

Chapter 5

Eigenvalues and Eigenvectors

Section 5.1

Eigenvalues and Eigenvectors

Definition

If A is an $n \times n$ square matrix and there is a nonzero vector v in $\mathbf{R}^n$ and a scalar λ in $\mathbf{R}$ with

$$Av = \lambda v,$$

then v is an **eigenvector** of A with **eigenvalue** λ.

Note: Eigenvectors are by definition nonzero. Eigenvalues may be equal to zero.

Note: This is the most important definition in the course.

Verifying Eigenvectors

Example

$$A = \begin{pmatrix} 0 & 6 & 8 \\ \frac{1}{2} & 0 & 0 \\ 0 & \frac{1}{2} & 0 \end{pmatrix} \qquad v = \begin{pmatrix} 16 \\ 4 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 6 & 8 \\ \frac{1}{2} & 0 & 0 \\ 0 & \frac{1}{2} & 0 \end{pmatrix} \begin{pmatrix} 16 \\ 4 \\ 1 \end{pmatrix}$$

Example

$$A = \begin{pmatrix} 2 & 2 \\ -4 & 8 \end{pmatrix} \qquad v = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

You Try It!

Poll

Poll

Which of the vectors

A. $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$ B. $\begin{pmatrix} 1 \\ -1 \end{pmatrix}$ C. $\begin{pmatrix} -1 \\ 1 \end{pmatrix}$ D. $\begin{pmatrix} 2 \\ 1 \end{pmatrix}$ E. $\begin{pmatrix} 0 \\ 0 \end{pmatrix}$

are eigenvectors of the matrix $\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$?

What are the eigenvalues?

Verifying Eigenvalues

Question: Is $\lambda = 3$ an eigenvalue of $A = \begin{pmatrix} 2 & -4 \\ -1 & -1 \end{pmatrix}$?

Q: is there a **nonzero** vector x such that Ax=3x?

https://textbooks.math.gatech.edu/ila/demos/rabbits/book_demo.html

A Biology Question

Motivation

In a population of rabbits:

1. half of the newborn rabbits survive their first year;
2. of those, half survive their second year;
3. their maximum life span is three years;
4. rabbits have 0, 6, 8 baby rabbits in their three years, respectively.

If you know the population one year, what is the population the next year?

f_n = first-year rabbits in year n
s_n = second-year rabbits in year n
t_n = third-year rabbits in year n

The rules say:

$$\begin{pmatrix} 0 & 6 & 8 \\ \frac{1}{2} & 0 & 0 \\ 0 & \frac{1}{2} & 0 \end{pmatrix} \begin{pmatrix} f_n \\ s_n \\ t_n \end{pmatrix} = \begin{pmatrix} f_{n+1} \\ s_{n+1} \\ t_{n+1} \end{pmatrix}.$$

Let $A = \begin{pmatrix} 0 & 6 & 8 \\ \frac{1}{2} & 0 & 0 \\ 0 & \frac{1}{2} & 0 \end{pmatrix}$ and $v_n = \begin{pmatrix} f_n \\ s_n \\ t_n \end{pmatrix}$. Then $Av_n = v_{n+1}$. ← difference equation

A Biology Question

Continued

If you know v_0, what is v_{10}?

$$v_{10} = Av_9 = AAv_8 = \cdots = A^{10}v_0.$$

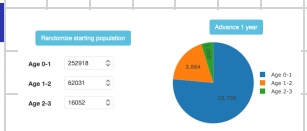
This makes it easy to compute examples by computer: [interactive]

v_0	v_{10}	v_{11}
$\begin{pmatrix} 3 \\ 7 \\ 9 \end{pmatrix}$	$\begin{pmatrix} 30189 \\ 7761 \\ 1844 \end{pmatrix}$	$\begin{pmatrix} 61316 \\ 15095 \\ 3881 \end{pmatrix}$
$\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$	$\begin{pmatrix} 9459 \\ 2434 \\ 577 \end{pmatrix}$	$\begin{pmatrix} 19222 \\ 4729 \\ 1217 \end{pmatrix}$
$\begin{pmatrix} 4 \\ 7 \\ 8 \end{pmatrix}$	$\begin{pmatrix} 28856 \\ 7405 \\ 1765 \end{pmatrix}$	$\begin{pmatrix} 58550 \\ 14428 \\ 3703 \end{pmatrix}$

What do you notice about these numbers?

1. Eventually, each segment of the population doubles every year: $Av_n = v_{n+1} = 2v_n$.
2. The ratios get close to $(16 : 4 : 1)$:

$$v_n = (\text{scalar}) \cdot \begin{pmatrix} 16 \\ 4 \\ 1 \end{pmatrix}.$$



Problem: One of the eigenvalues of A is $\lambda = 8$. Identify the other eigenvalue and find at least two eigenvectors for each eigenvalue for the matrix $A = \begin{pmatrix} 2 & 4 \\ 3 & 6 \end{pmatrix}$

Important

If x is a nonzero vector in Nul(A), then x is an eigenvector of A with eigenvalue $\lambda = 0$.

Consequently, non-invertible matrices always have λ= 0 as an eigenvalue.

Eigenspaces

Definition

Let A be an $n \times n$ matrix and let λ be an eigenvalue of A. The λ-**eigenspace** of A is the set of all eigenvectors of A with eigenvalue λ, plus the zero vector:

$$\begin{aligned} \lambda\text{-eigenspace} &= \{v \text{ in } \mathbf{R}^n \mid Av = \lambda v\} \\ &= \{v \text{ in } \mathbf{R}^n \mid (A - \lambda I)v = 0\} \\ &= \mathrm{Nul}(A - \lambda I). \end{aligned}$$

Since the λ-eigenspace is a null space, it is a *subspace* of $\mathbf{R}^n$.

How do you find a basis for the λ-eigenspace? Parametric vector form!

Eigenspaces

Example

Find a basis for the 3-eigenspace of

$$A = \begin{pmatrix} 2 & -4 \\ -1 & -1 \end{pmatrix}.$$

Eigenspaces

Example

Find a basis for the 2-eigenspace of

$$A = \begin{pmatrix} 7/2 & 0 & 3 \\ -3/2 & 2 & -3 \\ -3/2 & 0 & -1 \end{pmatrix}.$$

Question: how many eigenvalues can a matrix have? Can they have more than one eigenvalue?

Eigenspaces
Example

Find a basis for the $\frac{1}{2}$-eigenspace of

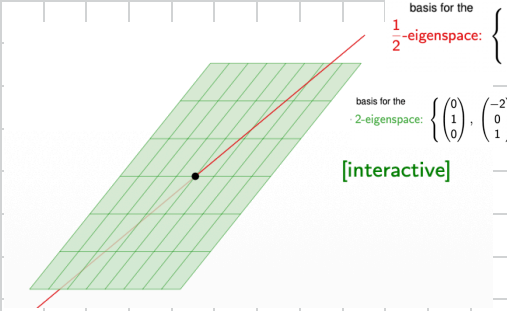
$$A = \begin{pmatrix} 7/2 & 0 & 3 \\ -3/2 & 2 & -3 \\ -3/2 & 0 & -1 \end{pmatrix}.$$

https://textbooks.math.gatech.edu/ila/demos/eigenspace.html?nomult

Eigenspaces
Example: picture

$$A = \begin{pmatrix} 7/2 & 0 & 3 \\ -3/2 & 2 & -3 \\ -3/2 & 0 & -1 \end{pmatrix}.$$

We computed bases for the 2-eigenspace and the 1/2-eigenspace:



basis for the $\frac{1}{2}$-eigenspace: $\left\{ \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} \right\}$

basis for the 2-eigenspace: $\left\{ \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -2 \\ 0 \\ 1 \end{pmatrix} \right\}$

[interactive]

Eigenspaces
Geometry; example

Let $T\colon \mathbf{R}^2 \to \mathbf{R}^2$ be reflection over the line L defined by $y = -x$, and let A be the matrix for T.

Question: What are the eigenvalues and eigenspaces of A? No computations!

https://textbooks.math.gatech.edu/ila/demos/eigenspace.html?mat=0,-1:-1,0&nomult

Eigenspaces
Geometry; example

Let $T\colon \mathbf{R}^2 \to \mathbf{R}^2$ be the vertical projection onto the x-axis, and let A be the matrix for T.

Question: What are the eigenvalues and eigenspaces of A? No computations!

https://textbooks.math.gatech.edu/ila/demos/eigenspace.html?mat=1,0:0,0&nomult

DLC.

A Matrix is Invertible if and only if Zero is not an Eigenvalue

Fact: A is invertible if and only if 0 is not an eigenvalue of A.

Why?

$$\begin{aligned} 0 \text{ is an eigenvalue of } A &\iff Ax = 0x \text{ has a nontrivial solution} \\ &\iff Ax = 0 \text{ has a nontrivial solution} \\ &\iff A \text{ is not invertible.} \end{aligned}$$

invertible matrix theorem

The Invertible Matrix Theorem

Addenda

We have a couple of new ways of saying "A is invertible" now:

The Invertible Matrix Theorem

Let A be a square $n \times n$ matrix, and let $T\colon \mathbf{R}^n \to \mathbf{R}^n$ be the linear transformation $T(x) = Ax$. The following statements are equivalent.

1. A is invertible.
2. T is invertible.
3. The reduced row echelon form of A is I_n.
4. A has n pivots.
5. $Ax = 0$ has no solutions other than the trivial one.
6. $\mathrm{Nul}(A) = \{0\}$.
7. $\mathrm{nullity}(A) = 0$.
8. The columns of A are linearly independent.
9. The columns of A form a basis for $\mathbf{R}^n$.
10. T is one-to-one.
11. $Ax = b$ is consistent for all b in $\mathbf{R}^n$.
12. $Ax = b$ has a unique solution for each b in $\mathbf{R}^n$.
13. The columns of A span $\mathbf{R}^n$.
14. $\mathrm{Col}\, A = \mathbf{R}^n$.
15. $\dim \mathrm{Col}\, A = n$.
16. $\mathrm{rank}\, A = n$.
17. T is onto.
18. There exists a matrix B such that $AB = I_n$.
19. There exists a matrix B such that $BA = I_n$.
20. The determinant of A is *not* equal to zero.
21. The number 0 is *not* an eigenvalue of A.

Eigenvectors with Distinct Eigenvalues are Linearly Independent

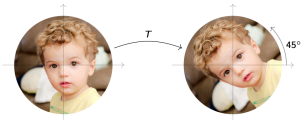
Fact: If $v_1, v_2, \ldots, v_k$ are eigenvectors of A with *distinct* eigenvalues $\lambda_1, \ldots, \lambda_k$, then $\{v_1, v_2, \ldots, v_k\}$ is linearly independent.

Warning! Knowing vectors v1 and v2 have the **same** eigenvalue does NOT mean that they are linearly dependent!

You Try It!

Poll

Let $T\colon \mathbf{R}^2 \to \mathbf{R}^2$ be counterclockwise rotation by 45°, and let A be the matrix for T.



Poll

Find an eigenvector of A without doing any computations.

A. Okay. **B.** No way.

Eigenspaces

Summary

Let A be an $n \times n$ matrix and let λ be a number.

1. λ is an eigenvalue of A if and only if $(A - \lambda I)x = 0$ has a nontrivial solution, if and only if $\mathrm{Nul}(A - \lambda I) \neq \{0\}$.
2. In this case, finding a basis for the λ-eigenspace of A means finding a basis for $\mathrm{Nul}(A - \lambda I)$ as usual, i.e. by finding the parametric vector form for the general solution to $(A - \lambda I)x = 0$.
3. The eigenvectors with eigenvalue λ are the nonzero elements of $\mathrm{Nul}(A - \lambda I)$, i.e. the nontrivial solutions to $(A - \lambda I)x = 0$.

Summary

- **Eigenvectors** and **eigenvalues** are the most important concepts in this course.
- Eigenvectors are by definition nonzero; eigenvalues may be zero.
- The eigenvalues of a triangular matrix are the diagonal entries.
- A matrix is invertible if and only if zero is not an eigenvalue.
- Eigenvectors with distinct eigenvalues are linearly independent.
- The λ-eigenspace is the set of all λ-eigenvectors, plus the zero vector.
- You can compute a basis for the λ-eigenspace by finding the parametric vector form of the solutions of $(A - \lambda I_n)x = 0$.

Section 5.2

The Characteristic Polynomial

The Characteristic Polynomial

Definition

Let A be a square matrix. The **characteristic polynomial** of A is

$$f(\lambda) = \det(A - \lambda I).$$

The **characteristic equation** of A is the equation

$$f(\lambda) = \det(A - \lambda I) = 0.$$

Important

The eigenvalues of A are the roots of the characteristic polynomial $f(\lambda) = \det(A - \lambda I)$.

The Characteristic Polynomial

Example

Question: What are the eigenvalues of

$$A = \begin{pmatrix} 5 & 2 \\ 2 & 1 \end{pmatrix}?$$

You Try It!

Q: What are the eigenvalues of A?

$$A = \begin{pmatrix} 2 & -4 \\ -1 & -1 \end{pmatrix}$$

Problem: Find the characteristic polynomial of A and then find the eigenvalues of the matrix where $A = \begin{pmatrix} 3 & 0 & 0 \\ 1 & 2 & 0 \\ 2 & 1 & 1 \end{pmatrix}$

Recall from before

If A is upper or lower triangular, then the determinant of A is the product of the diagonal entries.

Consequently, if A is upper or lower triangular, then the eigenvalues of A are just the diagonal entries.

Warning! This trick does **not work** to find the eigenvalues unless A is upper/lower triangular!

The Characteristic Polynomial

Example

Question: What is the characteristic polynomial of

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}?$$

Definition

The **trace** of a square matrix A is $\mathrm{Tr}(A)$ = sum of the diagonal entries of A.

Shortcut

The characteristic polynomial of a 2×2 matrix A is $f(\lambda) = \lambda^2 - \mathrm{Tr}(A)\,\lambda + \det(A)$.

Summary

We did two different things today.

First we talked about the geometry of eigenvalues and eigenvectors:

- Eigenvectors are vectors v such that v and Av are on the same line through the origin.
- You can pick out the eigenvectors geometrically if you have a picture of the associated transformation.

Then we talked about characteristic polynomials:

- We learned to find the eigenvalues of a matrix by computing the roots of the characteristic polynomial $p(\lambda) = \det(A - \lambda I)$.
- For a 2×2 matrix A, the characteristic polynomial is just

$$p(\lambda) = \lambda^2 - \mathrm{Tr}(A)\lambda + \det(A).$$