

Section 1.1

Systems of Linear Equations

Line, Plane, Space, ...

Recall that \mathbb{R} denotes the collection of all real numbers, i.e. the number line. It contains numbers like $0, -1, \pi, \frac{1}{2}, \dots$

Definition

Let n be a positive whole number. We define

$$\mathbb{R}^n = \text{all ordered } n\text{-tuples of real numbers } (x_1, x_2, x_3, \dots, x_n).$$

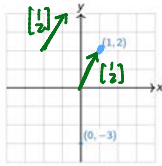
Example

When $n = 1$, we just get \mathbb{R} back: $\mathbb{R}^1 = \mathbb{R}$. Geometrically, this is the number line.



Example

When $n = 2$, we can think of \mathbb{R}^2 as the plane. This is because every point on the plane can be represented by an ordered pair of real numbers, namely, its x - and y -coordinates.



$(1, 2)$ location in x - y plane \mathbb{R}^2

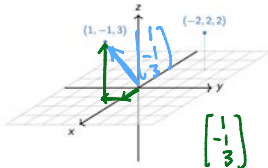
$\begin{bmatrix} 1 \\ 2 \end{bmatrix}$ direction & length or "how to move around in \mathbb{R}^2 "

"move right 1 & move up 2"

\mathbb{R}^n

Example

When $n = 3$, we can think of \mathbb{R}^3 as the space we (appear to) live in. This is because every point in space can be represented by an ordered triple of real numbers, namely, its x -, y -, and z -coordinates.



$$\begin{bmatrix} 1 \\ -1 \\ 3 \end{bmatrix}$$

Says
First move in x -direction 1 step (forward)
then move in y -direction -1 step (backward)
then move in z -direction 3 steps (up)

\mathbb{R}^3

consists of 3-tuples (x, y, z)

thought of as locations in 3-space, or

$\begin{bmatrix} x \\ y \\ z \end{bmatrix}$ direction & length

§1.1

So what is \mathbb{R}^1 ? or \mathbb{R}^2 ? or \mathbb{R}^3 ?

... go back to the definition: ordered n -tuples of real numbers

$$(x_1, x_2, x_3, \dots, x_n).$$

They're still "geometric" spaces, in the sense that our intuition for \mathbb{R}^2 and \mathbb{R}^3 sometimes extends to \mathbb{R}^n , but they're harder to visualize.

We'll make definitions and state theorems that apply to any \mathbb{R}^n , but we'll only draw pictures for \mathbb{R}^2 and \mathbb{R}^3 .

The power of using these spaces is the ability to use elements of \mathbb{R}^n to label various objects of interest, like solutions to systems of equations.

\mathbb{R}^2 all points (x, y) where x, y are real numbers

\mathbb{R}^3 all points (x, y, z) where x, y, z are real

You try it!

TRUE or FALSE: The set of points in \mathbb{R}^3 consisting of all the points with z -value equal to zero equals the set \mathbb{R}^2 .

e.g. $(1, 1, 0)$, $(0, -2, 0)$, $(3, -4, 0)$, $(\pi, \sqrt{2}, 0), \dots$

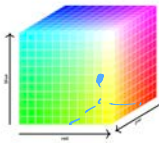
are true in \mathbb{R}^2 ?

all the points have 3 components (numbers) so they are all in \mathbb{R}^3 .

Labeling with \mathbb{R}^n

Example

All colors you can see can be described by three quantities: the amount of red, green, and blue light in that color. Therefore, we can use the elements of \mathbb{R}^3 to label all colors: the point $(.2, .4, .9)$ labels the color with 20% red, 40% green, and 90% blue.



on your phone screen

all the pixels are really

just a point/vector in \mathbb{R}^3

Labeling with \mathbb{R}^n

Example

Last time we could have used \mathbb{R}^4 to label the amount of traffic (x, y, z, w) passing through four streets.



For instance the point $(100, 20, 30, 150)$ corresponds to a situation where 100 cars per hour drive on road x , 20 cars per hour drive on road y , etc.

What does the solution set of a linear equation look like?

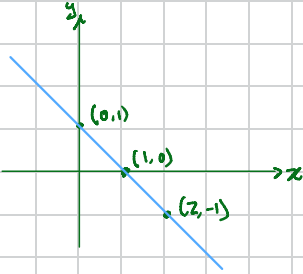
Example: Graph the implicit equation $x+y=1$ in \mathbb{R}^2 and find an explicit parametrization of the line.

idea: write explicit equation

$$x+y=1 \Rightarrow y=-x+1$$

$$\text{Slope } m = -1$$

$$y - m x = b = 1$$



check: points on line b/c

$$0+1=1 \quad \checkmark$$

$$1+0=1 \quad \checkmark$$

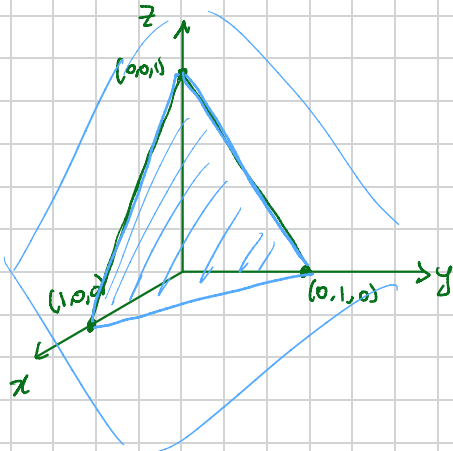
$$2+(-1)=1 \quad \checkmark$$

$x+y=1$ equation of the line is

implicit

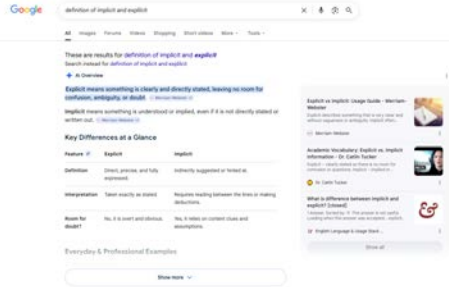
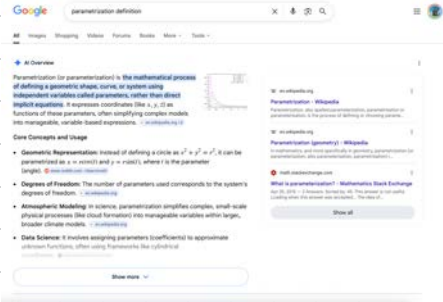
$y=-x+1$ equation is explicit

Example: Graph the implicit equation $x+y+z=1$ in \mathbb{R}^3 and find an explicit parametrization of the plane

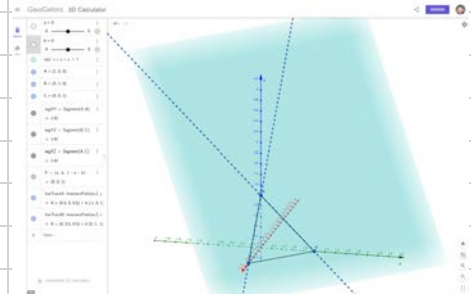


e.g. $(2, 3, z)$ to be in the plane?
 $2+3+z=1 \Rightarrow z=1-5=-4$

$$z=1-x-y, \quad x, y \text{ can be anything}$$



<https://www.geogebra.org/3d/kjrqt66w>

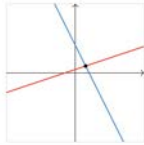


Systems of Linear Equations

What does the solution set of a system of more than one linear equation look like?

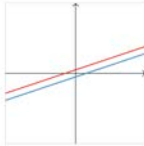
$$\begin{aligned}x - 3y &= -3 \\ 2x + y &= 8\end{aligned}$$

... is the intersection of two lines, which is a point in this case.



$$\begin{aligned}x - 3y &= -3 \\ x - 3y &= 3\end{aligned}$$

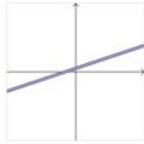
has no solution: the lines are parallel.



A system of equations with no solutions is called **inconsistent**.

$$\begin{aligned}x - 3y &= -3 \\ 2x - 6y &= -6\end{aligned}$$

has infinitely many solutions: they are the same line.



Note that multiplying an equation by a nonzero number gives the same solution set. In other words, they are **equivalent** (systems of) equations.

Summary

- \mathbb{R}^n is the set of ordered lists of n numbers.
- \mathbb{R}^n can be used to label geometric objects, like \mathbb{R}^2 can label points on a plane.
- The solutions of a system equations look like an intersection of lines, planes, etc.
- Finding all the solutions of a system of equations means finding a **parametric form**: a labeling by some \mathbb{R}^n .

↗ location (POINTS)
↘ direction & length (VECTOR)

\mathbb{R}^n

mathbb{R}^n

\mathbb{R}^n

Natural Questions

- * Is there always exactly one solution? **No**
- * How to find the solution(s) systematically
- * How to determine IF there are solutions without finding any?

Section 1.2

Row Reduction

Review from 1.1: Solving Systems of Equations

Example

Solve the system of equations

$$\begin{aligned} x + 2y + 3z &= 6 \\ 2x - 3y + 2z &= 14 \\ 3x + y - z &= -2 \end{aligned}$$

Definition

A system of equations is called **inconsistent** if it has no solution. It is **consistent** otherwise.

want: a point(s) (x, y, z) which are on ALL 3 planes

- A solution is a list of numbers x, y, z, \dots that makes all of the equations true.
- The solution set is the collection of all solutions.
- Solving the system means finding the solution set in a "parameterized" form.

Solve:

$$\begin{aligned} x + 2y + 3z &= 6 \\ 2x - 3y + 2z &= 14 \\ 3x + y - z &= -2 \end{aligned}$$

* row reduction

* substitution (solve for one var of sub into other eqns)

→ * elimination (add a multiple of one ~~eqn~~ equation to another)

You try it! What are some techniques that you already know to solve a system like this?

$$\begin{aligned} \textcircled{1} \quad x + 2y + 3z &= 6 \\ \textcircled{2} \quad 2x - 3y + 2z &= 14 \\ \textcircled{3} \quad 3x + y - z &= -2 \end{aligned}$$

$$\left\{ \begin{aligned} \textcircled{1} \quad x + 2y + 3z &= 6 \\ \textcircled{1} + \textcircled{2} \quad 3x - y + 5z &= 20 \\ \textcircled{3} \quad 3x + y - z &= -2 \end{aligned} \right.$$

$$\begin{aligned} \textcircled{1} \quad x + 2y + 3z &= 6 \\ \textcircled{2} \quad 3x - y + 5z &= 20 \\ \textcircled{2} + \textcircled{3} \quad 6x + 4z &= 18 \end{aligned}$$

adding two eqns together doesn't change solns. is lolc

$\star = \begin{pmatrix} 3 \\ 3 \end{pmatrix}$ and $\triangle = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ then

$$\star + \triangle = \begin{pmatrix} 4 \\ 4 \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

Elimination method: in what ways can you manipulate the equations?

- Multiply an equation by a nonzero number.
- Add a multiple of one equation to another.
- Swap two equations.

doesn't change solns.

(scale)
(replacement)
(swap)

doesn't change solns.

doesn't change solns.

Solve: $x + 2y + 3z = 6$
 $2x - 3y + 2z = 14$
 $3x + y - z = -2$

$\rightsquigarrow \left[\begin{array}{ccc|c} 1 & 2 & 3 & 6 \\ 2 & -3 & 2 & 14 \\ 3 & 1 & -1 & -2 \end{array} \right]$ \leftarrow manipulate this directly.

You try it! What are some techniques that you already know to solve a system like this?

Elimination method: in what ways can you manipulate the equations?

- ▶ Multiply an equation by a nonzero number. (scale)
- ▶ Add a multiple of one equation to another. (replacement)
- ▶ Swap two equations. (swap)

using matrices

$$\left[\begin{array}{ccc|c} 1 & 2 & 3 & 6 \\ 2 & -3 & 2 & 14 \\ 3 & 1 & -1 & -2 \end{array} \right]$$

$\sim -2R_1 + R_2 \rightarrow$
 $-3R_1 + R_3$

$$\left[\begin{array}{ccc|c} 1 & 2 & 3 & 6 \\ 0 & -7 & -4 & 2 \\ 0 & -5 & -10 & -20 \end{array} \right]$$

using eqns

$$\begin{cases} x + 2y + 3z = 6 \\ 2x - 3y + 2z = 14 \\ 3x + y - z = -2 \end{cases}$$

\Rightarrow

$$\begin{cases} x + 2y + 3z = 6 \\ -7y - 4z = 2 \\ -5y - 10z = -20 \end{cases}$$

idea is that the new system of equations will be easier to solve bc two eqns don't have x 's.

$x + 2y + 3z = 6$
 $2x - 3y + 2z = 14$
 $3x + y - z = -2$

becomes $\left(\begin{array}{ccc|c} 1 & 2 & 3 & 6 \\ 2 & -3 & 2 & 14 \\ 3 & 1 & -1 & -2 \end{array} \right)$

the coefficients

of the system of linear equations, & constants on the RHS of equations

This is called an (augmented) matrix. Our equation manipulations become elementary row operations:

- ▶ Multiply all entries in a row by a nonzero number. (scale)
- ▶ Add a multiple of each entry of one row to the corresponding entry in another. (row replacement)
- ▶ Swap two rows. (swap)

The augmentation bar is a visual aid it's not part of the matrix and whether it's there or not DOESN'T CHANGE any answers about questions you can ask.

Row Equivalence

Definition

Two matrices are called **row equivalent** if one can be obtained from the other by doing some number of elementary row operations.

So the linear equations of row-equivalent matrices have the **same solution set**.

Important

The process of doing row operations to a matrix does not change the solution set of the corresponding linear equations!

\sim \downarrow sim
"row equivalence"

You try it!

$$A = \left[\begin{array}{ccc|c} 1 & 2 & 3 & 6 \\ 2 & -3 & 2 & 14 \\ 3 & 1 & -1 & -2 \end{array} \right]$$

T/F is $A = B$? **no.**

T/F is $A \sim B$? yes. they
are row equivalent.

$$\sim \begin{array}{l} -2R_1 + R_2 \rightarrow \\ -3R_1 + R_3 \rightarrow \end{array} \left[\begin{array}{ccc|c} 1 & 2 & 3 & 6 \\ 0 & -7 & -4 & 2 \\ 0 & -5 & -10 & -20 \end{array} \right] = B$$

How do you get to a "simple" system?

Row Echelon Form

Let's come up with an algorithm for turning an arbitrary matrix into a "solved" matrix. What do we mean by "solved"?

A matrix is in **row echelon form** if

1. All zero rows are at the bottom.
2. Each leading nonzero entry of a row is to the right of the leading entry of the row above.
3. Below a leading entry of a row, all entries are zero.

(REF)

leading entries form a "staircase"

they're to the right & below the leading entries above them.

Picture:

$$\begin{pmatrix} \boxed{+} & 0 & + & + \\ 0 & \boxed{+} & 0 & + \\ 0 & 0 & 0 & \boxed{+} \\ 0 & 0 & 0 & 0 \end{pmatrix} \quad \begin{array}{l} + = \text{any number} \\ \boxed{+} = \text{any nonzero number} \end{array}$$

Definition

A **pivot** $\boxed{+}$ is the first nonzero entry of a row of a matrix. A **pivot column** is a column containing a pivot of a matrix in row echelon form.

in any of its row echelon forms.

Reduced Row Echelon Form

A matrix is in **reduced row echelon form** if it is in row echelon form, and in addition,

4. The pivot in each nonzero row is equal to 1.
5. Each pivot is the only nonzero entry in its column.

(RREF)

Picture:

$$\begin{pmatrix} 1 & 0 & + & 0 & + \\ 0 & 1 & + & 0 & + \\ 0 & 0 & 0 & 1 & + \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix} \quad \begin{array}{l} + = \text{any number} \\ 1 = \text{pivot} \end{array}$$

An Inconsistent Example

Example
Solve the system of equations

$$\begin{aligned} x + y &= 2 \\ 3x + 4y &= 5 \\ 4x + 5y &= 9 \end{aligned}$$

Solve: $x + y = 2$
 $3x + 4y = 5$
 $4x + 5y = 9$

① $A|b = \left[\begin{array}{cc|c} 1 & 1 & 2 \\ 3 & 4 & 5 \\ 4 & 5 & 9 \end{array} \right] \sim \begin{array}{l} \text{REF/REF no} \\ -2R_1 + R_2 \\ -4R_1 + R_3 \end{array} \left[\begin{array}{cc|c} 1 & 1 & 2 \\ 0 & 1 & -1 \\ 0 & 1 & 1 \end{array} \right] \sim \begin{array}{l} \text{REF/REF} \\ -R_2 + R_3 \end{array} \left[\begin{array}{cc|c} 1 & 1 & 2 \\ 0 & 1 & -1 \\ 0 & 0 & 2 \end{array} \right]$

③ $x + y = 2$
 $y = -1$
 $0 = 2$

$\left\{ \begin{array}{l} 1x + 1y = 2 \\ 0x + 1y = -1 \\ 0x + 0y = 2 \end{array} \right.$

paradox: once you write down the simple equations you can see that there are NO SOLUTIONS (b/c 3rd equation is NEVER true)

A: So the original system has NO SOLUTIONS and is inconsistent.

META

- Write the system as an augmented matrix $[A|b]$
- row reduce to get the aug. matrix to either REF/RREF
- rewrite the eqns of the REF/RREF

x x & those simpler expressions.
REF/RREF no REF/RREF

1.2: Row Reduction

Theorem
Every matrix is row equivalent to one and only one matrix in reduced row echelon form. (RREF)

You try it! REF? RREF?

Which of the following matrices are in reduced row echelon form?

REP A. $\begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}$ B. $\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ RREF

C. $\begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$ D. $\begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{pmatrix}$ E. $\begin{pmatrix} 0 & 1 & 8 & 0 \end{pmatrix}$ RREF

F. $\begin{pmatrix} 1 & 17 & 0 \\ 0 & 0 & 1 \end{pmatrix}$ RREF

$x + 17 = 0$
 $0 = 1$

Row Echelon Form

Let's come up with an algorithm for turning an arbitrary matrix into a "solved" matrix. What do we mean by "solved"?

A matrix is in row echelon form if

- All zero rows are at the bottom.
- Each leading nonzero entry of a row is to the right of the leading entry of the row above.
- Below a leading entry of a row, all entries are zero.

staircase

Reduced Row Echelon Form

A matrix is in reduced row echelon form if it is in row echelon form, and in addition,

- The pivot in each nonzero row is equal to 1.
- Each pivot is the only nonzero entry in its column.

Picture:

$$\begin{pmatrix} 1 & 0 & * & 0 & * \\ 0 & 1 & * & 0 & * \\ 0 & 0 & 0 & 1 & * \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

* = any number
1 = pivot

Bonus

$$\left[\begin{array}{cc|c} 1 & 2 & 2 \\ 0 & 0 & 1 \end{array} \right]$$

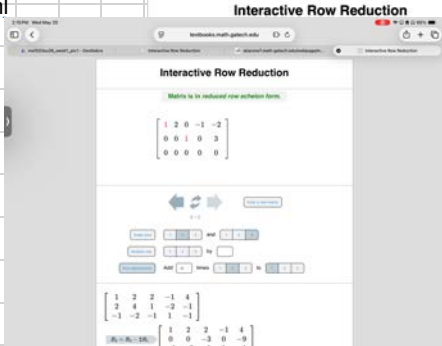
$x + 2y = ?$
 $0 = 1$
REF/RREF?

Extra example 1

Translate the equation to an augmented matrix and put the matrix in RREF.
Label all pivots. Feel free to use the [Interactive Row Reducer](#).

$$\begin{aligned} x_1 + 2x_2 + 2x_3 - x_4 &= 4 \\ 2x_1 + 4x_2 + x_3 - 2x_4 &= -1 \\ -x_1 - 2x_2 - x_3 + x_4 &= -1 \end{aligned}$$

<https://textbooks.math.gatech.edu/ila/demos/rprinter.html>



Enter this into the interactive row reducer:

1, 2, 2, -1, 4
2, 4, 1, -2, -1
-1, -2, -1, 1, -1

$$\left[\begin{array}{cccc|c} 1 & 2 & 2 & -1 & 4 \\ 2 & 4 & 1 & -2 & -1 \\ -1 & -2 & -1 & 1 & -1 \end{array} \right] \sim \dots \sim \left[\begin{array}{cccc|c} 1 & 2 & 0 & -1 & 2 \\ 0 & 0 & 1 & 0 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

RREF

2 pivots, in row 1 - col 1
and row 2 - col 3

Summary

- We can more easily do elimination with matrices. The allowable moves are row swaps, row scales, and row replacements. This is called row reduction.
- A matrix in row echelon form corresponds to a system of linear equations that we can easily solve by back substitution.
- A matrix in reduced row echelon form corresponds to a system of linear equations that we can easily solve just by looking.
- We have an algorithm for row reducing a matrix to reduced row echelon form.
- The reduced row echelon form of a matrix is unique.
- Two matrices that differ by row operations are called row equivalent. Row-equivalent systems have the same solution set.
- A system of equations is inconsistent **exactly** when the corresponding augmented matrix has a pivot in the last column.

(Reduced) Row Echelon Form

1.2 Review

A matrix is in **row echelon form** if

1. All zero rows are at the bottom.
2. Each leading nonzero entry of a row is to the right of the leading entry of the row above.
3. Below a leading entry of a row, all entries are zero.

A matrix is in **reduced row echelon form** if it is in row echelon form, and in addition,

4. The pivot in each nonzero row is equal to 1.
5. Each pivot is the only nonzero entry in its column.

Row echelon form:

$$\left(\begin{array}{cccc|c} \color{red}{\boxed{1}} & * & * & * & * \\ 0 & \color{red}{\boxed{2}} & * & * & * \\ 0 & 0 & 0 & \color{red}{\boxed{3}} & * \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

Reduced row echelon form:

$$\left(\begin{array}{cccc|c} 1 & 0 & * & 0 & * \\ 0 & 1 & * & 0 & * \\ 0 & 0 & 0 & 1 & * \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

□ = pivots

Reinforcing 1.2: Row Reduction Algorithm

Step 1a Swap the 1st row with a lower one so a leftmost nonzero entry is in 1st row (if necessary).

Step 1b Scale 1st row so that its leading entry is equal to 1.

Step 1c Use row replacement so all entries below this 1 are 0.

Step 2a Swap the 2nd row with a lower one so that the leftmost nonzero entry is in 2nd row.

Step 2b Scale 2nd row so that its leading entry is equal to 1.

Step 2c Use row replacement so all entries below this 1 are 0.

Step 3a Swap the 3rd row with a lower one so that the leftmost nonzero entry is in 3rd row.

etc.

Last Step Use row replacement to clear all entries above the pivots, starting with the last pivot (to make life easier).

Example

$$\left(\begin{array}{cccc|c} 0 & -7 & -4 & 2 & 2 \\ 2 & 4 & 6 & 12 & 2 \\ 3 & 1 & -1 & -2 & -2 \end{array} \right)$$

The diagrams show the progression of a matrix through various stages of row reduction:

- Get a 1 here:** A matrix with a pivot of 1 in the first row, first column.
- Clear down:** The matrix with zeros below the pivot in the first column.
- Get a 1 here:** A pivot of 1 in the second row, second column.
- Clear down:** The matrix with zeros below the pivot in the second column.
- (maybe these are already zero):** A matrix with a pivot of 1 in the third row, third column.
- Get a 1 here:** A pivot of 1 in the first row, second column.
- Clear down:** The matrix with zeros below the pivot in the first row, second column.
- Matrix is in REF:** The matrix in Row Echelon Form.
- Clear up:** The matrix with zeros above the pivot in the first row, second column.
- Clear up:** The matrix with zeros above the pivot in the first row, third column.
- Matrix is in RREF:** The matrix in Reduced Row Echelon Form.

The final RREF matrix is shown as:

$$\left(\begin{array}{cccc|c} 1 & * & * & 0 & * \\ 0 & 1 & * & 0 & * \\ 0 & 0 & 0 & 1 & * \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$
 The text 'Profit?' is written next to it.

Reinforcing 1.2: Row Reduction Algorithm

Step 1a Swap the 1st row with a lower one so a leftmost nonzero entry is in 1st row (if necessary).

Step 1b Scale 1st row so that its leading entry is equal to 1.

Step 1c Use row replacement so all entries below this 1 are 0.

Step 2a Swap the 2nd row with a lower one so that the leftmost nonzero entry is in 2nd row.

Step 2b Scale 2nd row so that its leading entry is equal to 1.

Step 2c Use row replacement so all entries below this 1 are 0.

Step 3a Swap the 3rd row with a lower one so that the leftmost nonzero entry is in 3rd row.

etc.

Last Step Use row replacement to clear all entries above the pivots, starting with the last pivot (to make life easier).

Example

$$\begin{pmatrix} 0 & -7 & -4 & 2 \\ 2 & 4 & 6 & 12 \\ 3 & 1 & -1 & -2 \end{pmatrix}$$

Get a 1 here Clear down Get a 1 here Clear down

$$\begin{pmatrix} 0 & * & * & * \\ * & * & * & * \\ * & * & * & * \\ * & * & * & * \end{pmatrix} \rightarrow \begin{pmatrix} 1 & * & * & * \\ * & * & * & * \\ * & * & * & * \\ * & * & * & * \end{pmatrix} \rightarrow \begin{pmatrix} 1 & * & * & * \\ 0 & * & * & * \\ 0 & * & * & * \\ 0 & * & * & * \end{pmatrix} \rightarrow \begin{pmatrix} 1 & * & * & * \\ 0 & 1 & * & * \\ 0 & * & * & * \\ 0 & * & * & * \end{pmatrix}$$

(maybe these are already zero) Get a 1 here Clear down Matrix is in REF

$$\begin{pmatrix} 1 & * & * & * \\ 0 & 1 & * & * \\ 0 & 0 & 0 & * \\ 0 & 0 & 0 & * \end{pmatrix} \rightarrow \begin{pmatrix} 1 & * & * & * \\ 0 & 1 & * & * \\ 0 & 0 & 0 & * \\ 0 & 0 & 0 & * \end{pmatrix} \rightarrow \begin{pmatrix} 1 & * & * & * \\ 0 & 1 & * & * \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & * \end{pmatrix} \rightarrow \begin{pmatrix} 1 & * & * & * \\ 0 & 1 & * & * \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Clear up Clear up Matrix is in RREF Profit?

$$\begin{pmatrix} 1 & * & * & * \\ 0 & 1 & * & * \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & * & * & 0 \\ 0 & 1 & * & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & * & 0 \\ 0 & 1 & * & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

You try it!

Question

What does an augmented matrix in reduced row echelon form look like, if its system of linear equations is inconsistent?

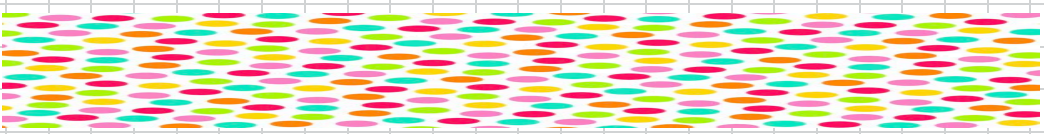
Answer:

$$\begin{pmatrix} 1 & 0 & * & * & 0 \\ 0 & 1 & * & * & 0 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

An augmented matrix corresponds to an inconsistent system of equations if and only if the last (i.e., the augmented) column is a pivot column.

↑ pivot in augmented column.

all coefficients zero but constant nonzero!



Section 1.3

Parametric Form

<https://textbooks.math.gatech.edu/ila/demos/rprinter.html?mat=2,1,12,1:1,2,9,-1>

Example 1

How do we solve a system of linear equations if the row reduced matrix has a column without a pivot? Let's do an example.

$2x + y + 12z = 1$
 $x + 2y + 9z = -1$ gives rise to the matrix $\begin{pmatrix} 2 & 1 & 12 & 1 \\ 1 & 2 & 9 & -1 \end{pmatrix}$.

① $\begin{bmatrix} 2 & 1 & 12 & 1 \\ 1 & 2 & 9 & -1 \end{bmatrix} \xrightarrow{\sim} \begin{bmatrix} 1 & 2 & 9 & -1 \\ 2 & 1 & 12 & 1 \end{bmatrix} \xrightarrow{-2R_1+R_2} \begin{bmatrix} 1 & 2 & 9 & -1 \\ 0 & -3 & -6 & 3 \end{bmatrix}$

REF ✓

$\xrightarrow{-\frac{1}{3}R_2} \begin{bmatrix} 1 & 2 & 9 & -1 \\ 0 & 1 & 2 & -1 \end{bmatrix} \xrightarrow{-2R_2+R_1} \begin{bmatrix} 1 & 0 & 5 & 1 \\ 0 & 1 & 2 & -1 \end{bmatrix}$ ②

NOT equivalent

x z (free)

① [A|b]

② [A|b] → REF/REFP

③ write eqns & solve

④ Solve for pivot var in terms of free (non-pivot) var (don't forget to write free var!!)

⑤ $\begin{cases} x + 5z = 1 \\ y + 2z = -1 \end{cases}$

$$\begin{cases} x = 1 - 5z \\ y = -1 - 2z \\ z = z \text{ (free)} \end{cases}$$

parametric equation form of the solution.

all solutions.

So for example all the following are solutions

(z=0) $\begin{cases} x=1 \\ y=-1 \\ z=0 \end{cases}$

(z=1) $\begin{cases} x=-4 \\ y=-3 \\ z=1 \end{cases}$

(z=7) $\begin{cases} x=-34 \\ y=-15 \\ z=7 \end{cases}$

Eqn was $\begin{cases} 2x+y+12z=1 \\ x+2y+9z=-1 \end{cases}$ ✓

Check ① $(x,y,z) = (1, -1, 0)$ ✓

$2(1) + (-1) + 12(0) = 1$ ✓
 $1 + 2(-1) + 9(0) = -1$ ✓

Check ② $(x,y,z) = (-4, -3, 1)$

$2(-4) + (-3) + 12(1) \stackrel{?}{=} 1$ ✓
 $(-4) + 2(-3) + 9(1) = -1$ ✓

Free Variables

Definition

Consider a consistent linear system of equations in the variables x_1, \dots, x_n . Let A be a row echelon form of the matrix for this system.

We say that x_i is a **free variable** if its corresponding column in A is not a pivot column.

Important

1. You can choose any value for the free variables in a (consistent) linear system.
2. Free variables come from columns without pivots in a matrix in row echelon form.

Example 2

Suppose the reduced row echelon form of the matrix for a linear system in x_1, x_2, x_3, x_4 is

$$\left(\begin{array}{cccc|c} 1 & 0 & 0 & 3 & 2 \\ 0 & 0 & 1 & 4 & -1 \end{array} \right)$$

What happened to x_2 ? What is it allowed to be?

Note: Two pivot vars x_1, x_3
two free vars x_2, x_4 .

$$\begin{cases} 1x_1 + 0x_2 + 0x_3 + 3x_4 = 2 \\ 0x_1 + 0x_2 + 1x_3 + 4x_4 = -1 \end{cases}$$

You tried it??

Example 3

Solve the system of linear equations in x_1, x_2, x_3, x_4 :

$$\begin{aligned} x_1 + 5x_3 &= 0 \\ x_4 &= 0 \end{aligned}$$

equality!

x_2, x_3 (Free)

$$[A|b] = \left[\begin{array}{cccc|c} 1 & 0 & 5 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{array} \right]$$

$$\begin{aligned} x_1 + 5x_3 &= 0 \\ x_4 &= 0 \end{aligned}$$

rewrite w/ free vars on RHS & adding free vars as well

a particular soln

$$\begin{aligned} x_1 &= 0 \\ x_2 &= 0 \\ x_3 &= 0 \\ x_4 &= 0 \end{aligned}$$

$$\begin{aligned} x_1 &= -10 \\ x_2 &= 1 \\ x_3 &= 2 \\ x_4 &= 0 \end{aligned}$$

The boxed equation is called the **parametric form** of the general solution to the system of equations. It is obtained by moving all free variables to the right-hand side of the =.

- ① $[A|b] \checkmark$
- ② $[A|b] \rightsquigarrow$ REPAREF \checkmark
- ③ & ④ write easier system and solve

$$\begin{cases} x_1 + 3x_4 = 2 \\ x_3 + 4x_4 = -1 \end{cases}$$

all solns \rightarrow

$$\begin{aligned} x_1 &= 2 - 3x_4 \\ x_2 &= x_2 \text{ (Free)} \\ x_3 &= -1 - 4x_4 \\ x_4 &= x_4 \text{ (Free)} \end{aligned}$$

??

Check one particular

$$\begin{aligned} x_1 &= 2 \\ x_2 &= 5 \\ x_3 &= -1 \\ x_4 &= 0 \end{aligned}$$

parametric eqn form at solutions (2 free vars)

parametric eqn form

$$\begin{aligned} x_1 &= -5x_3 \\ x_2 &= x_2 \text{ (Free)} \\ x_3 &= x_3 \text{ (Free)} \\ x_4 &= 0 \end{aligned}$$

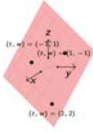
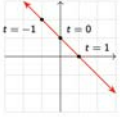
all solns \swarrow

Free variables

Geometry, looking ahead!

If we have a consistent system of linear equations, with n variables and k free variables, then the set of solutions is a k -dimensional object in \mathbb{R}^n . We will make this precise later, but it is worth thinking about now.

Why does this make sense?



You try it!

Poll

A linear system has 4 variables and 3 equations.

What are the possible solution sets?

- 20% (a) point
- 20% (b) two points
- 80% (c) line
- 70% (d) plane
- 50% (e) 3-dimensional object ✓
- 4 (f) 4-dimensional object ✓



Coefficient matrix
3 rows & 4 cols

$$[A|b] = \left[\begin{array}{cccc|c} * & * & * & * & * \\ * & * & * & * & * \\ * & * & * & * & * \end{array} \right] \left\{ \begin{array}{l} \text{augmented matrix} \\ 3 \text{ rows } \& \# 5 \text{ cols.} \end{array} \right.$$

$$(b) \left[\begin{array}{cccc|c} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \begin{array}{l} 0=0 \quad x_1 = \text{free} \\ 0=0 \quad x_2 = \text{free} \\ 0=0 \quad x_3 = \text{free} \\ \quad \quad x_4 = \text{free} \end{array} \quad \begin{array}{l} 4\text{-dim Solution set} \end{array}$$

$$(c) \left[\begin{array}{cccc|c} 1 & 0 & 0 & 0 & 2 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \begin{array}{l} x_1 = 2 \\ x_2 = \text{free} \\ x_3 = \text{free} \\ x_4 = \text{free} \end{array} \quad \begin{array}{l} 3\text{-dim Solution set.} \end{array}$$

$$(d) \left[\begin{array}{cccc|c} 1 & 0 & 0 & 0 & 2 \\ 0 & 1 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \begin{array}{l} x_1 = 2 \\ x_2 = 3 \\ x_3 = \text{free} \\ x_4 = \text{free} \end{array} \quad \begin{array}{l} 2\text{-dim Solution set} \end{array}$$

$$(e) \left[\begin{array}{cccc|c} 1 & 0 & 0 & 0 & 2 \\ 0 & 1 & 0 & 0 & 3 \\ 0 & 0 & 1 & 0 & 4 \end{array} \right] \begin{array}{l} x_1 = 2 \\ x_2 = 3 \\ x_3 = 4 \\ x_4 = \text{free} \end{array}$$

(a) Not possible b/c # eqns > # vars
so can't have only pivot vars
(at most 1 pivot per row).

(b) NEVER POSSIBLE.
only possible if eq solns

none/exactly one/infinite many

Yet Another Example

The linear system

$$x + y + z = 1 \text{ has matrix form } (1 \ 1 \ 1 | 1).$$

Q: What is the parametric form of the general solution to this linear system of one equation in three variables?

Trichotomy

There are *three possibilities* for the reduced row echelon form of the augmented matrix of a linear system.

1. **The last column is a pivot column.**

In this case, the system is *inconsistent*. There are zero solutions, i.e. the solution set is empty. Picture:

$$\left(\begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{array} \right)$$

2. **Every column except the last column is a pivot column.**

In this case, the system has a *unique solution*. Picture:

$$\left(\begin{array}{ccc|c} 1 & 0 & 0 & * \\ 0 & 1 & 0 & * \\ 0 & 0 & 1 & * \end{array} \right)$$

3. **The last column is not a pivot column, and some other column isn't either.**

In this case, the system has *infinitely many solutions*, corresponding to the infinitely many possible values of the free variable(s). Picture:

$$\left(\begin{array}{ccc|c} 1 & * & 0 & * \\ 0 & 0 & 1 & * \end{array} \right)$$

So far:

* Systems of linear eqns.

* Matrices & row reduction

* Representing solns using parametric eqn. form.

Summary

- ▶ **Row reduction** is an algorithm for solving a system of linear equations represented by an augmented matrix.
- ▶ The goal of row reduction is to put a matrix into **(reduced) row echelon form**, which is the "solved" version of the matrix.
- ▶ An augmented matrix corresponds to an inconsistent system if and only if there is a pivot in the augmented column.
- ▶ Columns without pivots in the RREF of a matrix correspond to **free variables**. You can assign any value you want to the free variables.
- ▶ We can tell whether a linear system has zero, one, or infinitely many solutions using the RREF of the augmented matrix.