), 2t \rangle$, each with domain $[0, 2\pi]$. What do you think the graph of each looks like? How are they similar and how are they different?



Check your intuition

§13.2: Calculus of vector-valued functions

Unifying theme: Do what you already know, componentwise.

This works with limits: $\mathbf{r}(t) = \langle t^2, 2, \ln t \rangle, t > 0$ space curve.

Example 11. Compute $\lim_{t \rightarrow e} \langle t^2, 2, \ln(t) \rangle$. Near $t=e$ where is $\mathbf{r}(t)$?

$$= \langle \lim_{t \rightarrow e} t^2, \lim_{t \rightarrow e} 2, \lim_{t \rightarrow e} \ln t \rangle$$

$$= \langle e^2, 2, \ln e \rangle = \langle e^2, 2, 1 \rangle$$

↙ [A] credit p12
Simplicity.

And with continuity:

Example 12. Determine where the function $\mathbf{r}(t) = t\mathbf{i} - \frac{1}{t^2 - 4}\mathbf{j} + \sin(t)\mathbf{k}$ is continuous.

Since $\mathbf{r}(t) = \langle t, -\frac{1}{t^2-4}, \sin t \rangle$

Idea just figure out where each component is continuous. $\hat{\imath}$ must that t is in EACH region where EACH component is continuous.

Components:

$$x(t) = t$$

$x(t)$ & $z(t)$ are continuous everywhere

$$y(t) = -\frac{1}{t^2-4}$$

So need $y(t)$ to be continuous.

$$z(t) = \sin t$$

domain of $y(t) = -\frac{1}{t^2-4}$ is

$$(-\infty, -2) \cup (-2, 2) \cup (2, \infty)$$

And with derivatives:

Example 13. If $\mathbf{r}(t) = \langle 2t - \frac{1}{2}t^2 + 1, t - 1 \rangle$, find $\mathbf{r}'(t)$.

$$\begin{aligned} x(t) &= 2t - \frac{1}{2}t^2 + 1 & \text{so } x'(t) &= 2 - t \\ y(t) &= t - 1 & y'(t) &= 1 & \mathbf{r}'(t) \end{aligned}$$

so $\mathbf{r}'(t) = \langle x'(t), y'(t) \rangle = \langle 2 - t, 1 \rangle$

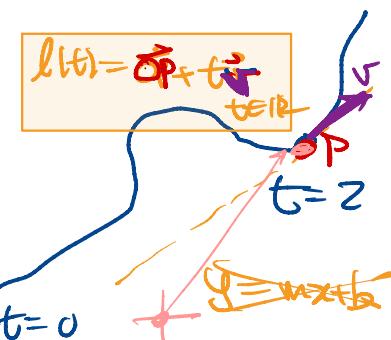
Sanity Check what is $\mathbf{r}(0) = \langle 2, 1 \rangle$
 $\mathbf{r}(1) = \langle 1, 1 \rangle$

what do they mean?
 "velocity"

Interpretation: If $\mathbf{r}(t)$ gives the position of an object at time t , then

- $\mathbf{r}'(t)$ gives velocity vector at time t (direction & magnitude)
- $|\mathbf{r}'(t)|$ gives speed at time t
- $\mathbf{r}''(t)$ gives acceleration at time t

Let's see this graphically



Example 14. Find an equation of the tangent line to $\mathbf{r}(t) = \langle 2t - \frac{1}{2}t^2 + 1, t - 1 \rangle$ at time $t = 2$.

$t=2$

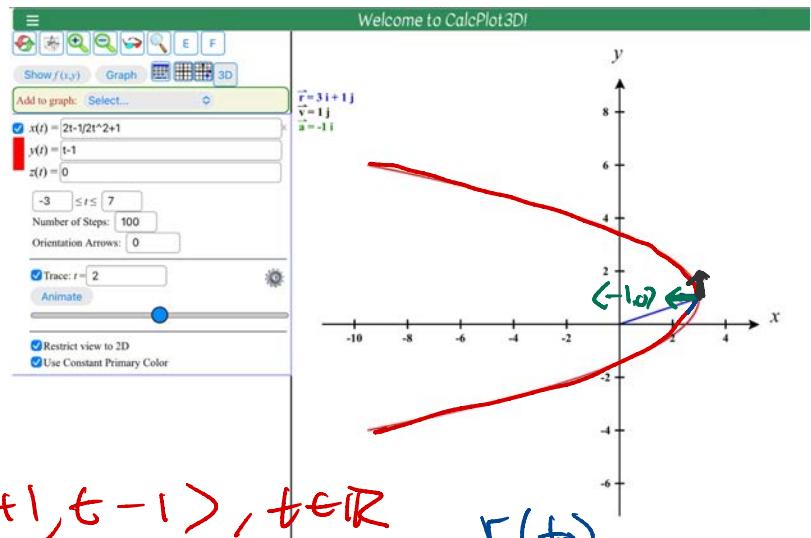
$$\begin{aligned} \vec{OP} &= \mathbf{r}(2) = \langle 2(2) - \frac{1}{2}(2)^2 + 1, 2 - 1 \rangle = \langle 3, 1 \rangle \\ \vec{V} &= \mathbf{r}'(2) = \langle 2 - 2, 1 \rangle = \langle 0, 1 \rangle \end{aligned}$$

so $\mathbf{l}(t) = \vec{OP} + t\vec{V}$ becomes

$$\mathbf{l}(t) = \langle 3, 1 \rangle + t \langle 0, 1 \rangle, \quad t \in \mathbb{R}$$

Curious $\mathbf{r}''(t) = \langle -1, 0 \rangle$ for all t .

Example 14. (cont.) Find an equation of the tangent line to $\mathbf{r}(t) = \langle 2t - \frac{1}{2}t^2 + 1, t - 1 \rangle$ at time $t = 2$.



$$\mathbf{r}(t) = \langle 2t - \frac{1}{2}t^2 + 1, t - 1 \rangle, t \in \mathbb{R} \quad \mathbf{r}(t_0)$$

$$\text{so } \mathbf{r}'(t) = \langle x'(t), y'(t) \rangle = \langle 2 - t, 1 \rangle$$

$$\mathbf{r}''(t) = \langle -1, 0 \rangle \quad \text{for all } t.$$

$$\mathbf{d}(t) = \langle 3, 1 \rangle + t \langle 0, 1 \rangle, t \in \mathbb{R}$$

And with integrals:

$\mathbf{r}(t) = \langle t, e^{2t}, \sec^2(t) \rangle$ space curve in \mathbb{R}^3
(vs. plane curve)

Example 15. Find $\int_0^1 \langle t, e^{2t}, \sec^2(t) \rangle dt$.

↙ [N] credit in \mathbb{R}^2

$$= \left\langle \int_0^1 t dt, \int_0^1 e^{2t} dt, \int_0^1 \sec^2 t dt \right\rangle$$

$$= \left\langle \frac{1}{2}t^2, \frac{1}{2}e^{2t}, \tan t \right\rangle \Big|_0^1$$

$$= \left\langle \frac{1}{2}, \frac{1}{2}e^2, \tan(1) \right\rangle - \left\langle 0, \frac{1}{2}, \tan(0) \right\rangle$$

$$= \boxed{\left\langle \frac{1}{2}, \frac{1}{2}e^2 - \frac{1}{2}, \tan(1) \right\rangle} \quad \leftarrow \text{simplify for [A]-credit.}$$

At this point we can solve initial-value problems like those we did in single-variable calculus:

Example 16. Wallace is testing a rocket to fly to the moon, but he forgot to include instruments to record his position during the flight. He knows that his velocity during the flight was given by



$$\mathbf{v}(t) = \langle -200 \sin(2t), 200 \cos(t), 400 - \frac{400}{1+t} \rangle \text{ m/s.}$$

If he also knows that he started at the point $\mathbf{r}(0) = \langle 0, 0, 0 \rangle$, use calculus to reconstruct his flight path.

initial value problem

Idea: Given $\mathbf{r}'(t) = \mathbf{v}(t)$ & initial value $\mathbf{r}(0)$, reconstruct $\mathbf{r}(t)$. [IVP]

$$\mathbf{r}(t) = \int \mathbf{v}(t) dt = \int \langle -200 \sin 2t, 200 \cos t, 400 - \frac{400}{1+t} \rangle dt$$

$$= \left\langle +\frac{100}{2} \cos 2t + C_1, 200 \sin t + C_2, 400t - 400 \ln(1+t) + C_3 \right\rangle$$

To get C_1, C_2, C_3 figured out we use $\mathbf{r}(0) = \langle 0, 0, 0 \rangle$ the initial value

$$\begin{aligned} \text{So } \mathbf{r}(0) &= \langle 0, 0, 0 \rangle = \langle 100 \cos(0) + C_1, 200 \sin(0) + C_2, 400(0) - 400 \ln(1+1) + C_3 \rangle \\ &= \langle 100 + C_1, C_2, C_3 \rangle = \langle 0, 0, 0 \rangle \quad \text{So } C_1 = -100, C_2 = C_3 = 0 \end{aligned}$$

$$\boxed{\mathbf{r}(t) = \langle 100 \cos 2t - 100, 200 \sin t, -400t - 400 \ln(1+t) \rangle \text{ for } [0, \infty)}$$

From §13.2 workbooks on Sal's website

You try it!

#7. Suppose $r(t) = \langle te^{t^2}, e^{-t}, 1 \rangle$. Integrate $\int_0^1 r(t) dt$

#13. Solve the IVP $\frac{d\vec{r}}{dt} = \langle (t+1)^{1/2}, e^{-t}, \frac{1}{t+1} \rangle$ $r(0) = \langle 0, 0, 1 \rangle$
(initial value problem)

§13.3 Arc length of curves

We have discussed motion in space using by equations like $\mathbf{r}(t) = \langle x(t), y(t), z(t) \rangle$.

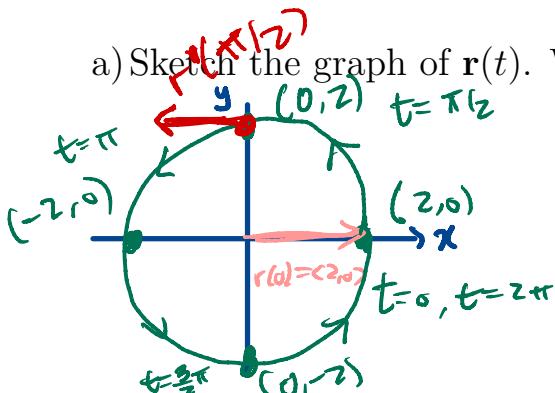
Our next goal is to be able to measure distance traveled or arc length.

Motivating problem: Suppose the position of a fly at time t is

$$\mathbf{r}(t) = \langle 2 \cos(t), 2 \sin(t) \rangle,$$

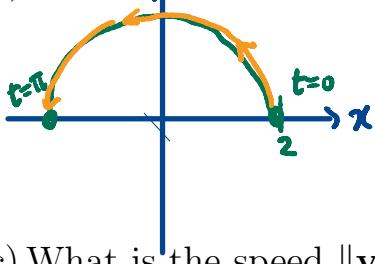
where $0 \leq t \leq 2\pi$.

a) Sketch the graph of $\mathbf{r}(t)$. What shape is this?



circle, centered @ (0,0)
w/ radius 2

b) How far does the fly travel between $t = 0$ and $t = \pi$?



$$C = 2\pi r \text{ if } r=2$$

$$C = 4\pi \text{ half circle so total distance is } 2\pi.$$

c) What is the speed $\|\mathbf{v}(t)\|$ of the fly at time t ?

(velocity) $\mathbf{v} = \mathbf{r}'(t) = \langle -2 \sin t, 2 \cos t \rangle$

$\|\mathbf{v}\| = \sqrt{4 \sin^2 t + 4 \cos^2 t} = \sqrt{4(\sin^2 t + \cos^2 t)} = \sqrt{4} = 2$

(speed) $\|\mathbf{v}(t)\| dt$

d) Compute the integral $\int_0^\pi \|\mathbf{v}(t)\| dt$. What do you notice?

(doesn't depend on t)

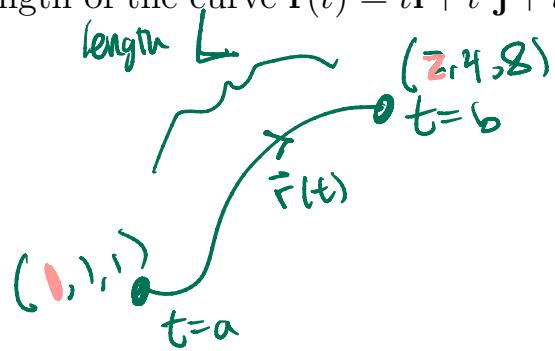
$$\int_0^\pi 2 dt = 2t \Big|_0^\pi = 2\pi - 0 = 2\pi$$

integrate speed to get distance travelled.

Definition 17. We say that the **arc length** of a smooth curve $\mathbf{r}(t) = \langle x(t), y(t), z(t) \rangle$ from $t=a$ to $t=b$ that is traced out exactly once is

$$L = \int_a^b \|\mathbf{r}'(t)\| dt$$

Example 18. Set up an integral for the arc length of the curve $\mathbf{r}(t) = t\mathbf{i} + t^2\mathbf{j} + t^3\mathbf{k}$ from the point $(1, 1, 1)$ to the point $(2, 4, 8)$.



$$L = \int_a^b \|\mathbf{r}'(t)\| dt$$

$$\mathbf{r}(t) = \langle t, t^2, t^3 \rangle$$

$$\therefore \mathbf{r}'(t) = \langle 1, 2t, 3t^2 \rangle \quad \text{how about } a? b?$$

$$(a=1)$$

$$\begin{aligned} \text{Want } \mathbf{r}(a) &= \langle 1, 1, 1 \rangle \\ &= \langle a, a^2, a^3 \rangle \end{aligned}$$

So

$$L = \int_1^2 \|\langle 1, 2t, 3t^2 \rangle\| dt$$

$$\begin{aligned} \mathbf{r}(b) &= \langle 2, 4, 8 \rangle \quad (b=2) \\ &= \langle b, b^2, b^3 \rangle \end{aligned}$$

$$= \int_1^2 \sqrt{1^2 + (2t)^2 + (3t^2)^2} dt$$

$$= \boxed{\int_1^2 \sqrt{1 + 4t^2 + 9t^4} dt}$$

===== ??

Example 19. *You try it!* Find the length of the portion of the curve in \mathbb{R}^3 given by the parametrization $\mathbf{r}(t) = \langle 6 \sin(2t), 6 \cos(2t), 5t \rangle$, $0 \leq t \leq 2\pi$.

Example 20. *You try it!* Find the length of the portion of the curve in \mathbb{R}^3 given by the parametrization $\mathbf{r}(t) = t\mathbf{i} + \frac{2}{3}t^{3/2}\mathbf{k}$, $0 \leq t \leq 8$.

Example 19. *You try it!* Find the length of the portion of the curve in \mathbb{R}^3 given by the parametrization $\mathbf{r}(t) = \langle 6 \sin(2t), 6 \cos(2t), 5t \rangle$, $0 \leq t \leq 2\pi$.

$$\vec{v}(t) = \frac{d\vec{r}}{dt} = \langle 12 \cos 2t, -12 \sin 2t, 5 \rangle$$

$$\Rightarrow |\vec{v}(t)|^2 = 144(\cos^2 2t + \sin^2 2t) + 25 = 169$$

$$\Rightarrow |\vec{v}(t)| = 13$$

So,

$$L = \int_0^{2\pi} |\vec{v}(t)| dt = \int_0^{2\pi} 13 dt = 13t \Big|_0^{2\pi} = 26\pi$$

Example 20. *You try it!* Find the length of the portion of the curve in \mathbb{R}^3 given by the parametrization $\mathbf{r}(t) = t\mathbf{i} + \frac{2}{3}t^{3/2}\mathbf{k}$, $0 \leq t \leq 8$.

Example 20. *You try it!* Find the length of the portion of the curve in \mathbb{R}^3 given by the parametrization $\mathbf{r}(t) = t\mathbf{i} + \frac{2}{3}t^{3/2}\mathbf{k}$, $0 \leq t \leq 8$.

$$L = \int_a^b \|\vec{v}(t)\| dt$$

$$\vec{v}(t) = \vec{r}'(t) = 1\mathbf{i} + \frac{2}{3}\frac{3}{2}t^{1/2}\mathbf{k}$$

$$\text{so } \|\vec{v}(t)\| = \sqrt{1^2 + (t^{1/2})^2} = \sqrt{1+t}$$

$$\begin{aligned} x(t) &= t & a &= 0 \\ y(t) &= 0 & b &= 8 \\ z(t) &= \frac{2}{3}t^{3/2} \end{aligned}$$

and

$$L = \int_0^8 \sqrt{1+t} dt$$

u-sub Box

$$\begin{aligned} u &= 1+t \\ du &= dt \end{aligned}$$

$$\begin{aligned} t=0 &\Rightarrow u=1 \\ t=8 &\Rightarrow u=9 \end{aligned}$$

$$= \int_1^9 \sqrt{u} du = \frac{2}{3}u^{3/2} \Big|_1^9$$

$$= \frac{2}{3}9^{3/2} - \frac{2}{3}1^{3/2}$$

$$= \frac{2}{3}27 - \frac{2}{3} = \frac{2}{3}26 = \boxed{\frac{52}{3}}$$

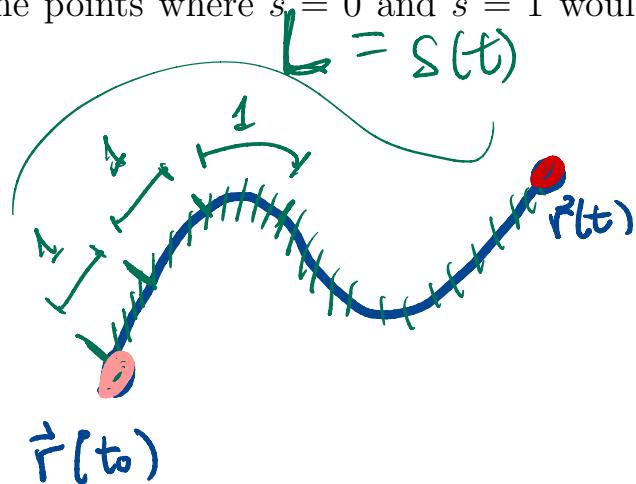
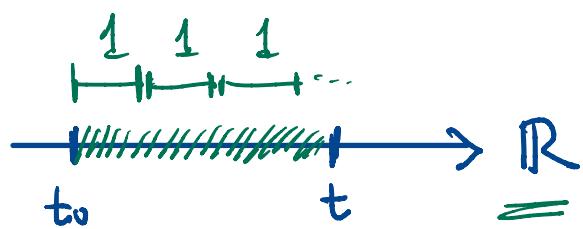
$$\int x \, dx = x^2 + C \quad \int y \, dy = y^2 + C$$

Arc length parametrization

Sometimes, we care about the distance traveled from a fixed starting time t_0 to an arbitrary time t , which is given by the **arc length function**.

$$s(t) = \int_{t_0}^t \|\vec{v}(\tau)\| \, d\tau$$

We can use this function to produce parameterizations of curves where the parameter s measures distance along the curve: the points where $s = 0$ and $s = 1$ would be exactly 1 unit of distance apart.



Idea: why should we be measuring out units in the parameter space \mathbb{R} ?

More natural to measure units in the codomain of $\vec{r}(t)$, $\vec{r}: \mathbb{R} \rightarrow \mathbb{R}^n$.

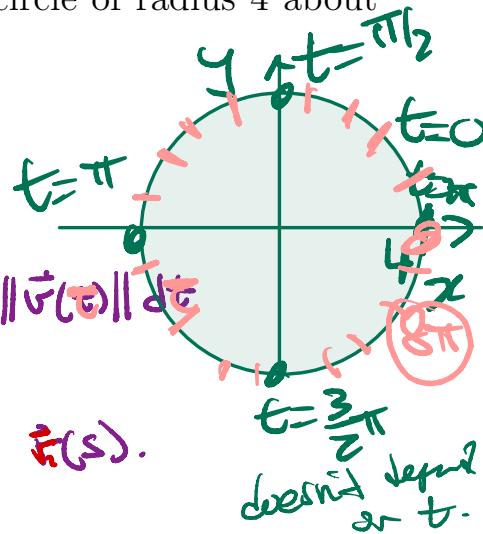
FACT. IF $\vec{r}_2(s)$ is an arc-length parametrization of C , then $\|\vec{r}_2'(s)\| = 1$ for all s .
(constant speed of 1)

Example 21. Find an arc length parameterization of the circle of radius 4 about the origin in \mathbb{R}^2 , $\mathbf{r}(t) = \langle 4 \cos(t), 4 \sin(t) \rangle$, $0 \leq t \leq 2\pi$.

$$\stackrel{=}{t_0=0}$$

META

- ① Compute arc length function $S(t) = \int_{t_0}^t \|\vec{r}'(\tau)\| d\tau$
- ② Solve $S = S(t)$ for $t = f(s)$
- ③ Substitute back into $\vec{r}(t)$ to obtain $\vec{r}(s)$.
doesn't depend on t .



- ① Note: $\mathbf{r}'(t) = \langle -4 \sin t, 4 \cos t \rangle$

$$\Rightarrow \|\mathbf{r}'(t)\| = \sqrt{16 \sin^2 t + 16 \cos^2 t} = \sqrt{16} = 4$$

$$\text{Find } S(t) = \int_0^t \|\mathbf{r}'(\tau)\| d\tau = \int_0^t 4 d\tau$$

$$\Rightarrow S(t) = 4\tau \Big|_0^t = 4t - 0 \Rightarrow S(t) = 4t$$

- ② Solve $S = 4t$ for t , $t = S/4$.

- ③ Substitute into $\vec{r}(t)$ to get $\vec{r}_2(s)$

Sub where $\vec{r}_2(s) = \vec{r}(s/4)$ $0 \leq t \leq 2\pi$ $t = s/4$

$t = s/4$

so $\mathbf{r}(t) = \mathbf{r}(s/4) = \langle 4 \cos(s/4), 4 \sin(s/4) \rangle = \vec{r}_2(s)$

$0 \leq s \leq 8\pi$

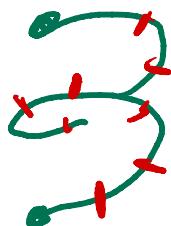
Example 22. *You try it!* Find (a) an arc length parameterization $s(t)$ of the curve \mathcal{C} , the portion of the helix of radius 4 in \mathbb{R}^3 parameterized by $\mathbf{r}(t) = \langle 4\cos(t), 4\sin(t), 3t \rangle$, $0 \leq t \leq \pi/2$, and (b) use $s(t)$ to find L the length of \mathcal{C}

$\mathbf{r}_2(s)$ arc-length parameterization.

(a) Find $\mathbf{r}_2(s)$

META

- ① Compute arc length function $S(t) = \int_{t_0}^t \|\mathbf{r}'(\tau)\| d\tau$
- ② Solve $S = S(t)$ for $t = f(s)$
- ③ Substitute back into $\mathbf{r}(t)$ to obtain $\mathbf{r}(s)$.



① $\mathbf{r}'(t) = \langle -4\sin t, 4\cos t, 3 \rangle$

$$\|\mathbf{r}'(t)\| = \sqrt{16\sin^2 t + 16\cos^2 t + 9} = \sqrt{16+9} = \sqrt{25} = 5$$

$$\underline{S(t)} = \int_0^t \|\mathbf{r}'(\tau)\| d\tau = \int_0^t 5 d\tau = 5\tau \Big|_0^t = 5t \quad \begin{matrix} t = 5t - 0 \\ = st \end{matrix}$$

$S = 5t$

So $t = s/5$ and $\mathbf{r}_2(s) = \langle 4\cos(s/5), 4\sin(s/5), 3s/5 \rangle$

$0 \leq s \leq 5\pi/2$

what $s = ?$
when $t = \pi/2$
using $t = s/5$

(b) Need to compute.

$$L = \int_0^{5\pi/2} \|\mathbf{r}'_2(s)\| ds$$

$$= \int_0^{5\pi/2} 1 ds = s \Big|_0^{5\pi/2} = \boxed{5\pi/2}$$

$$\mathbf{r}'_2(s) = \langle -\frac{4}{5}\sin(s/5), \frac{4}{5}\cos(s/5), \frac{3}{5} \rangle$$

$$\begin{aligned} \|\mathbf{r}'_2(s)\| &= \sqrt{\frac{16}{25}\sin^2(s/5) + \frac{16}{25}\cos^2(s/5) + \frac{9}{25}} \\ &= \sqrt{\frac{16}{25} + \frac{9}{25}} = \sqrt{25/25} = \boxed{1} \end{aligned}$$

Example 22. *You try it!* (a) Find an arc length parameterization of the portion of the helix of radius 4 in \mathbb{R}^3 parametrized by $\mathbf{r}(t) = \langle 4 \cos(t), 4 \sin(t), 3t \rangle$, $0 \leq t \leq \pi/2$.

(b) Use $s(t)$ to find L the length of \mathcal{C} .

① Find $s(t)$:

$$\hat{\mathbf{r}} = \frac{d\mathbf{r}}{dt} = \langle -4 \sin t, 4 \cos t, 3 \rangle$$

$$|\hat{\mathbf{r}}|^2 = 16 + 9 = 25$$

$$\text{so } |\hat{\mathbf{r}}| = 5$$

So,

$$s(t) = \int_0^t |\hat{\mathbf{r}}(\tau)| d\tau = \int_0^t 5 d\tau = 5\tau \Big|_0^t$$

$$\text{and } s = 5t \quad //$$

② Solve for t :

$$s = s(t) = 5t \quad \text{so} \quad t = f(s) = s/5$$

Sub into $\hat{\mathbf{r}}$: $\hat{\mathbf{r}}_2(s) = \mathbf{r}(f(s))$

$$\boxed{\hat{\mathbf{r}}_2(s) = \langle -4 \sin(s/5), 4 \cos(s/5), 3 \rangle, \quad 0 \leq s \leq 5\pi/2}$$

$$\begin{cases} t=0 \\ t=\pi/2 \end{cases} \Rightarrow \begin{cases} s=0 \\ s=5\pi/2 \end{cases}$$

$$(b) L = \int_0^{\pi/2} |\hat{\mathbf{r}}| d\tau = s \Big|_{t=0}^{t=\pi/2} = \boxed{\frac{5}{2}\pi}$$

