§14.3

- Safety-Quiz

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 $\frac{\partial}{\partial x}(\chi y^2) = y^2$ MAIN IDEA

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§14.3: Partial Derivatives $\frac{\partial}{\partial y} (\chi_y^2) = 2\chi_y^2$

Goal: Describe how a function of two (or three, later) variables is changing a point (a, b).

Example 47. Let's go back to our example of the small hill that has height

$$h(x,y) = 4 - \frac{1}{4}x^2 - \frac{1}{4}y^2$$

meters at each point (x, y). If we are standing on the hill at the point with (2, 1, 11/4), and walk due north (the positive *y*-direction), at what rate will our height change? What if we walk due east (the positive *x*-direction)?

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Definition 48. If f is a function of two variables x and y, its are the functions f_x and f_y defined by

$$f_{x}(x,y) = \lim_{h \to 0} \frac{f(x,h,q) - f(x,y)}{h} \qquad f_{y}(x,y) = \lim_{h \to 0} \frac{f(x,y+h) - f(x,q)}{h}$$
Notations:
$$f_{x} = \frac{\partial}{\partial x}f = \frac{\partial f}{\partial x} \qquad \text{partial derivative of } f$$

$$f_{y} = \frac{\partial}{\partial y}f = \frac{\partial f}{\partial y} \qquad \text{m for } x - doreton$$

$$M = \int_{M} \int$$

Interpretations:



Example 49. Find $f_x(1,2)$ and $f_y(1,2)$ of the functions below.

a)
$$f(x, y) = \sqrt{5x - y}$$

 $f_{\chi} = \frac{3}{5\pi} f(x, y) = \frac{1}{2\sqrt{5x - y}} + 5 = \frac{5}{2\sqrt{5x - y}}$
 $at (x, y) = (1, z)$ get $f_{\chi}(1, 2) = \frac{5}{2\sqrt{5x - y}}$
 $f_{\chi} = \frac{3}{3\sqrt{y}} f(x, y) = \frac{1}{2\sqrt{5x - y}} + (-1) = \frac{-1}{2\sqrt{5x - y}}$
 $e(1, z) \quad f_{\chi}(1, z) = \frac{-1}{2\sqrt{5x - y}} = \frac{-1}{2\sqrt{2}}$
b) $f(x, y) = \tan(xy)$
 $f_{\chi} = \sec^{2}(xy) + y$
 $f_{\chi} = \sec^{2}(xy) + \chi$
 $e(2, 1)$
 $f_{\chi}(z, 1) = 4 \sec^{2}(z)$
 $f_{\chi}(z, 1) = 2 \sec^{2}(z)$

Question: How would you define the second partial derivatives?

$$f_{XX} = \frac{1}{2x} f_X = \frac{1}{2x} \frac{1}{2x} \frac{1}{2x} = \frac{1}{2x} \frac{1}{2x} \frac{1}{2x} \frac{1}{2x} = \frac{1}{2x} \frac{1}$$

What do you notice about f_{xy} and f_{yx} in the previous example?

Theorem 51 (Clairaut's Theorem). Suppose f is defined on a disk D that contains the point (a, b). If the functions $f, f_x, f_y, f_{xy}, f_{yx}$ are all continuous on D, then

Example 52. You try it! What about functions of three variables? How many partial derivatives should $f(x, y, z) = 2xyz - z^2y$ have? Compute them.

$$f_{x} = 2y_{z} - 0 = 2y_{z}$$

 $f_{y} = 2x_{z} - z^{2}$
 $f_{z} = 2x_{y} - 2z_{y}$



So, we computed partial derivatives. How might we **organize** this information?

For any function $f : \mathbb{R}^n \to \mathbb{R}^m$ having the form $f(x_1, \dots, x_n) = \begin{bmatrix} f_1(x_1, \dots, x_n) \\ \vdots \\ f_m(x_1, \dots, x_n) \end{bmatrix}$

we have $\underline{\mathcal{N}}$ inputs, $\underline{\mathcal{M}}$ output, and $\underline{\mathcal{M} \times \mathcal{N}}$ partial derivatives, which we can use to form the **total derivative**.

This is a <u>map</u> map from $\mathbb{R}^n \to \mathbb{R}^m$, denoted Df, and we can represent it with an **man**, with one column per input and one row per output.

It has the formula $Df_{ij} = \frac{1}{2} f_i(\mathbf{x}_1, \dots, \mathbf{x}_n)$ $I \leq j \leq n \quad (n = \# \alpha_1 r)$ $I \leq i \leq m \quad (m = \# rows)$

Example 54. You try it! Find the total derivatives of each function:

a) $f(x) = x^2 + 1$ Zz 1:R-JR Df has size 1x1 $Df = \begin{vmatrix} r_i(t) \\ r_i$ b) $\mathbf{r}(t) = \langle \cos(t), \sin(t), t \rangle$ [(t) = cost $F_2(t) = sint$ r:RJR3 ら(と)=セ Df has size 3x1 c) $f(x, y) = \sqrt{5x - y}$ $Df = [f_x f_y] = \begin{bmatrix} 5 \\ 255x - y \\ 255x - y \end{bmatrix}$ f: IRZ > IR Dt 16 1x2 d) $f(x, y, z) = 2xyz - z^2y$ $Df = [f_x f_y f_z] = [2yz 2xz - z^2 2xy - 2yz]$ F:R3-R Dt is 1x3 e) $\mathbf{f}(s,t) = \langle s^2 + t, 2s - t, st \rangle$ $Df = \begin{cases} \chi_s & \chi_t \\ \gamma_s & \gamma_t \\ \chi_s & \gamma_t \end{cases} = \begin{cases} Zs & 1 \\ Z & -1 \\ z & -1 \end{cases}$ F: 12 - 123 Df sze 3xZ

What does it mean? In differential calculus, you learned that one interpretation of the derivative is as a slope. Another interpretation is that the derivative measures how a function transforms a neighborhood around a given point.

Check it out for yourself. (credit to samuel.gagnon.nepton, who was inspired by 3Blue1Brown.)

In particular, the (total) derivative of **any** function $f : \mathbb{R}^n \to \mathbb{R}^m$, evaluated at $\mathbf{a} = (a_1, \ldots, a_n)$, is the linear function that best approximates $f(\mathbf{x}) - f(\mathbf{a})$ at \mathbf{a} .

This leads to the familiar linear approximation formula for functions of one variable: $f(x) \not\approx f(a) + f'(a)(x-a) = \lfloor c x \rfloor$

Definition 55. The linearization or linear approximation of a differentiable function $f : \mathbb{R}^n \to \mathbb{R}^m$ at the point $\mathbf{a} = (a_1, \ldots, a_n)$ is



Question: What do you notice about the equation of the linearization?

Viri p y= fire



We say $f : \mathbb{R}^n \to \mathbb{R}$ is **differentiable** at **a** if its linearization is a good approximation of f near **a**.

$$\lim_{(x,y)\to(a,b)}\frac{f(x,y)-L(x,y)}{\|(x,y)-(a,b)\|}=0.$$

In particular, if f is a function f(x, y) of two variables, it is differentiable at (a, b) its graph has a unique tangent plane at (a, b, f(a, b)).



§14.4 The Chain Rule

Recall the Chain Rule from single variable calculus:

$$\frac{d}{dx}f(g(x)) = \frac{d}{dx}f(g(x)) + \frac{d}{dx}g(x)$$

Similarly, the **Chain Rule** for functions of multiple variables says that if $f : \mathbb{R}^p \to \mathbb{R}^m$ and $g : \mathbb{R}^n \to \mathbb{R}^p$ are both differentiable functions then (mxp) * (pm)

 $D(f(g(\mathbf{x}))) = Df(g(\mathbf{x}))Dg(\mathbf{x}).$

Df size Mxp Dg size pxn

wxn



$$h(t) = h(t(t)) = h(t(t), 2-t^{2})$$

$$Dh(t) = Dh(t(t)) + Dt(t)$$

$$\sum_{n=1}^{\infty} Dh(1) = Dh|_{(n,n)=(n,1)} + \frac{1}{2} + \frac$$

 $\mathbb{R}^n \xrightarrow{g} \mathbb{R}^n \xrightarrow{f} \mathbb{R}^m$

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 $g(s_{it}) = \langle u(s_{it}), v(s_{it}) \rangle$ Page 51

Example 59. Suppose that W(s,t) = F(u(s,t), v(s,t)), where F, u, v are differentiable functions and we know the following information.

$$u(1,0) = 2$$

$$v(1,0) = 3$$

$$u_{s}(1,0) = -2$$

$$v_{s}(1,0) = 5$$

$$u_{t}(1,0) = 6$$

$$V_{t}(1,0) = 4$$

$$F_{v}(2,3) = -1$$

$$D(f(g(x))) = Df(g(x)) Dg(x)$$

$$Find W_{s}(1,0) \text{ and } W_{t}(1,0).$$

$$f = F$$

$$g = \langle u_{v}v \rangle$$

$$\chi = \langle s_{1}t \rangle$$

$$T = (F u F v) \begin{bmatrix} u_{s} & u_{t} \\ v_{s} & v_{t} \end{bmatrix}$$

e.g. (a) S=1, t=0 $U_{s}(1,0) = -2$ U(1,0) = 2 U(1,0) = 3 $= (-1 \ 10) * (-2 \ 6)$ U(1,0) = 3 $= (57 \ 34)$ $U_{w_{s}}$ $W_{t}|_{e(1,0)}$

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Application to Implicit Differentiation: If F(x, y, z) = c is used to *implicitly* define z as a function of x and y, then the chain rule says:

Example 60. Compute
$$\frac{\partial z}{\partial x}$$
 and $\frac{\partial z}{\partial y}$ for the sphere $x^2 + y^2 + z^2 = 4$.
 $z = z$ Get
 $F(x_{141}, z) = x^2 + y^2 + z^2$
 $F_x = 2x$
 $F_y = -\frac{F_x}{F_z} = -\frac{2y}{2z} = -\frac{x}{z}$
 Cod
 $\frac{\partial z}{\partial x} = -\frac{F_x}{F_z} = -\frac{2y}{2z} = -\frac{y}{z}$